Foreword

Encom product EDS-V300 is designed and produced according to EN61800-5-1: 2003, EN61800-3: 2004 standards under ISO9001:2000 quality management system.

We adopt advanced current vector control mode for EDS-V300 series sensorless current vector control inverter to realize drive performance of big torque at low frequency, high steady-state accuracy and wide speed adjusting range, which can fulfil all kinds of requirement in industrial applications. It is suitable for: machine tools, treadmill, metallurgy, extruder, food, chemical, transmission, ore machinery, building materials, packaging machinery, wood machinery and etc.. EDS-V300 provides end-users with kinds of powerful function, such as practical PID regulator, simple PLC, programmable input output terminals control, remote synchronization control, pulse frequency provision and other special inverter control.

Assembling wiring, parameter setting, troubleshooting and daily maintenance notices are available in this manual. To make sure that you can correctly assemble and operate EDS1000 series inverters to exert their excellent performance, please read this user manual detailed before you assemble the device and conserve the manual appropriately before the end-user get them.

Please contact our office or dealer in all places at any moment if you have any doubts or special demands when using these inverters, and you can also contact our after service center in our Headquarters directly. We will serve you with all our heart.

We reserve our right to notice you if we change contents of this manual.

Welcome to choose other inverters of our company:

- **EDS800 series mini inverter**
- **EDS1000 series multi-function universal inverter**
- **EDS2000 series high performance universal inverter**
- **EDS2800 series engineering current vector special inverter**
- **EDS2860 series special integrative inverter for injection molding machine**
- **EDS3000 series high performance closed loop vector control inverter (in developing)**

CONTENTS

1 Safety information and use notice points

In order to ensure the safety of your personal and equipment, before using the inverter, please read this chapter of contents conscientiously.

1.1 Safety precautions

There are four kinds of safe relevant warnings in this service manual, they are as follows:

This symbol is briefed on some useful information.

This symbol briefs on: If does not operate on request, may make the body injured or the equipment damaged.

This symbol briefs on: If does not operate on request, may cause death, severely injured or serious property loss.

(1) Forbid to connect U, V, W output end to AC power supply, otherwise cause the complete damage of the inverter.

(2) Don't make P- and P + short-circuited, otherwise cause the inverter to be damaged.

(3) The inverter is forbidden to install on the flammables, otherwise have danger of fire.

(4) Don't install it in the environment with explosive gas, otherwise have danger of causing explosion.

(5) After connecting main loop, should carry on insulating treatment to bare wiring end, otherwise have danger of getting an electric shock.

(6) If being connected to the power supply, don't operate the inverter with moist hands, otherwise have danger of getting an electric shock.

(7) The ground terminal of the inverter must be grounded well.

(8) Inverter being connected to power supply, please don't open cover and carry on wiring, can connect the wire or check only after closing power for10 minutes.

(9) Only qualified personnel may carry on wiring and forbid leaving over any conductive thing in machine, otherwise have danger of getting an electric shock or causing damage of the inverter.

(10) Inverter stored for over 2 years, should be stepped up gradually with voltage regulator first while having the electricity, otherwise have danger of getting electric shock and explosion.

(1) It is prohibited that connect AC220V signal to control ends except TA, TB, TC, otherwise have danger of damaging property.

(2) If the inverter is damaged or without all parts, please don't install and operate it, otherwise have danger of fire or cause personnel to be injured.

(3) When installing, should choose a place where can endure the inverter, otherwise have danger of injuring personnel or damaging property while falling down.

1.2 Use range

(1) This inverter is only suitable for three phases AC asynchronous motor in general industrial field.

(2) While applying inverter to such equipments that relate much to the life, great property, safety devices etc., must handle cautiously, and consult with producer, please.

(3) This inverter belongs to the control device of general industrial motor, if used in dangerous equipment, must consider the security safeguard procedures when the inverter breaks down.

1.3 Use notice points

(1) EDS300 series inverter is voltage-type inverter, so temperature, noise and vibration slightly increasing compared to power source running when using, belongs to normal phenomenon.

(2) If need to run for a long time with constant torque of low-speed, must select motor of frequency conversion for use. Use general asynchronous AC motor when running at a low speed, should control temperature of the motor or carry on heat dissipation measure forcedly, so as not to burn the generator.

(3) Such mechanical device needing lubricating as the gearbox and gear wheel, etc., after running at a low speed for a long time, may be damaged as lubrication result become poor, please take necessary measure in advance.

(4) When the motor running with frequency above specified, besides considering the vibration, noise increase of the motor, must also confirm speed range of the motor bearing and the mechanical device.

(5) For hoist and great inertia load, etc., the inverter would shut off frequently due to over-current or over-voltage failure, in order to guarantee normal work, should consider choosing proper brake package.

(6) Should switch on/off the inverter through terminal or other normal order channels. It is prohibited that switch on/off the inverter frequently by using strong electric switch such as magnetic control conductor, otherwise will cause the equipment to be damaged.

(7) If need to install such switch as the magnetic control conductor, etc. between inverter output and the motor, please guarantee the inverter is switched on/off without output, otherwise may damage the inverter.

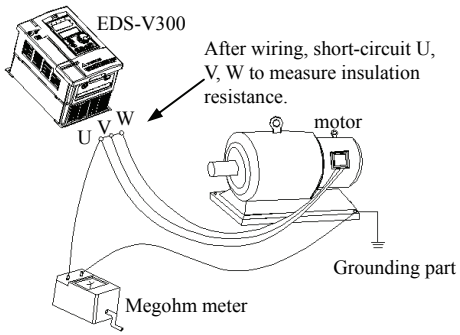
(8) The inverter may meet with mechanical resonance of the load within certain range of frequency output, can set up jumping frequency to evade.

(9) Before using, should confirm the voltage of the power is within the working voltage range allowed, otherwise should vary voltage or order special inverter.

(10) In the condition of altitude above 1000 meters, should use the inverter in lower volume, reduce output current by 10% of specified current after each 1500 meters height increasing.

(11) Should make insulation check to the motor before using it for the first time or after a long time placement. Please inspect with 500V voltage-type megohm meter according to method shown as graph 1-1 and insulation resistance should not be smaller than 5 MΩ, otherwise inverter may be damaged.

(12) To forbid assembling capacitor for improving power factor or lightningproof voltage-sensible resistance etc., otherwise will cause malfunction trip of the inverter or damage of the parts, shown as graph 1-2.



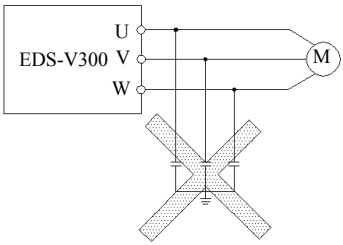


Fig.1-1 motor insulation measure **Fig.1-2 capacitor at output side forbidden**

1.4 Scrap notice points

When disposing scrap inverter and its parts, please note:

(1) The unit: please discard as industrial useless.

(2) Electrolytic capacitor: when burning the inverter electrolytic capacitor in it may explode.

(3) Plastic: when plastic, rubber parts etc. in the inverter are burning, they may bring bad, poisonous gas, so please be ready to safeguards.

2 Type and specification of the inverter

2.1 Incoming inverter inspect

(1) Check if there is damage during transportation and inverter itself has damage or fall-off parts.

(2) Check if parts presented in packing list are all ready.

(3) Please confirm rated data of the inverter is in line with your order requirement.

Our product is guaranteed by strict quality system during manufacturing, packing, transportation etc., please contact our company or local agent rapidly if some careless omission or mistake arise, we'll deal with it as soon as possible.

2.2 Type explanation

EDS – V300 – 4 T 0022 B

Inverter serial no.

code	Volt.grad
2	220V
4	380V

code	Input volt.
S	Single phase
T	Three phase

code	Fitting part
B	built-in brake unit
C	built-in brake unit &brake resistance
E	remote-control keypad

code	Motor power (KW)
0004	0.4
0007	0.75
⋮	⋮
0220	22

Fig. 2-1 type description

note If the inverter hasn't relevant content or can be defaulted, code after "/" will be ignored.

2.3 Nameplate explanation

Nameplate presented as figure 2-2 with type and rating data at the bottom of inverter right side.

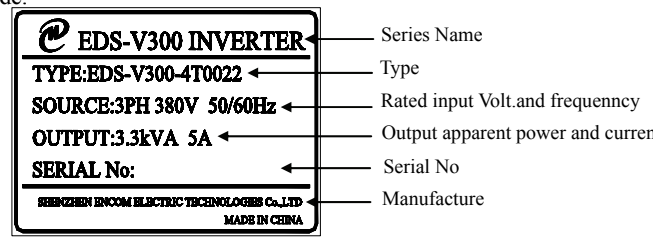


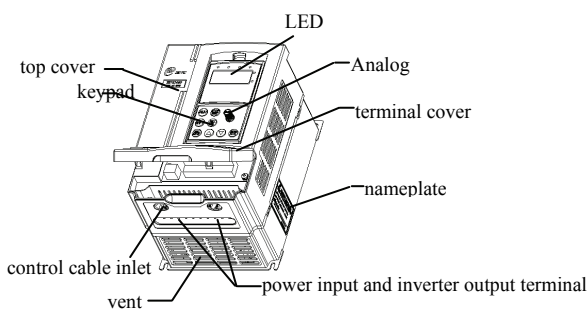
Fig. 2-2 Nameplate

2.4 Series type explanation

Table 2-1 series type explanation

Inverter type (G: general with constant torque: P: special for blower water pump)	Input voltage (V)	Rated power (KVA)	Rated output current (A)	Adapted motor (KW)
EDS-V300-2S0004	Single phase 220V ±15%	1.1	3	0.4
EDS-V300-2S0007		1.8	4.7	0.75
EDS-V300-2S0015		2.8	7.5	1.5
EDS-V300-2S0022		3.8	10	2.2
EDS-V300-2S0037		5.6	17	3.7
EDS-V300-4T0007	Three phase 380V ±15%	1.5	2.3	0.75
EDS-V300-4T0015		2.4	3.7	1.5
EDS-V300-4T0022		3.3	5	2.2
EDS-V300-4T0037		5.6	8.5	3.7
EDS-V300-4T0055		8.6	13	5.5
EDS-V300-4T0075		11	17	7.5
EDS-V300-4T0110		17	25	11
EDS-V300-4T0150		21.7	33	15
EDS-V300-4T0185		25.7	39	18.5
EDS-V300-4T0220		29.6	45	22
EDS-V300-4T0300		39.5	60	30
EDS-V300-4T0370		49.4	75	37
EDS-V300-4T0450		60	91	45
EDS-V300-4T0550		73.7	112	55

2.5 Appearance and parts name explanation



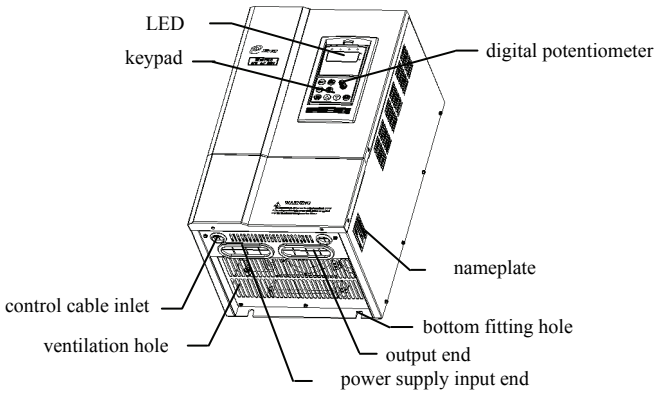


Fig. 2-3 Parts name sketch

2.6 Outer size and gross weight

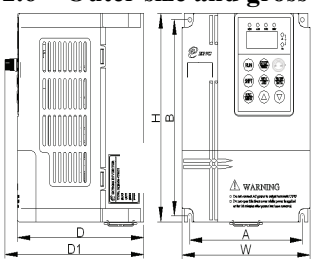


Fig.a outer dimension

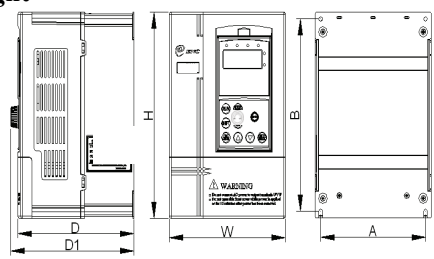


Fig.b outer dimension

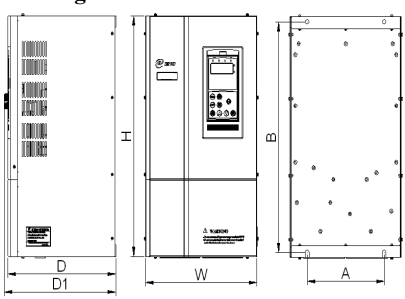


Fig.c outer dimension

Fig.2-4 outer dimension

Table 2-1 EDS-V300-2S0004～EDS-V300-4T0550 mounting size

Inverter type	A (mm)	B (mm)	W (mm)	H (mm)	D (mm)	D1 (mm)	Fixing aperture (mm)	Gross weight (mm) (kg)	Fig
EDS-V300-2S0004	110	160	125	170	123.2	135.5	4	1.5	Fig.a
EDS-V300-2S0007									
EDS-V300-2S0015									
EDS-V300-4T0007									
EDS-V300-4T0015									
EDS-V300-2S0022	140	215	155	230	155	164	5	3.5	Fig.b
EDS-V300-2S0037									
EDS-V300-4T0022									
EDS-V300-4T0037									
EDS-V300-4T0055									
EDS-V300-4T0075	185	275	200	290	178	187	6	6.1	Fig.b
EDS-V300-4T0110									
EDS-V300-4T0150	135	330	218	345	210	221	7	10	Fig.c
EDS-V300-4T0185	180	410	260	430	252	261	9	17	Fig.c
EDS-V300-4T0220									
EDS-V300-4T0300	200	485	280	505	252	261	9	22	Fig.c
EDS-V300-4T0370									
EDS-V300-4T0450	200	515	300	535	252	261	9	26	Fig.c
EDS-V300-4T0550	250	620	370	645	258	267	12	50	Fig.c

2.7 Outer size of keypad and its fixing box (unit: mm)

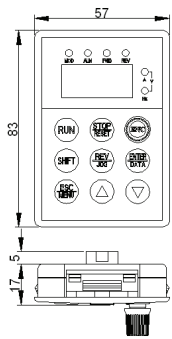


Fig.2-5 EN-KB19 outer size

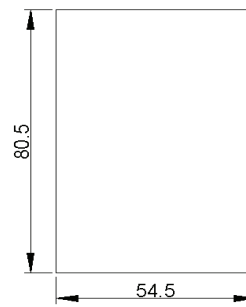


Fig.2-6 EN-KB19 hole size

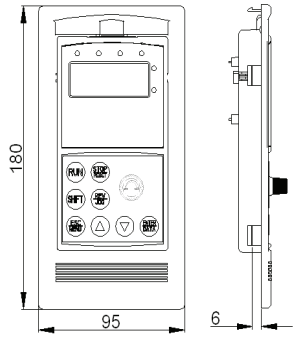


Fig.2-7 EN-KB20 outer size

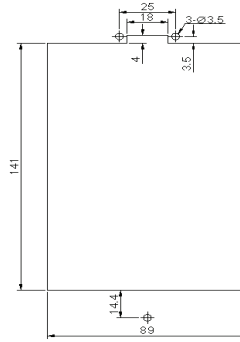


Fig.2-8 EN-KB20 hole size

2.8 Product technic index and spec

item			Item description
Input	Rating volt., frequency		3 phase 380V grade: 3 phase 380V ,50Hz/60Hz; 1 phase 220V grade: 1 phase 220V ,50Hz/60Hz
	Allowed work volt. range		3 phase 380 V grade: 320V~460V 1 phase 220V grade: 200V~260V
output	Voltage		380V grade: 0~380V; 220V grade: 0~220V
	Frequency		0Hz-400Hz
	Over loading capacity		150% of rating current for1 minute， 200% of rating current for 0.5 second；
Control performance	Control mode		Un-speed sensorless current vector control, open loop V/F control
	Speed regulation range		1: 100
	Start-up torque		150% of rating torque at 0.5 Hz frequency
	Running speed stable state precision		≤±0.5% of rating synchronous speed
	Torque limit		Current control to decomposition torque.set torque in 50%~200%
	Frequency precision		Digital setting: max. frequency×±0.01%；analog setting: max.frequency×±0.5%
	Frequency resolution	Analog setting	0.1% of max. frequency
		Digital setting	precision : <100Hz 0.01Hz； ≥100hz：0.1Hz
		Exterior impulse	0.5% of max. frequency

	Torque boost		Automatic torque boost，manual torque boost 0.1%~20.0%
	V/F curve (volt. frequency characteristic)		Set rating frequency randomly at range of 5~400Hz，can choose constant torque, degressive torque 1, degressive torque 2, degressive torque 3 and user-defined V/F in total 5 kinds of curve
	Accelerating decelerating curve		2 modes: straight line accelerating decelerating and S curve accelerating decelerating; 7 kinds of accelerating decelerating time (unit minute/second can be optioned), max. time 6000 minutes.
	brake	Powerconsumption brake	Interior or exterior brake resistance.
		DC brake	Optional start-up and stop，action frequency 0~15Hz，action volt. 0~15%，action time 0~20.0 s
	Jog		Jog frequency range: 0.50Hz~50.00Hz; jog accelerating decelerating time 0.1~60.0s can be set
	Multisection speed running		Realized by interior PLC or control terminal
	Interior PID controller		Be convenient to make closed-loop system
	Automatic volt. regulation (AVR)		Can keep constant output volt. When power source voltage varies.
	Automatic current limiting		Limit running current automatically to avoid frequent over-current which will cause trip
Running function	Running order specified channel		Key pad specified, control terminal specified, serial port specified
	Running frequency specified channel		Digital provision, analog provision, impulse provision, serial port provision, combined provision，can be switched at any time by kinds of method
	pulse output channel		Impulse square wave signal output of 0.1~20KHz，can realize output of physical parameter such as setting frequency, output frequency etc.
	Analog output channel		2 channel of analog signal output，thereinto AO1 channel can be 4~20mA or 0~10V and AO2 channel is 0~10V; through them the inverter can realize output of physical parameter such as setting frequency, output frequency etc.
keypad	LED display		Can display setting frequency, output frequency, output voltage, output current etc.
	Lock the button		Lock all or part of the buttons(analog potentiometer can't be locked)
Protection function			Over-current protection, over-voltage protection, lack-voltage protection, over-heat protection, over-load protection, etc.

Fitting parts		brake subassembly, remote-control keypad, connecting cable for remote-control keypad etc.
ambient	Use ambient	indoor，not bare to sunlight，no dust, no corrosive gas, no flammable gas, no oil fog, no vapor, no water drop or salt etc.
	altitude	Lower than 1000m ,if higher than 1000m ,need to reduce amont to use.
	Ambient temperature	-10ºC~+40ºC(under ambient temperature 40ºC ~50ºC, please reduce the volume or strengthen heat sink)
	Ambient humidity	Smaller than 95%RH, no condensation water
	vibration	Smaller than 5.9m/s²(0.6g)
	Storage temperature	-40ºC~+70ºC
configuration	Defending grade	IP20
	Cooling mode	By fan with automatic temperature control
Mounting mode		Wall hanging

To exert excellent performance of this inverter, please choose correct type and check relevant content according to this chapter before wiring for use.

Must choose correct type, otherwise may cause abnormal running of the motor or damage of the inverter.

3 Installation and wiring

3.1 Installation ambient

3.1.1 Demand for installation ambient

(1) Installed in drafty indoor place，ambient temperature within -10ºC~40ºC，need external compulsory heat sink or reduce the volume if temperature exceeds 40ºC.

(2) Avoid installing in place with direct sunlight, much dust, floating fiber and metal powder.

(3) Forbid to install in place with corrosive, explosive gas.

(4) Humidity should be smaller than 95%RH，without condensation water.

(5) Installed in place of plane fixing vibration smaller than 5.9m/s²(0.6g).

(6) Keep away from electromagnetic disturbance source and other electronic apparatus sensible to electromagnetic disturbance.

3.1.2 Installation direction and space

(1) Normally the inverter should be mounted vertically, horizontal mounting will seriously affect heat dissipation and the inverter must be used in lower volume.

(2) Demand for minimum mounting space and distance，please see Fig. 3-1.

(3) When install multiple inverters up and down, must apply leading divider between them, see Fig. 3-2.

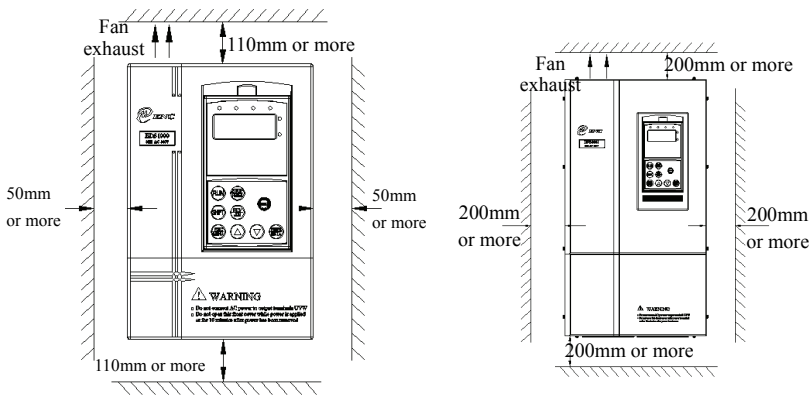


Fig. 3-1 mounting space

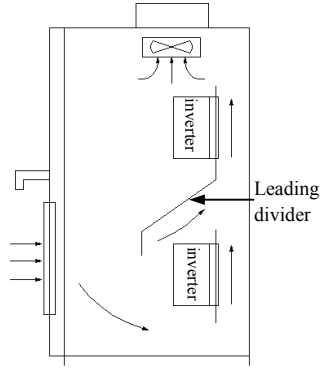


Fig. 3-2 mounting of multiple inverters

3.2 Parts disassembly and installation

3.2.1 Key board disassembly and installation

(1) Disassembly

Let the forefinger press finger inlet on the keypad，depress fixing flexible plate on the top lightly, draw it outward, then you can disassemble the keypad.

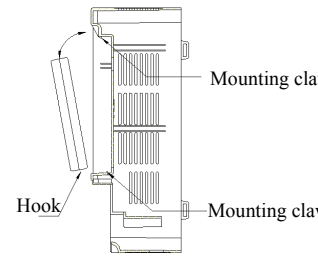


Fig.3-3 mounting sketch of keypad

(2) Assembly

First place the fixing hook at the bottom of keypad onto mounting claw on keypad mounting hole, let forefinger press fixing flexible plate on top of keypad and then push it inside, release it in proper location(after a crisp sound), see Fig. 3-3 。.

3.2.2 Plastic/metal cover disassembly and installation

Plastic cover disassembly and installation:

(1) Disassembly

Put the finger into handle hole on the bottom of cover, lift it in force, till buckle between cover and unit body off, draw the cover backward, then you can disassemble the cover.

(2) Assembly

1> tilt the cover for 5~10 degree；

2> put the mounting claw into relevant hole on the unit body and then press downward in force, see fig. 3-4-a.

Metal cover disassembly and installation

(1) disassembly

First take off 2 screws at sides of the cover and move it a bit outward horizontally, then tilt it at 15 degree and draw it outward at direction shown in right figure, now you can take the cover off.

(2) assembly

First put down the cover in parallel with unit body and make it just locked at 2 sides of the inverter, secondly force it ahead and make fixing part on its top inserted into fixing slot of unit body, at last screw the cover and finish assembly for the cover. As shown in Fig.3-4-b.

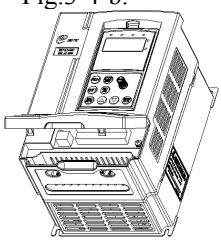


Fig. 3-4 disassembly and mounting sketch of plastic cover

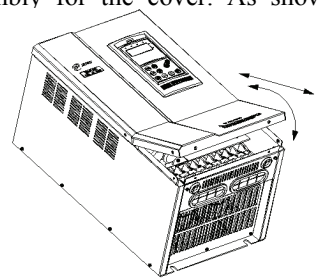


Fig.3-5 disassembly and assembly for metal cover

3.3 wiring notice points

(1)Assure power cut off completely for above 10 minutes before wiring，otherwise have danger of getting electric shock.

(2)Forbid connecting power wire to output U, V, W of the inverter.

(3)There is current leakage in the inverter and leak current of middle/high power inverter is bigger than 5mA，for safety reason，inverter and motor must be earthed safely，commonly use 3.5mm² above copper wire as ground wire and ground resistance smaller than 10Ω.

(4)Before shipment compression resistance test of the inverter is passed，so user should not conduct compression resistance test again.

(5)Should not assemble electromagnetic contactor and absorbing capacitance or other absorbing device, see fig. 3-5.

(6)To be convenient to over current protect of input side and power off maintenance inverter should be connected to power supply through relay.

(7)Connecting wire for relay input and output loop(X1~X8, OC1~OC4, FWD, REV), should use above 0.75mm² glued wire or shielding wire，one shielding layer end hung in the air, the other connected to grounding end PE or E, connecting wire

(1)Before wiring, assure power supply is cut off completely for 10 minutes and all LED indicators light extinguished.

(2)Before internal wiring, confirm that DC volt. Between main loop end P+ and P- fall down to below DC36V.

(3)Wiring can only be done by professional person trained and qualified.

(4)Before electrification, check if voltage grade of the inverter is in line with that of power supply volt.，otherwise will cause personnel injured and device damaged.

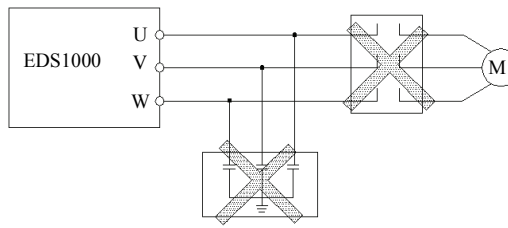


Fig.3-6 banned magnetic control conductor and absorbing capacitance between inverter and motor

3.4 Main loop terminal wiring

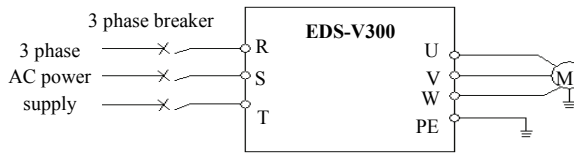


Fig.3-7 main loop simple wiring

3.4.1 Connection between inverter and fitting parts

(1) Must assemble disjunction device such as isolation switch etc. between power source and the inverter to assure personal safety when repairing the inverter and needing compulsory power off.

(2) Power supply loop must have breaker or fuse with over current protection function to avoid malfunction expanding caused by failure of after device.

(3) AC input reactor

If high-order harmonics between inverter and power supply is biggish which can't fulfill system requirement，or need to improve input side power factor, AC input reactor is needed.

(4) Magnetic control conductor only be applied to power supply control and don't apply magnetic control conductor to controlling on/off of the inverter

(5) Input side EMI filter
Can use EMI filter to inhibit high-frequency conduction disturbance and emission disturbance from inverter power supply wire.

(6) Output side EMI filter
Can use EMI filter to inhibit emission disturbance noise and wire leakage current from output side.

(7) AC output reactor
Advise assembling AC output reactor to avoid motor insulation damage, too large over current and inverter frequent protection when connecting wire from inverter to motor exceeds 50m.But voltage drop of AC output reactor must be considered. Improve input output voltage of the inverter or let the motor in lower volume to avoid burning off the motor.

(8) Complete ground wire
Inverter and motor must be earthed and grounding resistor smaller than 10Ω.Grounding wire should be shorter enough and wire diameter be bigger enough(not smaller than following standard):7.5KW or below motor: 3.5mm² above copper wire;11～15KW motor: 8mm² above copper wire. 18.5～37KW motor 14mm² above copper wire; 45～55KW motor: 22mm² above copper wire.

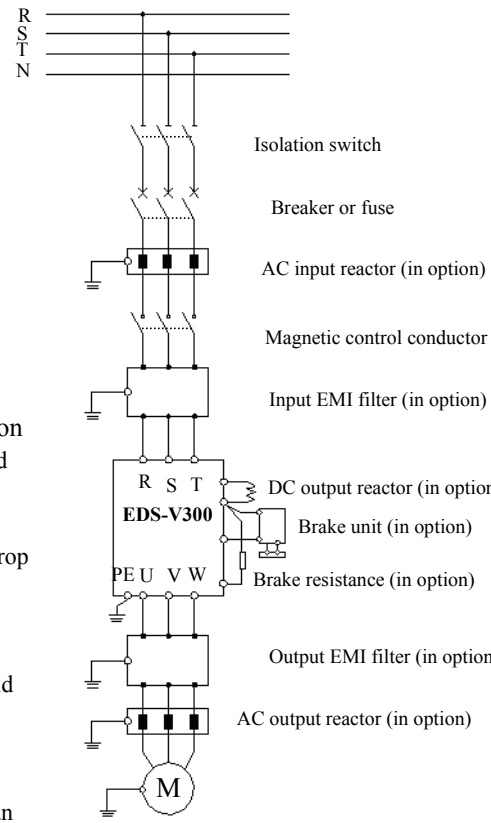
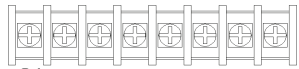
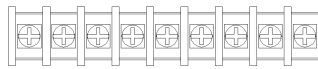
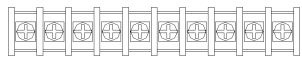
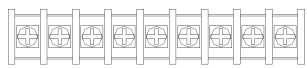
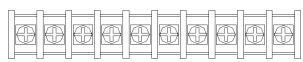
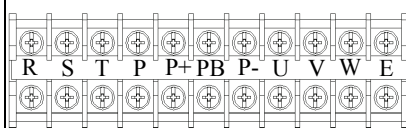


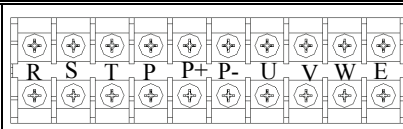
Fig.3-8 connection of inverter

3.4.2 Main loop terminal wiring

For main loop input output terminal, see table 3-1.

Table 3-1 main loop input output terminal description

Adapted type	Main loop terminal	End name	Function description
EDS-V300-2S0004 ~ EDS-V300-2S0015		L1 L2 P+ P– U, V, W E	Zero wire live wire DC volt. Positive end DC volt. negative end 3 phase AC output end Grounding terminal
EDS-V300-2S0022		L1 L2 P+ PB P– U, V, W E	Zero wire live wire DC volt. Positive end Reserved end for external braking resistance DC volt. negative end 3 phase AC output end Grounding terminal
EDS-V300-2S0037		L1 L2 P+ PB P– PE U, V, W	Zero wire Live wire DC volt. Positive end Reserved end for external braking resistance DC volt. negative end Grounding terminal 3 phase AC output end
EDS-V300-4T0007 ~ EDS-V300-4T0015		R,S,T P+ P- U,V,W E	3 phase AC 380V input terminal DC volt. Positive end DC volt. negative end 3 phase AC output end Grounding terminal
EDS-V300-4T0022C ~ EDS-V300-4T0075C		R, S, T P+ P– PB E U, V, W	3 phase AC 380V input terminal DC volt. Positive end DC volt. negative end Reserved end for external braking resistance Grounding terminal 3 phase AC output end
EDS-V300-4T0110B ~ EDS-V300-4T0150B		R, S, T P P+ P– PB U, V, W E	3 phase AC 380V input terminal DC side voltage positive terminal P, P+ can connect DC reactor DC side voltage negative terminal DC braking resistance can be connected between P and PB 3 phase AC output terminal Shield grounding terminal

EDS-V300-4T0185 ~ EDS-V300-4T0550		R, S, T P P+ P- U,V, W E	3 phase AC 380V input terminal DC side voltage positive terminal Reserved terminal for exterior DC reactor DC side voltage negative terminal 3 phase AC output terminal Shield grounding terminal

note

(1) Can connect braking unit between P+ and P- externally if necessary.
(2) Can connect DC braking resistor between PB and P+ externally if necessary.
(3) DC reactor can be connected between P and P+ if necessary.
(4) P and P+ must be short-circuited before shipment, otherwise the inverter can't work.

3.5 Basic running wiring diagram

Adapted type: EDS-V300-2S0004～EDS-V300-4T0550

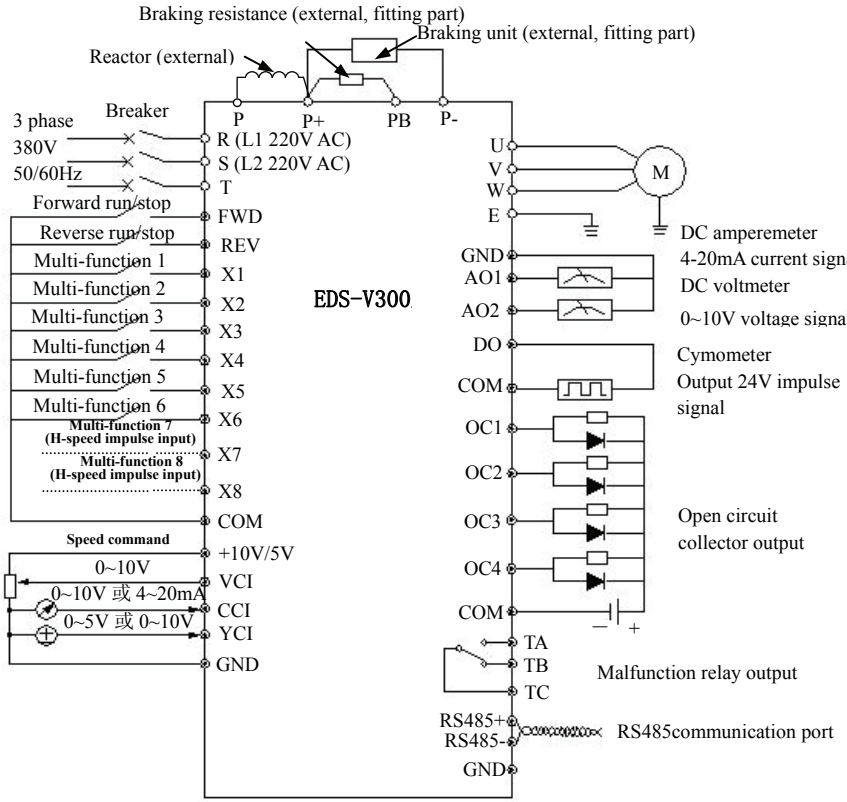


Fig. 3-9 basic wiring diagram

3.6 Control loop collocation and wiring

3.6.1 Location &function of terminal and jump-wire:

For location of terminal and slide switch on the CPU board, please see Fig.3-10. Function description of terminal provided for the user, please see Table 3-2，function and setup description of jumping-wire switch, please see Table 3-3，terminal CN1, CN3 and are for manufacturer's use. Should carry on terminal wiring correctly and set all wiper switch on the CPU board before using the inverter，to use 1mm² above conducting wire as terminal connecting wire is recommended.

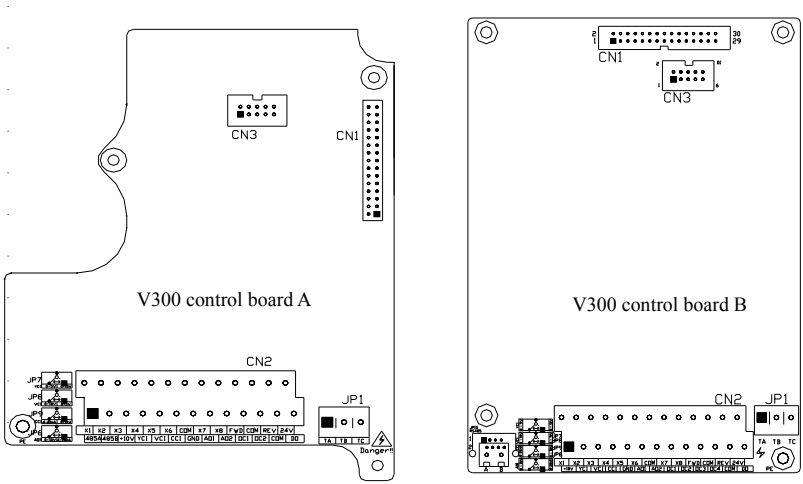


Fig. 3-10 wiper switch on CPU board

Table 3-2 function description of terminal provided for user

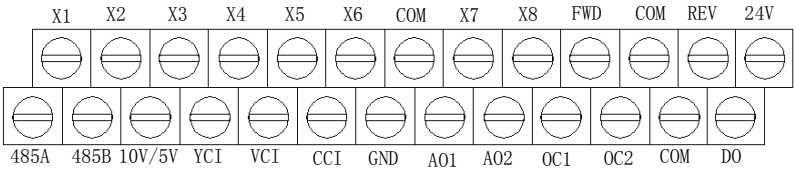
symbol	function	Description
RS485 JP15	RS485, JP15 communication port	connection port for remote-control keypad , upper machine control or cascade and synchronous control
JP1	Malfunction relay signal output	Always-open connect pin of the relay closed when malfunction in inverter occurs
CN2	External terminal input output control	Use this port when external terminal control inverter running

Table 3-3 function description of wiper switch provided for user

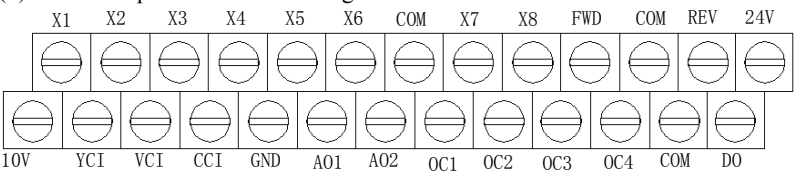
Symbol	Function	Setting	Factory default
JP7	YCI： 5V/10V voltage input mode selection	： 0~5V voltage signal; ： 0~10V voltage signal	0~5V
JP8	VCI：5V/10V voltage input mode selection	： 0~10V voltage signal ; ： voltage signal	0~10V
JP9	CCI：current/voltage input mode selection	： 0/4~20mA current signal; ： 0~10V voltage signal	0/4~20mA
JP6	analog output terminal AO1 output current/voltage type selection	： 0~10V：AO1 terminal output voltage signal ： 4~20mA： AO1 terminal output current signal	0~10V

3.6.2 Explanation for control CPU board

(1) control loop terminal CN2 arranged as follows for inverter below 1.5kw:



(2) control loop terminal CN2 arranged as follows for inverter above 2.2kw:



(3) CN2 terminal function description as Table 3-4.

Table 3-4 CPU board CN2 terminal function table

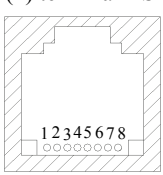
item	symbol	name	Function description	Spec
run command	FWD	Forward run command	Forward reverse run command, see F5.08 group double-wire and three-wire control function description	Optocoupler isolation input Input impedance: R=2K Ω
	REV	Reverse run command		
Multi-function input terminal	X1	Multi-function input 1	Used for multi-function input terminal, for detailed see Chapter 6 Section 6.6 terminal function parameter (F5 group)input	Max. input frequency: 200Hz X1~X8 FWD, REV COM Close effective
	X2	Multi-function input 2		
	X3	Multi-function input 3		
	X4	Multi-function input 4		

	X5	Multi-function input 5	end function description. X7, X8 can be set as H-speed impulse input port, for detailed see Chapter 6 Section 6.6 terminal function parameter(F5 group)input end function description. (common end: COM)	Input impedance of X7, X8 input channel: R=2K Ω Max. output Freq.: 20KHz Input voltage range: 15~24V
	X6	Multi-function input 6		
	X7	Multi-function input 7		
	X8	Multi-function input 8		
Power supply	+24V	+24V power supply	Provide +24V power supply. (negative pole: COM)	Max. output current: 150mA
	+10V	+10V power supply	Provide +10V/+5V power supply. (negative pole: GND)	Max. output current: 50mA
	COM	Common end+24V power supply negative pole	Common end and reference ground of digital signal input	Internal isolating between COM and GND
	GND	+10V power supply negative pole	Reference ground of analog signal and +10V power supply	
Analog value input	CCI	Analog value input CCI	Accept analog voltage/current input，voltage, current optioned by wiper switch JP9，factory default is current. (reference ground: GND)	Input voltage range: 0~10V (input impedance: 70KΩ) Input current range: 4~20mA (input impedance: 250Ω) Resolution: 1/1000
	YCI	Analog value input YCI	Accept analog voltage input, 0~5V or 0~10V optioned by wiper switch JP7, factory default is 0~5V. Can control running direction of the motor directly. (reference ground: GND)	Input voltage range: 0~5V(input impedance 70KΩ), 0~10V(input impedance 36KΩ) Resolution: 1/1000

	VCI	Analog value input VCI	Accept analog voltage input，0~5V or 0~10V optioned by wiper switch JP8，factory default is 0~10V. (reference ground: GND)	Input voltage range: 0~10V (input impedance: 70KΩ) resolution: 1/1000
Analog value output	AO1	Analog value output1	Provide analog voltage/current output，can express 6 kinds of parameter see F5.17 parameter description，output voltage/current optioned by slide switch JP6，factory default output voltage. (reference ground: GND)	Current output range: 4~20mA voltage output range: 0~10V
	AO2	Analog value output 2	Provide analog voltage output (reference ground: GND)	
Multifunction output end	OC1	Open circuit collector output terminal 1	Used for multi-function switch output terminal, for detailed see Chapter 6 Section 6.6 terminal function parameter (F5 group) output end function description. (common end: COM)	optocoupler isolation output Work voltage range: 15~30V Max. output current: 50mA Use method see Description of parameter F5.10~F5.13
	OC2	Open circuit collector output terminal 2		
	OC3	Open circuit collector output terminal 3		
	OC4	Open circuit collector output terminal 4		
	DO	H-speed impulse output terminal	Used for multi-function impulse signal output terminal, for detailed see Chapter 6 Section 6.6 terminal function parameter(F5 group) output end function description. (common end: COM)	Output impulse voltage: 24V Output frequency range: depending on parameter F5.24, max.20KHz

Table 3-4 CPU board CN2 terminal function table

(4) terminal RS485，arranged as follows(platform of RS485 terminal):



RS485 terminal arrangement								
No.	1	2	3	4	5	6	7	8
name	485+	*	485-	*	*	GND	*	+5V

"*" terminal is for the manufacturer, user can't use.

(5) RS485 terminal and JP15 function description as table 3-5

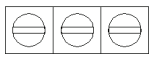
Table 3-5 CPU board RS485 terminal function table

item	symbol	name	Function description	spec
communication	RS485+	RS485 communication interface	485 difference signal positive end	For standard RS-485 communication interface please use twisted-pair or STP
	RS485-		485 difference signal negative end	
	JP15		485 connector	

Note

You can choose crystal plug or connector for communication cable.

(6) control terminal JP1，arranged as follows:



(7) JP1 terminal function description as Table 3-6.

Table 3-6 CPU board JP1 terminal function

Item	symbol	name	Function description	Spec
Relay output terminal	TA	Inverter malfunction output relay	Normal: TB-TC closed, TA-TC open Malfunction: TB-TC open, TA-TC closed	TB-TC: always-closed, TA-TC: always-open Contact capacity: AC250V/2A (COSΦ=1) AC250V/1A (COSΦ=0.4) DC30V/1A

3.6.3 Analog input output terminal wiring

(1) VCI terminal accepts analog voltage signal input，wiring as follow:

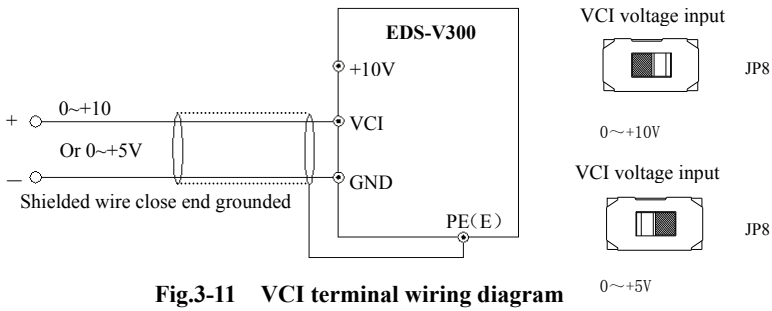


Fig.3-11 VCI terminal wiring diagram

(2) CCI terminal accepts analog signal input，slide switch decide to input voltage(0~10V) or input current(4~20mA)，wiring mode as follows:

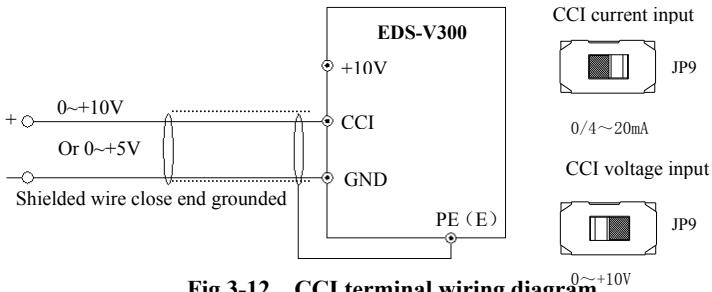


Fig.3-12 CCI terminal wiring diagram

(3) YCI terminal accepts analog voltage signal input，wiring mode as follows:

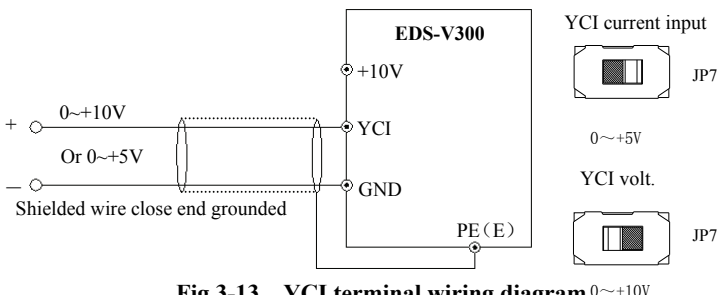
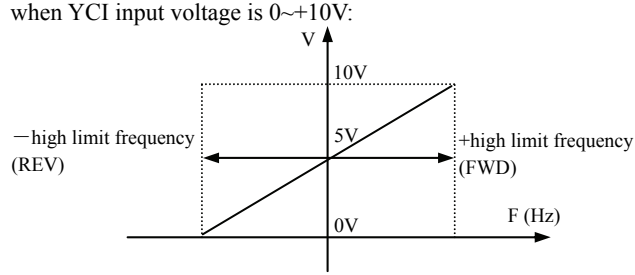


Fig.3-13 YCI terminal wiring diagram

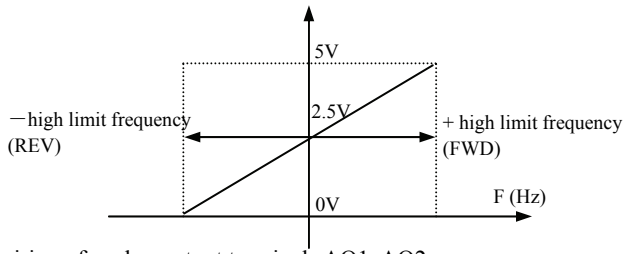
Explanation: relation between YCI input voltage and set frequency is as following figure:

1> when YCI input voltage is 0~+10V:



2> when YCI input voltage is 0~+5V:

V



(4) wiring of analog output terminals AO1, AO2

analog output terminals AO1, AO2 connected to analog meter and kinds of physical data can be indicated, there into AO1 can output current (4~20mA) or voltage (0~10V) decided by slide switch JP6. Terminal wiring mode as Fig.3-13.

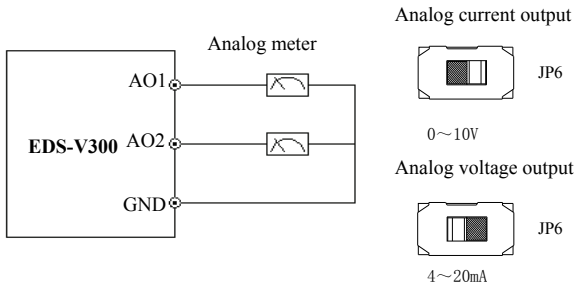


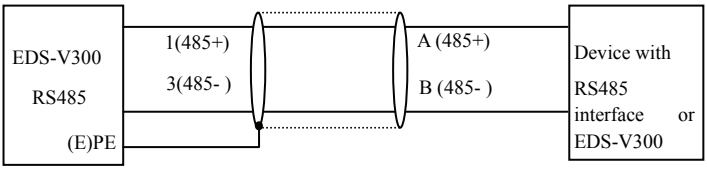
Fig.3-14 analog output terminal wiring

Note

(1) When inputting analog signal，can connect filter capacitor or common module inductance between VCI and GND or between CCI and GND or between YCI and GND.
(2) Analog input, output signal is easy to be disturbed，so must use shielded cable when wiring and well grounded, wiring length should be as short as possible.

3.6.4 Communication terminal wiring

EDS-V300 inverter provides RS485 serial communication interface for the user. Following wiring methods make single-main single-sub control system or single-main multi-sub control system possible. Using upper machine (PC or PLC controller) software can realize real time supervision to inverter in the industrial control system so that realize complicated run control such as long-distance control, high autoimmunization etc; you can also take one inverter as mainframe and the others as submachine to form cascade or synchronous control network.
(1) When inverter RS485 interface connected to other devices with RS485 interface, you can connect wire as below figure.



(2) To connect remote control keypad, you can connect plug of remote control keypad to RS485 directly. No need to set any parameter，inverter local keypad and remote control keypad can work at one time.

(3) Connection between inverter RS485 interface and upper machine (with RS232 interface):

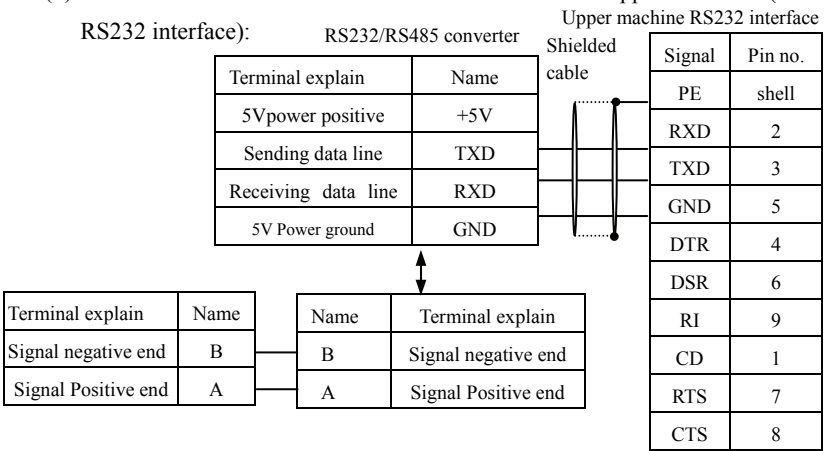


Fig. 3-16 RS485 communication wiring

(4) Multiple inverters can be connected together per RS485 and 31pcs inverter can be connected together at most. Communication system is more prone to disturbance as connected inverters increasing, following wiring is recommended:

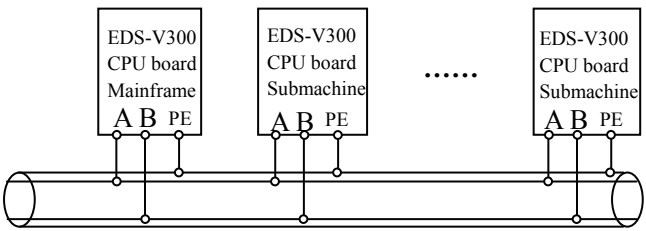


Fig. 3-18 recommended wiring for multiple inverters communication (all inverters and motors well earthed)

Normal communication still not available if using above wiring, can try to take

following measure:
1> Provide separate power supply for PLC (or upper machine) or isolate its power supply.
2> Apply magnetic circle on the communication wire.
3> Reduce inverter carrier wave frequency properly.

note

(1) When form the network only by inverters, you must set local address parameter F2.15 of the mainframe EDS-V300 to 0.

(2) For programming of RS485 interface，please refer to appendix communication protocol.

3.7 Installation guide for anti-jamming

Main circuit of the inverter is composed of high-power semiconductor switch gear，so some electromagnetic noise will arise during work，to reduce or stop disturbance to environment，show you assembling method of inverter disturbance suppressing from many aspects such as disturbance suppressing, spot wiring, system grounding, leak current, usage of power supply filter etc. In this section to be referred to during spot assembling.

3.7.1 Restraining to noise disturbance

Disturbance brought by the working inverter may affect nearby electronic device，effect degree relates to surrounding electromagnetic environment of the inverter and anti-disturbance capacity of this device.

(1) Type of disturbance noise

According to work principle of the inverter, there are mainly 3 kinds of noise disturbance source:
1> circuit conduction disturbance；
2> space emission disturbance；
3> electromagnetic induction disturbance；

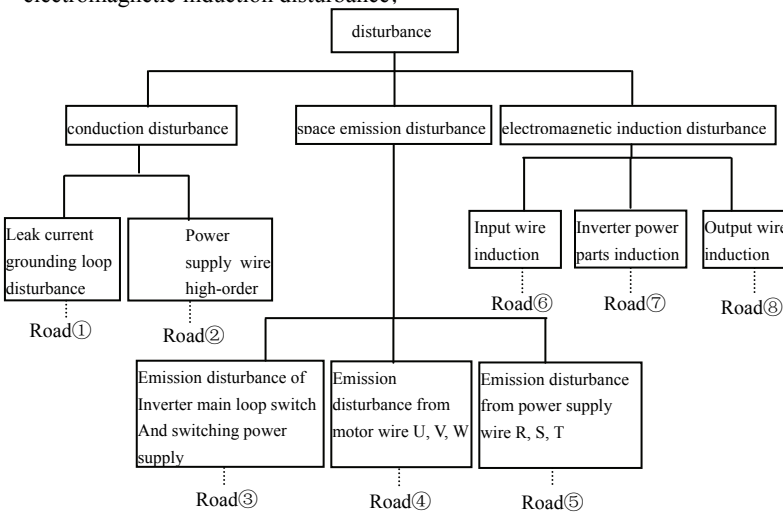


Fig.3-18 type of noise disturbance

(2) Noise spread road

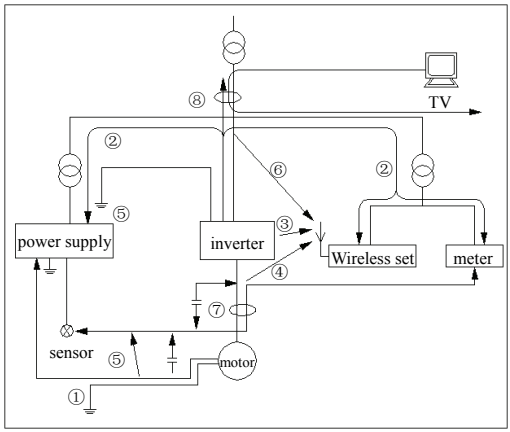


Fig.3-19 noise disturbance spread road sketch

(3) Basic countermeasure for suppressing disturbance

Table 3-7 disturbance suppressing countermeasure tables

Noise spread road	Countermeasure of weakening effect
①	When grounding wire of peripheral device and wiring of the inverter compose closed-loop, inverter grounding wire leakage current would make the device do wrong action. Can reduce wrong action if the device is not earthed here.
②	High-order harmonic from the inverter would make voltage and current transmit through power supply wire when peripheral device and the inverter electrified by same power supply, would disturb other devices in this same power supply system，can take following suppressing measure: assemble electromagnetic noise filter at inverter input end；Isolate other devices by isolation transformer; connect power supply for peripheral device with remote power source; install ferrite filter magnetic circle for R, S, T three-phase conducting wire of the inverter to suppress conduction of high-frequency harmonic current.

③④⑤	● Keep device and signal wire prone to disturbance from the inverter. Should use shielded signal wire, shielding layer single end earthed and try best to keep away from the inverter and its input, output wire. If signal wire must intersect strong power cable, must keep them in real intersection and avoid parallel. ● Install high-frequency noise filter(ferrite common module choke, folksay magnetic circle) separately at input, output root，which can effectively suppress emission disturbance from dynamic wire. ● Should place motor cable shield of biggish thickness, for instance set it in tube with biggish thickness (above 2mm) or bury it in cement slot. Dynamic wire set into metal tube and use shielding wire to be grounded (use 4-core motor cable, one side is earthed through the inverter, the other side connected to motor shell).
⑥⑦⑧	To prevent parallel or bundled power and weak conducting wire；should keep away from inverter mounted device to the best and its wiring should keep away from power wire of the inverter such as R, S, T, U, V, W etc.. Should pay attention to relative mounting place between device with strong electric field or strong magnetic field and the inverter, should keep distance and vertical intersection.

3.7.2 Local wiring and earthing

(1) Avoid parallel cable from inverter to motor (U, V, W terminal education wire) and power supply wire (R, S, T terminal input wire). Should keep distance of 30cm above.

(2) Try your best to place motor table from U, V, W terminals in metal tube or metal wiring slot.

(3) Should use shielded cable as common control signal cable，shielding layer close-to–inverter side earthed after connected with PE terminal of inverter.

(4) Cable educed from inverter PE terminal must be connected directly to earth-plate and can't be connected to ground through grounding wire of other devices.

(5) Powerful cable(R, S, T, U, V, W) should not parallel control signal cable closely, say nothing of being bundled together, must keep distance of 20~60cm above (related to size of powerful current). Should cross each other vertically if intersection, as Fig.3-20.

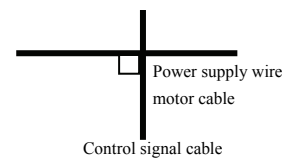


Fig.3-20 system wiring demand

(6) Powerful grounding wire must be connected to earth separately from weak grounding cable such as control signal and sensor cable etc.

(7) Forbid to connect other electricity consumption device to inverter power supply input end(R, S, T).

3.7.3 Relation of long-distance wiring and current leak and the countermeasure

High-order harmonic will form between-line leak current through distributing capacitor and to-earth leak current when long-distance wiring between inverter and motor commence. Can adopt following method to suppress:

(1) Install ferrite magnetic circle or output reactor at inverter output side.

End voltage of the motor will be reduced markedly when installing reactor of 5% above rated voltage down and make long-distance wiring to U, V, W. Fully loaded motor have the danger of burning itself，should work in lower volume or step up its input output voltage.

(2) Reduce carrier wave frequency but motor noise would increase accordingly.

3.7.4 Installation demand for electromagnetic on-off electronic device

Relay，magnetic control conductor and electromagnetic iron and so on, these electromagnetic on-off electronic device would bring lots of noise during work, so you should pay full attention to when installing them beside the inverter or in the same control chamber with the inverter and must install surge absorbing device as shown in Fig. 3-20.

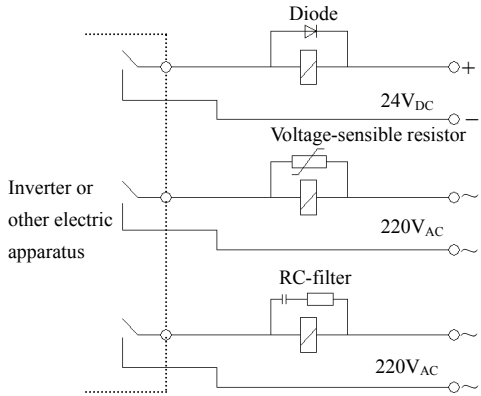


Fig.3-21 installation demand for electromagnetic on-off device

4 Run and operation explanation for inverter

4.1 Run of inverter

4.1.1 Operation of Inverter

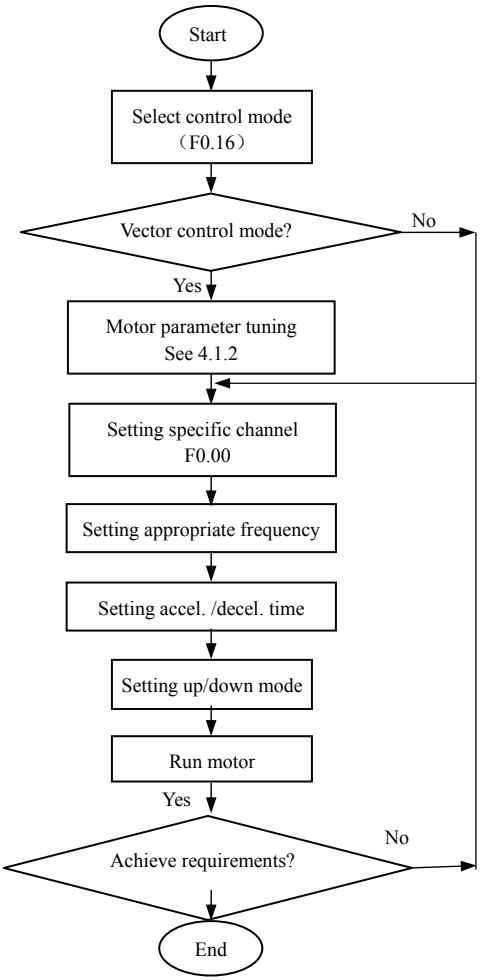


Fig.4-1 Operating Flow reference Chart

4.1.2 The tuning of motor parameters

Motor parameters need auto-tuning when chooses speed sensorless vector control. The parameters of motor nameplate should be rightly entered before self-tuning. For details, see F8.17 and motor parameter tuning flow chart 4-2.

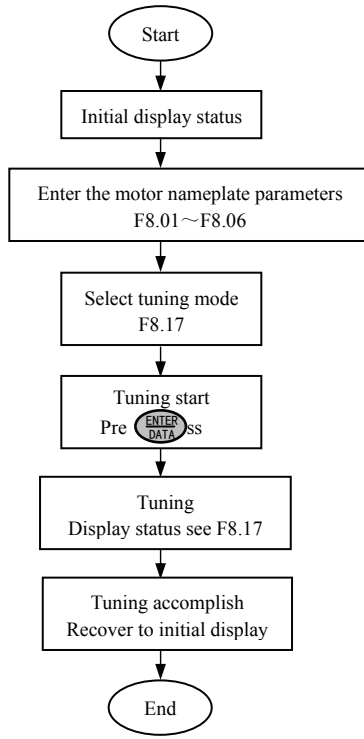


Fig.4-2 Motor Parameter Tuning Flow Chart

4.1.3 Running order channels

There are 3 kinds of order channel for controlling run action of the inverter such as run, stop, jog etc.:

0: keypad

Control by key RUN, STOP, REV JOG on keypad(factory default).

1: control terminal

Use control terminal FWD, REV, COM to make of double-line control， or

use one terminal of X1～X8 and FWD or REV to make of three-line control.

2: serial port

Control run and stop of the inverter through upper machine or other device which can communicate with the inverter.

Choose order channel by setting function code F0.02；and also can choose by multi-function input terminal(F5.00~F5.07 choose function 29, 30, 31).

Please make switching debugging in advance when switch the order channel to check if it can fulfill system requirement，otherwise have danger of damaging device and injuring personal.

4.1.4 Frequency-provision channel

EDS1000 common run mode there are 10 kinds of provision channel:

0: keypad analog potentiometer provision；

1: direct digital frequency provision；

2: terminal UP/DOWN provision(store after power-off or stop)；

3: serial port provision；

4: analog value VCI provision；

5: analog value CCI provision；

6: analog value YCI provision；

7: terminal pulse(PULSE) provision；

8: combination set;

9: terminal UP/DOWN provision (not store after power-off or stop)

4.1.5 Work state

Work state of EDS1000 is classified as waiting state and running state:
waiting state: If there is no running command after the inverter electrified or after stop command during running state, the inverter enters into waiting state.
running state: the inverter enters into running state after receiving run command.

4.1.6 Run mode

EDS1000 inverter have 6 kinds of run mode，following is in turn according to their priority: jog run→closed-loop run→PLC run→multisection speed run→swing frequency run→common run. Shown as Fig.4-3.

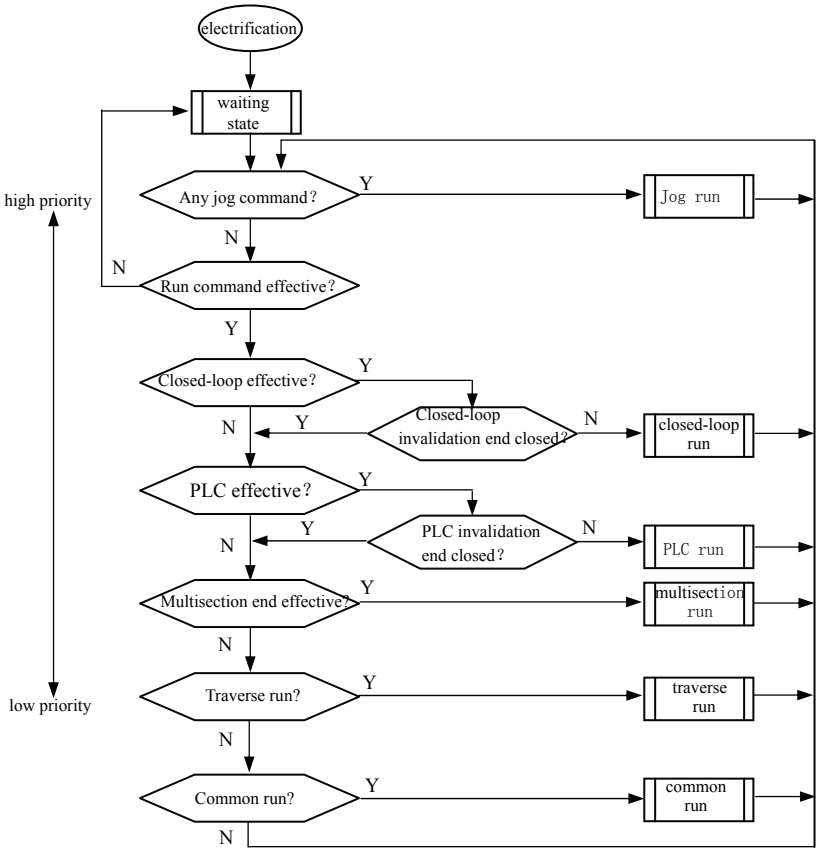


Fig.4-1 logic flow chart of EDS-V300 inverter run state

0: jog run

Upon receiving jog run command (for instance, press the REV/JOG key on keypad) during waiting state, the inverter run at jog frequency (see function code F2.06~F2.08).

1: closed-loop run

The inverter will come into closed-loop run mode when closed –loop run control effective parameter is set (F3.00=1). Namely carry on PID adjustment to specified value and feedback value(proportion integral differential calculation，see F3 group function code) and PID adjustor output is inverter output frequency. Can make

closed-loop run mode ineffective and switch to lower level run mode by multi-function terminal (function 20).

2: PLC run

The inverter will enter into PLC run mode and run according to run mode preset(see F4 group function code description) through setting PLC function effective parameter(F4.00 last bit≠0). Can make PLC run mode ineffective and switch to lower level run mode by multi-function terminal (function 21).

3: multi-section speed run

By nonzero combination of multi-function terminal(1, 2, 3, 4 function)，choose multisection frequency 1~7(F2.30~F2.36) to run at multisection speed.

4: common run

Common open loop run mode of general inverter.

In above 6 kinds of run mode except “jog run” the inverter can run according to kinds of frequency setting method. In “PID run”“PLC run”“multisection run”“common run” mode the inverter can also carry on pendular frequency adjustment.

4.2 Operation and use of key board

4.2.1 Keypad layout

Keypad is main unit for receiving command, displaying parameter. Outer dimension of EN-KB6 is as Fig.4-4:

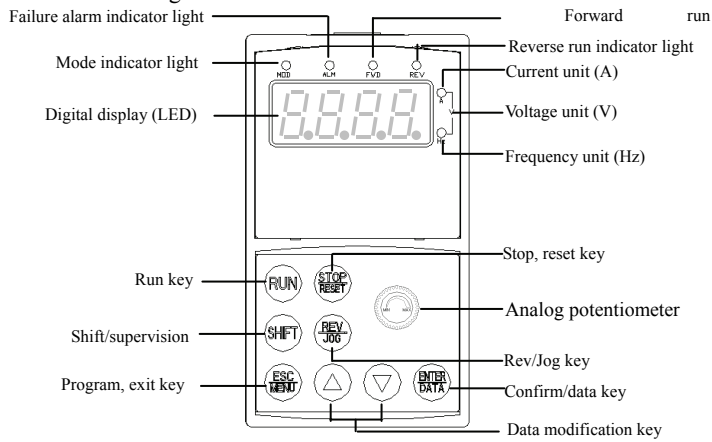


Fig.4-2 keypad layout sketch(EN-KB6)

4.2.2 Keypad function description

There are 8 key-presses and one adjusting button for analog potentiometer on inverter Keypad and function definition of each key is as shown in table 4-1.

Table 4-1 keypad function table

key	name	Function description
ESC MENU	Program/Exit key	Enter into or exit programming state
SHIFT	Shift/Supervision key	Can choose modification digit of set data under editor state; can switch display status supervision parameter under other state.
ENTER DATA	Function/Data key	Enter into the next menu or data confirmation
REV JOG	Rev/Jog key	Under keypad mode, to press this key can set reverse run or Jog run according to the 2nd bit of parameter F0.03
RUN	Run key	Enter into forward run under keypad mode
STOP RESET	Stop/reset key	In common run status the inverter will be stopped according to set mode after pressing this key if run command channel is set as keypad stop effective mode. The inverter will be reset and resume

		normal stop status after pressing this key when the inverter is in malfunction status.
	Analog potentiometer	Be used to set frequency; when F0.00=0 value set by analog potentiometer is frequency provision
	Increasing button	To increase data or function code (to press it continuously can improve increasing speed)
	Decreasing button	To decrease data or function code (to press it continuously can improve decreasing speed)

4.2.3 LED and indicator light

4 status indicator light: they are MOD (mode), ALM (alarm), FWD (forward run), REV(reverse run)from left to right on the LED, their respective indicating meaning is as shown in table 4-2.

Table 4-2 status indicator light description

<table>
<tr><th colspan="3">item</th><th colspan="2">Function description</th></tr>
<tr><td rowspan="6">Display function</td><td colspan="2">Digital display</td><td colspan="2">Display current run status parameter and set parameter</td></tr>
<tr><td rowspan="5">Status indicator light</td><td>A, Hz, V</td><td colspan="2">unit for relevant current digital displayed physical parameter(for current is A, for voltage is V, for frequency is Hz)</td></tr>
<tr><td>MOD</td><td colspan="2">This indicator light is lit in nonsupervision status and extinguished if no key pressed for a minute, then come back to supervision status</td></tr>
<tr><td>ALM</td><td colspan="2">Alarm indicator light, indicate that the inverter is in over current or over voltage suppressing status or failure alarm status currently</td></tr>
<tr><td>FWD</td><td>Forward run indicator light，indicate that the inverter output forward phase order and the connected motor rotate in forward direction</td><td rowspan="2">The inverter work in DC brake status if FWD, REV indicator light is lit at the same time</td></tr>
<tr><td>REV</td><td>reverse run indicator light, indicate that the inverter output reverse phase order and the connected motor rotate in reverse direction</td></tr>
</table>

4.2.4 Key board display status

EDS-V300 keypad display status is classified as waiting status parameter display, function code parameter editing status display, malfunction alarm status display, run status parameter display in total 4 kinds of status. LED indicator light will all be lit after the inverter electrified, and digital display LED will display character "-EN-", then enter into set frequency display. As shown in Fig.4-5 a.

(1) Waiting parameter display status

The inverter is in waiting status and waiting status supervision parameter is displayed on keyboard, normally parameter F3.28 decide which status supervision parameter to be displayed. As shown in Fig.4-5 b，the unit is indicated by rightward unit indicator light.

To press SHIFT key，it can display different waiting status supervision parameter circularly(display 15 kinds of supervision parameter of C group acquiescently，whether the last 7 kinds of supervision parameter are displayed is defined by function code F2.11，F2.12, for detail please see C group status supervision parameter in function parameter schedule graph of chapter 5).

(2) Run parameter display status

The inverter enters into run status when receiving effective run command and normally parameter F3.28 decide which status supervision parameter to be displayed on the keypad. As shown in Fig.4-5 c，unit is displayed by rightward unit indicator light.

To press SHIFT key，can display run status supervision parameter circularly (defined by function code F2.11 and F2.12). During displaying, can press ENTER DATA to switch to initial supervision parameter decided by F3.28, otherwise will display the last displayed parameter all along.

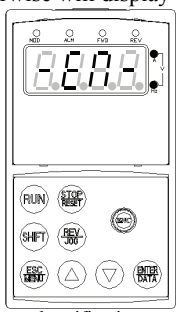


Fig.a electrification，display-EN-

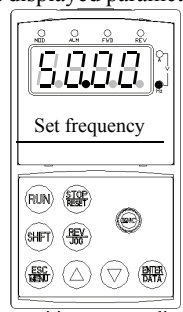


Fig.b waiting status，display waiting status parameter

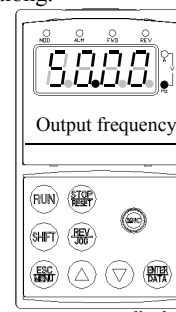


Fig.c run status, display run status parameter

Fig.4-5 inverter electrification, waiting, run status display

(3) Failure alarm display status

The inverter enters into failure alarm display status upon detecting failure signal and display failure code sparklingly(as shown in Fig.4-6); To press SHIFT key can look over relative parameter after stopping running；Can press ESC MENU key to enter into program status to see about Fd group parameter if want to search failure information.

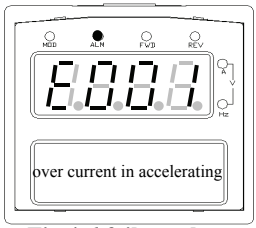


Fig.4-6 failure alarm

Can carry on failure restoration by STOP RESET key, control terminal or communication command on the keypad after troubleshooting. Keep displaying failure code if failure exist continuously.

For some serious failure，such as inverse module protect，over current, over voltage etc., must not carry on failure reset forcibly to make the inverter run again without failure elimination confirmed. Otherwise have danger of damaging the inverter！

(4) function code editing status

Under waiting, run or failure alarm status，press ESC MENU key，can enter into editing status(If user password is set，can enter into editing status after inputting the password，see also FF.00 description and Fig.4-12)，and editing status is displayed according to three classes menu mode，as shown in Fig. 4-7. To press ENTER DATA key can enter into one class by one class. Under function parameter display status，to press ENTER DATA key to carry on parameter storage operation；To press ESC MENU key can only come back to upper class menu without storing modified parameter.

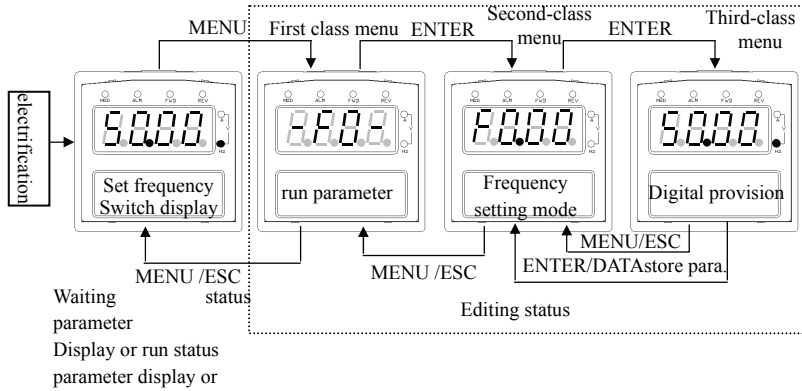


Fig.4-7 keypad display status switching

(5) Special display function

You can change set frequency under supervision state directly when keypad potentiometer is effective (F0.00=0) or keypad digital setting is effective (F0.00=1). Here the inverter displays set frequency if it's stop or displays output frequency if it's running. After set frequency stops changing for 1 second the inverter will go back to normal display status.

4.2.5 Method for operating keypad

Can carry on various operation to the inverter through keypad，for example:

(1) status parameter display switching:

After pressing key SHIFT, display C group status supervision parameter; after displaying one supervision parameter code for 1 second, will display this parameter value automatically.

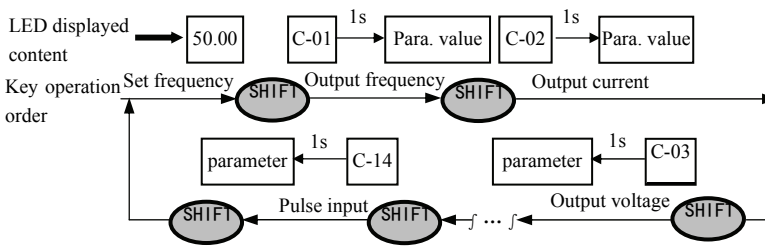


Fig. 4-8 waiting status parameter display operating example

Description:

1> All status parameters C-00～C-14 can be displayed when the inverter leaves factory. You can make a change by modifying function code F2.11, F2.12 if you want to, for detail please refer to F2.11, F2.12function code description.

2> Can press ENTER DATA key to switch into constant supervision C-01 display status directly when the user see about status supervision parameter.

(2) function code parameter setting

Take function code F2.06 modified from 5.00Hz to 6.00Hz as example.

Boldface in Fig.4-7 shows flickering digit.

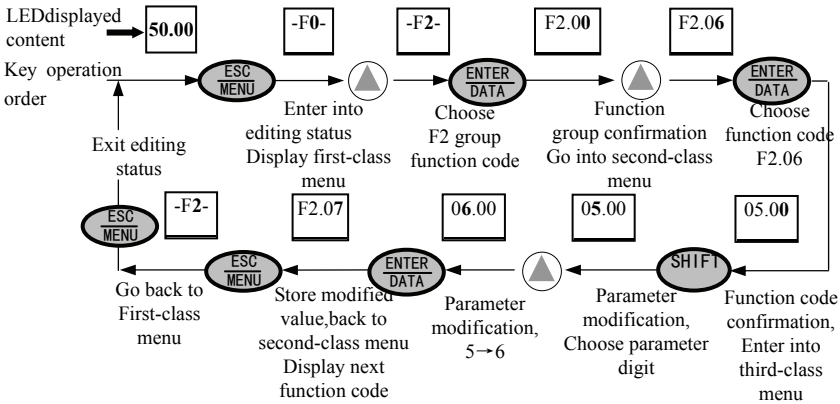


Fig.4-9 example for parameter setting and modification

Description: under third-class menu, if the parameter has no blinking digit，this function code can't be modified，possible reasons are as follows:

1> This function code shouldn't be modified, for example actual detected status parameter, run record parameter etc.；

2> This function code can't be modified under run status and can be changed after stopping running；

3> Parameter protected. All the function code can't be modified when function code F2.13=1 or 2，in order to avoid wrong operation. Need to set the function code F2.13 to 0 if you want to edit function code parameter.

(3) specified frequency adjustment for common run

Take example modifying specified frequency from 50.00Hz to 40.00Hz at F0.00=0 during running for explanation.

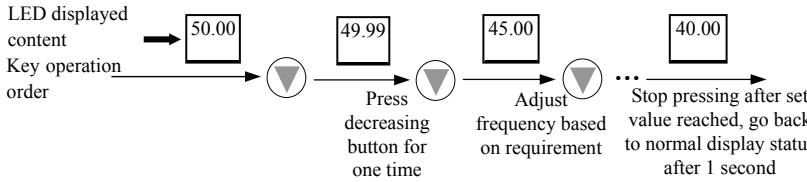


Fig. 4-10 set frequency adjustment operation example

(4) jog run operation

For example, keypad as current run command channel, jog run frequency 5Hz, waiting status.

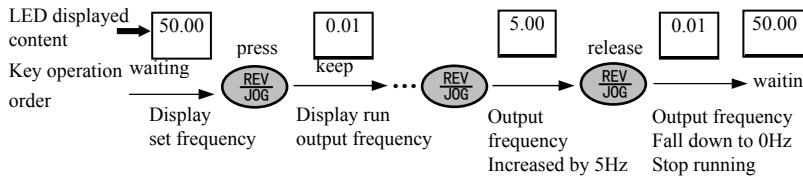


Fig.4-11 jog run operating example

(5) operation for entering to function code editing status after setting user password

"user password"FF.00 is set to "6886". Boldfaced digit in Fig.4-7 shows blinking bit.

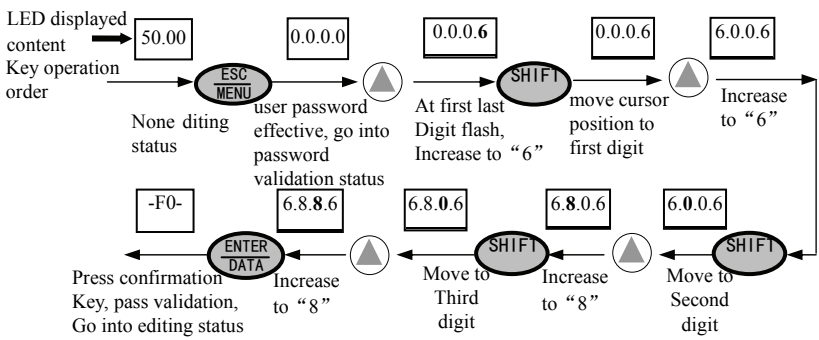


Fig.4-12 inputting password to go into function code operation

(6) See about failure parameter under failure status:

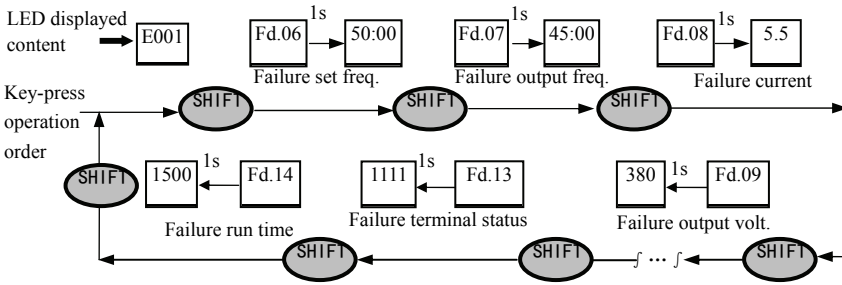


Fig.4-13 failure status searching operation example

Description:

1> If press SHIFT key under failure status the user can see about Fd group function code parameter, search range Fd.06～Fd.14，LED first display function code number when the user press SHIFT key and display parameter digit of this function code after 1s.

2> When the user see about failure parameter，can press ENTER DATA key directly to switch back to failure alarm display status (E0XX)

(7) keypad key-press locking operation

Under unlocked keypad situation，press ESC MENU key for 5s to lock the keypad. For detailed operation please refer to 2nd bit of F2.13 function code.

(8) keypad key-press unlocking operation

Under locked keypad situation，press ESC MENU key for 5s to unlock the keypad.

4.3 Inverter electrification

4.3.1 Check before electrification

Please carry on wiring based on operation requirement provided in “inverter wiring” of this Service manual.

4.3.2 First electrification

Close input side AC power supply switch after correct wiring and power supply confirmed, electrify the inverter and keypad LED display “-EN-”, contactor closed normally, LED displayed set frequency shows that electrification is finished. First electrification operation process is shown as figure in the page.

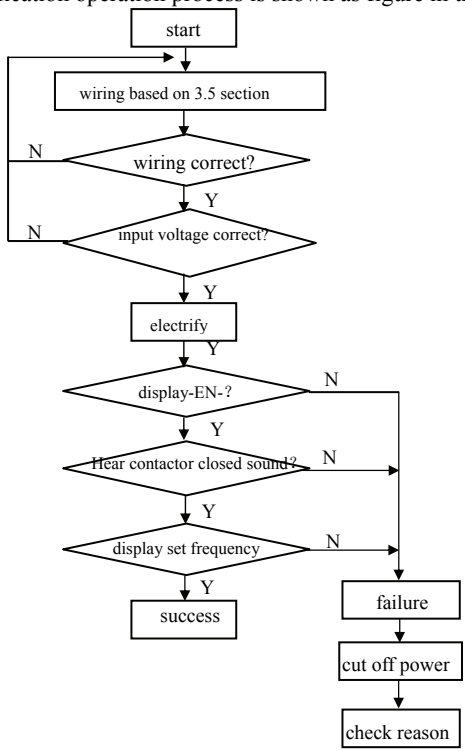


Fig. 4-14 first electrification operation flow

5 Function parameter schedule graph

5.1 Symbol description

× ---- parameter can't be changed in process of running

○ ---- parameter can be changed in process of running

* ---- read-only parameter, unmodifiable

5.2 Function parameter schedule graph

F0 –basic run function parameter group					
Function code	Name	Set range	Min. unit	Factory default	Modification
F0.00	Provided/Frequency input channel selection	0: keypad analog potentiometer setting 1: keypad digital setting 2: terminal UP/DOWN adjust setting (stored after power off) 3: serial port setting(not stored after power off) 4: VCI analog setting (VCI-GND) 5: CCI analog setting (CCI-GND) 6: YCI analog setting (YCI-GND) 7: terminal pulse (PULSE) setting 8: combination setting 9: terminal UP/DOWN adjust setting (not stored after power off) 10: serial port setting(stored after power off)	1	1	○
F0.01	Freq. digit setting	Lower limit Freq.～upper limit Freq.	0.01Hz	50.00Hz	○
F0.02	Run command channel selection	0: keypad run control 1: terminal run command control (keypad stop command ineffective) 2: terminal run command control (keypad stop command effective) 3: serial port run command control (keypad stop command ineffective) 4: serial port run command control (keypad stop command effective)	1	0	○
F0.03	Run direction setting	1st bit: 0, forward run; 1, reverse run 2nd bit: 0, reverse run allowed 1, reverse run banned 3rd bit: REV/JOG key selection 0: as reverse run key 1: as jog key	1	100	○
F0.04	Acce/Dece mode selection	0: linear accelerating decelerating mode 1: S curve accelerating decelerating mode	1	0	×
F0.05	S curve start section time	10.0(%)－50.0(%)(Acce/Dece time) F0.05+F0.06≤90(%)	0.1(%)	20.0(%)	○

F0.06	S curve risetime	10.0(%)－70.0(%)(Acce/Dece time) F0.05+F0.06≤90(%)	0.1(%)	60.0(%)	○
F0.07	Acce Dece time unit	0: second 1: minute	1	0	×
F0.08	Acce time 1	0.1－6000.0	0.1	20.0	○
F0.09	Dece time 1	0.1－6000.0	0.1	20.0	○
F0.10	Upper limit freq.	Lower limit freq.－400.00Hz	0.01Hz	50.00Hz	×
F0.11	Lower limit freq.	0.00－Upper limit freq.	0.01Hz	0.00Hz	×
F0.12	Lower limit freq. run mode	0: run at lower limit freq. 1: stop by slow down 2: free stop(when the provided freq. is higher than lower limit freq. then recover)	1	0	×
F0.13	Torque boost mode	0: manual boost 1: automatic boost	1	0	○
F0.14	Torque boost	0.0－12.0 (%)	0.1(%)	2.0(%)	○
F0.15	V/F curve setting	0: constant torque curve 1: degressive torque curve 1(the 2.0nd power) 2: degressive torque curve 2 (the 1.7th power) 3: degressive torque curve 3 (the 1.2th power) 4: End-user sets VF curve himself(determined by F2.37~F2.44)	1	0	×
		F2.37 VF Freq. value 0			
		F2.38 VF voltage value 0	0.01Hz	10.00Hz	×
		F2.39 VF Freq. value 1	0.01%	20.00%	×
		F2.40 VF voltage value 1	0.01Hz	20.00Hz	×
		F2.41 VF Freq. value 2	0.01%	40.00%	×
		F2.42 VF voltage value 2	0.01Hz	25.00Hz	×
		F2.43 VF Freq. value 3	0.01%	50.00%	×
		F2.44 VF voltage value 3	0.01Hz	40.00Hz	×
		Remark: VF frequency and voltage can't be 0 or maximum	0.01%	80.00%	×
F0.16	Control mode selection	0: V/F control 1: no-speed sensor vector control	1	0	×

F1 –start-up, stop, brake function parameter group					
Function code	Name	Set range	Min. unit	Factory default	Modifi-cation
F1.00	Start-up run mode	0: start at start-up freq. 1: first brake, then start at start-up freq.	1	0	×
F1.01	start-up freq.	0.0－10.00Hz	0.01Hz	0.00Hz	○
F1.02	start-up freq. duration	0.0－20.0S	0.1s	0.0s	○
F1.03	DC brake volt. at start-up	0－15(%)	1	0	○

F1.04	DC brake time at start-up	0.0－20.0S	0.1s	0.0s	○
F1.05	Stop mode	0: Dec stop 1: free stop 2: Dec＋DC brake stop	1	0	×
F1.06	DC brake initiative freq. when stop running	0.0－15.00Hz	0.01Hz	0.00Hz	○
F1.07	DC brake time when stop running	0.0－20.0s	0.1s	0.0s	○
F1.08	DC brake voltage when stop running	0－15(%)	1	0	○

F2 –auxiliary run function parameter group					
Function code	Name	Set range	Min. unit	Factory default	Modification
F2.00	Analog filter time constant	0.00－30.00s	0.01s	0.20s	○
F2.01	Forward reverse run dead-section time	0.0－3600.0s	0.1s	0.1s	○
F2.02	dead-section time Compensation fixed	0~150(%)	1	100	○
F2.03	AVR function	0: no action 1: action all the time 2: no action only during Dec	1	2	×
F2.04	Slip frequency compensation	0～150(%)0-no slip frequency compensation	1	0	×
F2.05	Carrier wave freq.	2－14.0K	0.1K	depend on machine type	×
F2.06	Jog run frequency	0.10－50.00Hz	0.01Hz	5.00Hz	○
F2.07	Jog Acc time	0.1－60.0s	0.1s	20.0s	○
F2.08	Jog Dec time	0.1－60.0s	0.1s	20.0s	○
F2.09	Provided/Frequency input channel combination	0: VCI＋CCI 1: VCI－CCI 2: YCI＋CCI 3: RS485+YCI 4: VCI＋YCI 5: reserved 6: exterior pulse provision＋CCI 7: exterior pulse provision－CCI 8: reserved 9: reserved 10: reserved 11: reserved 12: reserved 13: VCI，CCI any nonzero value effective, VCI preferred 14: reserved	1	0	×

		15: RS485+CCI 16: RS485-CCI 17: RS485+VCI 18: RS485-VCI 19: RS485+keypad potentiometer 20: RS485- keypad potentiometer 21: VCI+ keypad potentiometer 22: VCI- keypad potentiometer 23: CCI+ keypad potentiometer 24: CCI- keypad potentiometer 25: reserved 26: reserved 27: reserved 28: reserved			
F2.10	Principal subordinate machine communication frequency provision proportion	0(%)－500(%)	1(%)	100(%)	○
F2.11	LED display control 1	0000-1111 first bit: running time 0: not display 1: display second bit: accumulative time 0: not display 1: display third bit: input terminal status 0: not display 1: display kilobit(fourth bit): output terminal status 0: not display 1: display	1	0000	○
F2.12	LED display control 2	0000-1111 first bit: analog input VCI 0: not display 1: display second bit: analog input YCI 0: not display 1: display third bit: analog input CCI 0: not display 1: display kilobit(fourth bit): exterior pulse input 0: not display 1: display	1	1111	○
F2.13	Parameter operation	LED 1st bit:	1	0	×

	control	0: all parameter allowed to be modified 1: except this parameter，all other parameter not allowed to be modified 2: except F0.01 and this parameter, all other parameter not allowed to be modified LED 2nd bit: 0: no action 1: restore default value 2: clear history failure record LED 3rd bit: 0: lock all buttons 1: lock all buttons but not STOP key 2: lock all buttons but not ▲ ▼, STOP key 3: lock all buttons but not RUN, STOP key 4: lock all buttons but not SHIFT, STOP key			
F2.14	Communication configuration	LED first bit: baud rate selection 0: 1200BPS 1: 2400BPS 2: 4800BPS 3: 9600BPS 4: 19200BPS 5: 38400BPS LED second bit: data format 0: 1－8－1format, no checkout 1: 1－8－1 format, even checkout 2: 1－8－1 format, odd checkout	1	03	×
F2.15	Local address	0－127，127 is broadcast address. The inverter only receive but not send when it is set to be 127, 0 is address for main device.	1	1	×
F2.16	Communication overtime	0.0－1000.0s	0.1s	0.0s	×
F2.17	Local response delay	0－200ms	1ms	5ms	×
F2.18	Acce time 2	0.1－6000.0	0.1	20.0	○
F2.19	Dece time 2	0.1－6000.0	0.1	20.0	○
F2.20	Acce time 3	0.1－6000.0	0.1	20.0	○

F2.21	Dece time 3	0.1－6000.0	0.1	20.0	○
F2.22	Acce time 4	0.1－6000.0	0.1	20.0	○
F2.23	Dece time 4	0.1－6000.0	0.1	20.0	○
F2.24	Acce time 5	0.1－6000.0	0.1	20.0	○
F2.25	Dece time 5	0.1－6000.0	0.1	20.0	○
F2.26	Acce time 6	0.1－6000.0	0.1	20.0	○
F2.27	Dece time 6	0.1－6000.0	0.1	20.0	○
F2.28	Acce time 7	0.1－6000.0	0.1	20.0	○
F2.29	Dece time 7	0.1－6000.0	0.1	20.0	○
F2.30	Multisection freq. 1	Lower limit freq.－upper limit freq.	0.01Hz	5.00Hz	○
F2.31	Multisection freq. 2	Lower limit freq.－upper limit freq.	0.01Hz	10.00Hz	○
F2.32	Multisection freq. 3	Lower limit freq.－upper limit freq.	0.01Hz	20.00Hz	○
F2.33	Multisection freq. 4	Lower limit freq.－upper limit freq.	0.01Hz	30.00Hz	○
F2.34	Multisection freq. 5	Lower limit freq.－upper limit freq.	0.01Hz	40.00Hz	○
F2.35	Multisection freq. 6	Lower limit freq.－upper limit freq.	0.01Hz	45.00Hz	○
F2.36	Multisection freq. 7	Lower limit freq.－upper limit freq.	0.01Hz	50.00Hz	○
F2.37	VF frequency value 0	0.00-F2.39	0.01Hz	10.00Hz	○
F2.38	VF voltage value 0	0.00-F2.40	0.01%	20.00%	○
F2.39	VF frequency value 1	F2.37-F2.41	0.01Hz	20.00Hz	○
F2.40	VF voltage value 1	F2.38-F2.42	0.01%	40.00%	○
F2.41	VF frequency value 2	F2.39-F2.43	0.01Hz	25.00Hz	○
F2.42	VF voltage value 2	F2.40-F2.44	0.01%	50.00%	○
F2.43	VF frequency value 3	F2.41-high limit frquency	0.01Hz	40.00Hz	○
F2.44	VF voltage value 3	F2.42-100.0% (rated voltage)	0.01%	80.00%	○
F2.45	Jumping freq. 1	0.00－400.00Hz	0.01Hz	0.00Hz	×
F2.46	Jumping freq. 1 range	0.00－30.00Hz	0.01Hz	0.00Hz	×
F2.47	Reserved				
F2.48	Reserved				
F2.49	Reserved				
F2.50	Reserved				
F2.51	Setting run time	0－65535 hours	1	0	○
F2.52	Accumulative run time	0－65535 hours	1	0	*
F2.53	RS485/232 communication frame format selection	0: a ASCII frame of 14 byte or 18 byte 1: a hex frame of 8 byte or 10 byte, original response not changed 2: a hex frame of 8 byte or 10 byte, 12 command has no response 3: a hex frame of 8 byte or 10 byte, 14 command has no response 4: a hex frame of 8 byte or 10 byte, both 12 and 14 command have no response	1	0	×

F3– closed-loop run function parameter group					
Function code	Name	Set range	Min. unit	Factory default	Modif-ication
F3.00	Closed-loop run control selection	0: closed-loop control ineffective 1: PID closed-loop control effective 2: constant pressure water supply PID control effective(F5.10～F5.13 must be set to 21)	1	0	×
F3.01	Provision channel selection	0: digital provision 1: VCI analog 0—10V voltage provision 2: CCI analog provision 3: keypad potentiometer provision	1	1	○
F3.02	Feedback channel selection	0: VCI analog input voltage 0—10V 1: CCI analog input 2: VCI+CCI 3: VCI-CCI 4: Min { VCI, CCI } 5: Max { VCI, CCI } 6: pulse feedback	1	1	○
F3.03	Specified value digital setting	0.000~9.999V	0.001	1.000	○
F3.04	Minimum specified value	0.0—maximum specified value; percentage relative to 10.00V	0.1(%)	0.000	○
F3.05	feedback value responding to minimum specified value	0.0—100.0(%)	0.1(%)	0.000	○
F3.06	maximum specified value	Minimum specified value —100.0(%)	0.1(%)	100.0(%)	○
F3.07	feedback value responding to maximum specified value	0.0—100.0(%)	0.1(%)	100.0(%)	○
F3.08	proportion gain Kp	0.000—9.999	0.001	0.050	○
F3.09	Integral gain Ki	0.000—9.999	0.001	0.050	○
F3.10	Differential gain Kd	0.000—9.999	0.001	0.000	○
F3.11	Sampling cycle T	0.01—1.00s	0.01s	0.10s	○
F3.12	Deviation margin	0.0—20.0(%)percentage relative to 10.00V	0.1(%)	2.0(%)	○
F3.13	Integral separation PID adjusting threshold	0.0—100.0%	0.1%	100.0%	○
F3.14	Closed-lop preset frequency	0—upper limit frequency	0.01Hz	00.00	○
F3.15	Closed-loop preset frequency holding time	0.0-6000s	0.1s	000.0	○
F3.16	Reserved				

F3.17	Reserved				
F3.18	Reserved				
F3.19	Reserved				
F3.20	Reserved				
F3.21	Reserved				
F3.22	Reserved				
F3.23	Reserved				
F3.24	Run speed display factor	0.01－4.00	0.01	1	○
F3.25	Reserved				
F3.26	supervision parameter display selection	0: C-11, C-12 denote voltage value of VCI, CCI 1: C-11, C-12 denote PID specified pressure and feedback pressure	1	0	○
F3.27	Closed-loop adjusting characteristic	0: Forward function 1: Reverse function		0	○
F3.28	LED initial supervision parameter selection	0: set frequency 1: output frequency 2: output current 3: output voltage 4: DC bus bar voltage 5: motor speed 6: heat sink temperature 7: run time 8: accumulative run time 9: input terminal status 10: output terminal status 11: analog input VCI/PID provision 12: analog input CCI/PID feedback 13: analog input YCI 14: exterior pulse inputs		1	○
F3.29	Reserved				
F3.30	Failure relay TA，TB，TC function selection	0: inverter running(RUN) 1: frequency arriving signal(FAR) 2: frequency level detect signal (FDT1) 3: reserved 4: overload warning alarm signal (OL) 5: output frequency reach high limit(FHL) 6: output frequency reach low limit(FLL) 7: inverter under voltage blockage stop (LU) 8: external failure stop-running(EXT) 9: inverter zero speed running 10: PLC running 11: simple PLC section running finished 12: PLC finish a cycle running 13: reserved 14: inverter ready to run (RDY)		15	○

		15: inverter failure 16: reserved 17: interior counter reach final value 18: interior counter reach specified value 19: set run time arriving 20: interior timing arriving 21: reserved 22: reserved 23: reserved 24: reserved			
F3.31	Reserved				

F4 –simple PLC function parameter group					
Function code	Name	Set range	Min. unit	Factory default	Modif-ication
F4.00	Simple PLC running setting	LED first bit: 0: no action 1: stop after single circulation 2: keep final value after single circulation 3: consecutive circulation LED second bit: 0: start again from first section 1: continue to run at mid-section frequency LED third bit: PLC run time unit 0: second 1: minute	1	000	×
F4.01	Section 1 setting	000－621 LED first bit: frequency setting 0: multisection freq. i (i=1~7) 1: freq. determined by F0.00 function code LED second bit: run direction selection 0: forward run 1: reverse run 2: determined by run command LED third bit: Acc/Dec time selection 0: Acc/Dec time 1 1: Acc/Dec time 2 2: Acc/Dec time 3 3: Acc/Dec time 4 4: Acc/Dec time 5 5: Acc/Dec time 6	1	000	○

		6: Acc/Dec time 7			
F4.02	Section 1 run time	0－6000.0	0.1	10.0	○
F4.03	Section 2 setting	000－621	1	000	○
F4.04	Section 2 run time	0－6000.0	0.1	10.0	○
F4.05	Section 3 setting	000－621	1	000	○
F4.06	Section 3 run time	0－6000.0	0.1	10.0	○
F4.07	Section 4 setting	000－621	1	000	○
F4.08	Section 4 run time	0－6000.0	0.1	10.0	○
F4.09	Section 5 setting	000－621	1	000	○
F4.10	Section 5 run time	0－6000.0	0.1	10.0	○
F4.11	Section 6 setting	000－621	1	000	○
F4.12	Section 6 run time	0－6000.0	0.1	10.0	○
F4.13	Section 7 setting	000－621	1	000	○
F4.14	Section 7 run time	0－6000.0	0.1	10.0	○

F5 –terminal correlative function parameter group					
Function code	Name	Set range	Min. unit	Factory default	Modif-ication
F5.00	Input terminal X1 function selection	0: leave control terminal unused 1: multisection speed control terminal 1 2: multisection speed control terminal 2 3: multisection speed control terminal 3 4: multisection speed control terminal 4 5: external forward run jog control 6: external reverse run jog control 7: Acc/Dec time option terminal 1 8: Acc/Dec time option terminal 2 9: Acc/Dec time option terminal 3 10: external device failure input 11: external reset input 12: free stop input 13: external stop-running order 14: stop DC braking input command DB 15: inverter run banned 16: frequency increasing control (UP) 17: frequency degression control (DOWN) 18: Acc/Dec ban command 19: three-line run control 20: closed-loop ineffective 21: PLC ineffective 22: simple PLC pause control 23: PLC stop status reset 24: frequency provision channel option 1 25: frequency provision channel option 2 26: frequency provision channel option 3	1	0	×

		27: frequency switched to CCI 28: command switched to terminal 29: run command channel option 1 30: run command channel option 2 31: run command channel option 3 32: reserved 33: reserved 34: interior counter reset end 35: interior counter triggering end 36: interior timer reset end 37: interior timer triggering end 38: pulse frequency input(only effective forX7,X8) 39: reserved 40: reserved 41: reserved 42: reserved			
F5.01	Input terminal X2 function selection	Same as above	1	0	×
F5.02	Input terminal X3 function selection	Same as above	1	0	×
F5.03	Input terminal X4 function selection	Same as above	1	0	×
F5.04	Input terminal X5 function selection	Same as above	1	0	×
F5.05	Input terminal X6 function selection	Same as above	1	0	×
F5.06	Input terminal X7 function selection	Same as above	1	0	×
F5.07	Input terminal X8 function selection	Same as above	1	0	×
F5.08	FWD/REV run mode selection	0: double-line control mode 1 1: double-line control mode 2 2: three-line control mode 1 3: three-line control mode 2	1	0	×
F5.09	UP/DOWN velocity	0.01－99.99Hz/s	0.01Hz/s	1.00Hz/s	○
F5.10	Open circuit collector output terminal OC1 output setting	0: inverter running(RUN) 1: frequency arriving signal(FAR) 2: frequency level detect signal (FDT1) 3: reserved 4: overload warning alarm signal (OL) 5: output frequency reach high limit(FHL) 6: output frequency reach low limit(FLL) 7: inverter under voltage blockage stop (LU) 8: external failure stop-runnin(EXT) 9: inverter zero rotate speed running	1	0	×

		10: PLC running 11: simple PLC section running finished 12: PLC finish a cycle running 13: reserved 14: inverter ready to run (RDY) 15: inverter failure 16: reserved 17: interior counter reach final value 18: interior counter reach specified value 19: set run time arriving 20: interior timing arriving 21: multi-function input terminal signal input 22: reserved 23: reserved 24: reserved			
F5.11	Open circuit collector output terminal OC2 output setting	Same as above	1	0	×
F5.12	Open circuit collector output terminal OC3 output setting	Same as above	1	0	×
F5.13	Open circuit collector output terminal OC4 output setting	Same as above	1	0	×
F5.14	Frequency arriving (FAR) checkout scope	0.00－50.00Hz	0.01Hz	5.00Hz	○
F5.15	FDT1 (frequency level) electric level	0.00－high limit frequency	0.01Hz	10.00Hz	○
F5.16	FDT1 lag	0.00－50.00Hz	0.01Hz	1.00Hz	○
F5.17	Analog output (AO1) selection	0: output frequency(0－high limit frequency) 1: set frequency(0－high limit frequency) 2: output current(0－2×rated current) 3: output voltage(0－1.2×load motor rated voltage) 4: bus-bar voltage(0－800V) 5: PID provision (0.00-10.00V) 6: PID feedback (0.00-10.00V) 7: reserved 8: reserved 9: reserved	1	0	○
F5.18	Analog output (AO1) gain	0.00－2.00	0.01	1.00	○
F5.19	Analog output (AO1)	0.00－10.00V	0.01	0.00	○

	offset				
F5.20	Analog output (AO2) selection	Same as F5.17	1	0	○
F5.21	Analog output (AO2) gain	0.10－2.00	0.01	1.00	○
F5.22	Analog output (AO2) offset	0.00－10.00V	0.01	0.00	○
F5.23	DO terminal output function selection	Same as F5.17	1	0	○
F5.24	DO maximum pulse output frequency	0.1－20.0(max. 20KHz)Max. DO port output pulse frequency corresponds to Max. value selected by F5.23	0.1KHz	10.0	○
F5.25	Set interior counting value reaches provision	0--9999	1	0	○
F5.26	Specified interior counting value reaches provision	0--9999	1	0	○
F5.27	Interior timer setting	0.1－6000.0s	0.1	60.0	○

F6 –swing frequency special function parameter group					
Function code	Name	Set range	Min. unit	Factory default	Modif-ication
F6.00	Reserved				
F6.01	Suppression oscillator lower limit freq.	0.00－2.00	0.01Hz	0.50Hz	○
F6.02	Suppression oscillator upper limit freq.	8.50－35.00	0.01Hz	12.50Hz	○
F6.03	Suppression oscillator gain compensation	100.0－130.0(%)	0.1(%)	100.0(%)	○
F6.04	Torque limit value	50.0－200.0%	0.1%	150.0%	○
F6.05	Speed loop proportion gain	0.000－6.000	0.001	0.700	○
F6.06	Speed loop integral time constant	0.000－9.999	0.001	0.360	○
F6.07	Reserved				

F7–frequency provision function parameter group					
Function code	Name	Set range	Min. unit	Factory default	Modifi-cation
F7.00	VCI min. provision	0.00－F7.02	0.01V	0.00V	○
F7.01	VCI min. provision corresponding freq.	0.00－high limit frequency	0.01Hz	0.00 Hz	○
F7.02	VCI max. provision	0.00－10.00V	0.01V	9.9V	○
F7.03	VCI max. provision corresponding freq.	0.00－high limit frequency	0.01 Hz	50.00 Hz	○

F7.04	CCI min. provision	0.00－F7.06	0.01V	0.00V	○
F7.05	CCI min. provision corresponding freq.	0.00－high limit frequency	0.01 Hz	0.00 Hz	○
F7.06	CCI max. provision	0.00－10.00V	0.01V	9.9V	○
F7.07	CCI max. provision corresponding freq.	0.00－high limit frequency	0.01 Hz	50.00 Hz	○
F7.08	YCI min. provision	0.00－F7.10	0.01V	0.00V	○
F7.09	YCI min. provision corresponding freq.	0.00－high limit frequency (reverse run)	0.01 Hz	50.00 Hz	○
F7.10	YCI max. provision	0.00－10.00V	0.01V	9.9V	○
F7.11	YCI max. provision corresponding freq.	0.00－high limit frequency (forward run)	0.01 Hz	50.00 Hz	○
F7.12	YCI dead area setting	0.00V－2.00V	0.01V	0.10V	○
F7.13	PULSE max. input pulse	0.01－20.0K	0.01K	10.0K	○
F7.14	PULSE min. provision	0.0－F7.16(PULSE max. provision)	0.01K	0.0K	○
F7.15	PULSE min. provision corresponding freq.	0.00－high limit frequency	0.01 Hz	0.00 Hz	○
F7.16	PULSE max. provision	F7.14 (PULSE min. provision) － F7.13 (max. input pulse)	0.1K	10.0K	○
F7.17	PULSE max. provision corresponding freq.	0.00－high limit frequency	0.01 Hz	50.00 Hz	○

F8–motor and vector control parameter group					
Function code	Name	Set range	Min. unit	Factory default	Modifi-cation
F8.00	Load type	0: G type constant torque/ saltation load use 1: L type light load/steady load use 2: J type large inertia load/heavy load use	1	0	×
F8.01	Motor rated voltage	1－480V	1V	Depend on device type	×
F8.02	Motor rated current	0.1－999.9A	0.1A	Depend on device type	×
F8.03	Motor rated frequency	1.00－400.00Hz	0.01 Hz	Depend on device type	×
F8.04	Motor rated speed	1－9999r/min	1r/min	Depend on device type	×
F8.05	Motor pole	2－14	2	Depend on device type	×
F8.06	Motor rated power	0.1－999.9KW	0.1	Depend on device type	×
F8.07	stator resistance	0.000－9.9999ohm	0.001 ohm	Depend on device type	×

F8.08	rotor resistance	0.000－9.9999ohm	0.001 ohm	Depend on device type	×
F8.09	Stator leakage inductance	0.0－999.9mH	0.1 mH	Depend on device type	×
F8.10	rotor leakage inductance	0.0－999.9mH	0.1 mH	Depend on device type	×
F8.11	Mutual inductance	0.0－999.9mH	0.1 mH	Depend on device type	×
F8.12	Motor no load current	0.1－999.9A	0.1A	Depend on device type	×
F8.13	Reserved				
F8.14	Reserved				
F8.15	Reserved				
F8.16	Reserved				
F8.17	Parameter selfTune	0: no action 1: static selfTune 2: rotate no load selfTune	1	0	×

F9 –protection correlative function parameter group					
Function code	Name	Set range	Min. unit	Factory default	Modific-ation
F9.00	Instantaneous power off restarting latency time	0.0－10.0S 0 indicates ineffective power off restarting	0.1S	0.0S	×
F9.01	Failure self-renew times	0－10 0 shows no automatic reset function	1	0	×
F9.02	Failure self-renew interval	0.5－20.0S	0.1S	5.0S	×
F9.03	Motor overload protection mode selection	0: no action 1: inverter close off output	1	1	×
F9.04	Motor overload protection coefficient	20.0-120.0(%)	0.1(%)	100.0(%)	×
F9.05	Overload warning alarm checkout level	20－200(%)	1(%)	130(%)	○
F9.06	Overload warning alarmDelay time	0.0－20.0s	0.1s	5.0s	○
F9.07	Reserved				
F9.08	Overvoltage stall point	120-150(%)	1(%)	130(%)	○
F9.09	Automatic current limit level	110－200(%)	1(%)	150(%)	×

F9.10	Frequency declining rate during current limiting	0.00－99.99Hz/s	0.01Hz/s	10.00Hz/s	○
F9.11	Automatic current limiting action selection	0: constant speed ineffective 1: constant speed effective remark: Acc/Dec always effective	1	0	×

FA – stop assistant function parameter group					
Function code	Name	Set range	Mini. unit	Factory setting	Modif-ication
FA.00	auxiliaryDC brake time	0.0—999.9s	0.1s	0.0s	○
FA.01	auxiliaryDC brake time	0—10.0（%）	0.1（%）	0.0（%）	○
FA.02	Reserved				
FA.03	Reserved				

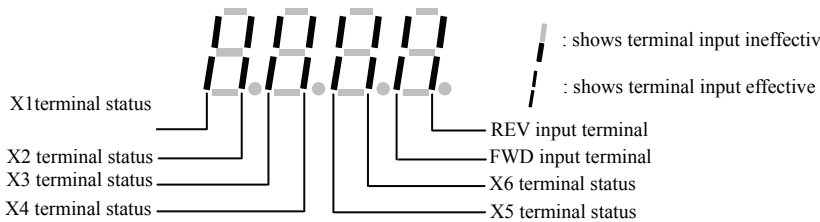
Fd –failure record function parameter group					
Function code	Name	Setting range	Min. unit	Factory default	Modif-ication
Fd.00	Previous one time failure record	Previous one time failure record	1	0	*
Fd.01	Previous two time failure record	Previous two time failure record	1	0	*
Fd.02	Previous three time failure record	Previous three time failure record	1	0	*
Fd.03	Previous four time failure record	Previous four time failure record	1	0	*
Fd.04	Previous five time failure record	Previous five time failure record	1	0	*
Fd.05	Previous six time failure record	Previous six time failure record	1	0	*
Fd.06	Set freq. of previous failure	Set freq. of previous failure	0.01Hz	0	*
Fd.07	output freq. of previous failure	output freq. of previous failure	0.01Hz	0	*
Fd.08	output current of previous failure	output current of previous failure	0.1A	0	*
Fd.09	output voltage of previous failure	output voltage of previous failure	1V	0	*
Fd.10	DC bus-bar voltage of previous failure	DC bus-bar voltage of previous failure	1V	0	*
Fd.11	Load motor speed of previous failure	Load motor speed of previous failure	1(r/m)	0	*
Fd.12	Module temperature of previous failure	Module temperature of previous failure	1℃	0	*
Fd.13	Input terminal status of previous failure	Input terminal status of previous failure		11111111	*
Fd.14	Accumulative run time of previous failure	Accumulative run time of previous failure		0	*

FF –password and manufacturer function parameter group					
Function code	Name	Setting range	Min. unit	Factory default	Modification
FF.00	User password	0000－9999	1	0000	×

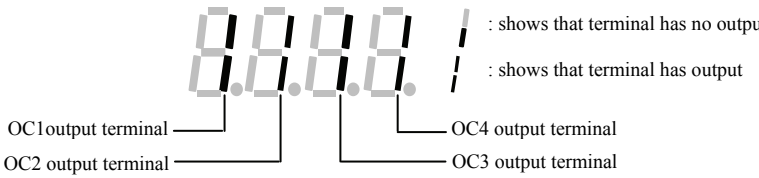
FF.01	Manufacturer password	0000－9999	1	0000	×

C –supervision function parameter group					
Function code	Name	Description	Min. unit	Factory default	Modific-ation
C-00	Set frequency	Current set frequency	0.01HZ		
C-01	Output freq.	Current output freq.	0.01HZ		*
C-02	Output current	Virtual value of current output current	0.1A		*
C-03	Output voltage	Virtual value of current output voltage	1V		*
C-04	DC bus-bar voltage	Current DC bus-bar voltage	1V		*
C-05	Load motor speed	Product of output frequency and load motor speed emendation factor	1(r/m)		*
C-06	Module temperature	IGBT heat sink temperature	1℃		*
C-07	Run time	Inverter electrification run time	1h		*
C-08	accumulative run time	Inverter accumulative run time	1h		*
C-09	Input terminal status	Switch value input terminal status	－－		*
C-10	output terminal status	Switch value output terminal status	－－		*
C-11	Analog input VCI	Analog input value of VCI	V		*
C-12	Analog input YCI	Analog input value of YCI	V		*
C-13	Analog input CCI	Analog input value of CCI	V		*
C-14	Exterior pulse input	Exterior pulse input	0.1KHz		*

(1) input terminal status corresponding relation is as follows:



(2) output terminal status corresponding relation is as follows:



6 Detailed function description

Listed column content for parameter function code description in this chapter is as follows:

Code	Name	Set range or description	Factory default

6.1 Basic run function parameter group: F0

F0.00	**Provided/Frequency input channel selection**	**range: 0~16**	**0**

0: keypad analog potentiometer. Set running frequency by keypad analog potentiometer.

1: keypad frequency number setting. Initial set frequency value is F0.01，can change set frequency by changing F0.01 parameter through keypad，and you can also modify F0.01 by ▲ , ▼ key.

2: terminal UP/DOWN adjust set frequency(stored after power off orstop). Initial set frequency value is the value stored during the last power off time，and you can adjust set running frequency by terminal UP/DOWN.

3: serial port provision(no memory after electric off). Serial port frequency set initial value is F0.01，change set frequency by setting F0.01 through serial port,after electic off ,it need to set the new specified frequency value.

4: VCI analog setting(VCI－GND). Frequency setting determined by VCI terminal analog voltage，input voltage range: DC0~10V.

5: CCI analog setting (CCI－GND). Frequency setting determined by CCI terminal analog voltage /current，input range: DC0~10(CCI jumping wire choose V side)，DC: 4~20mA (CCI jumping wire choose A side).

6: YCI analog setting (YCI－GND). Frequency setting determined by YCI terminal analog voltage，input range: DC0~10V(YCI jumping wire choose10V side)or DC0~5V(YCI jumping wire choose 5V side).

7: terminal pulse (PULSE) setting. Frequency set by terminal pulse(only input through X7 or X8，see F5.06~F5.07 definition)，input pulse signal spec: voltage range15~24V；frequency range 0~20.0KHz.

8: combination setting. See function parameter F2.09，set frequency by eachchannel combination setting.

9: terminal UP/DOWN adjust set frequency(not stored after power off or stop)Initial set frequency value is F0.01，and adjust set running frequency by terminal UP/DOWN.

10:serial port specified(memory after electric off):when the inverter is disconnected with electic,it will keep the currently running frequency,and next time it will keep the former frequency running the electric on .

Note

Relation between frequency and input information is determined by function code F7.00~F7.17 when frequency input channel is 4, 5, 6, 7，please see Section 6.8.

F0.01	Freq. number setting	range: low limit ～high limit	50.00Hz

F0.01 parameter is original set frequency of the inverter when frequency setting channel is defined as number setting (F0.00＝1, 3).

F0.02	Run command channel selection	range: 0~4	0

0: keypad run frequency command channel. Start and stop the inverter by RUN , STOP, REV/JOG key on the keypad.

1: terminal run command channel(keypad STOP comand ineffective). Start and stop the inverter by exterior control terminal FWD, REV, X1~X8 etc..

2: terminal run command channel(keypad STOP command effective). Start and stop the inverter by exterior control terminal FWD, REV, X1~X8 etc..

3: serial port run command channel(keypad STOP command ineffective). Start and stop the inverter by RS485 interface.

4: serial port run command channel(keypad STOP command effective). Start and stop the inverter by RS485 interface.

The inverter can change run command channel by modifying F0.02 during waiting and running，please confirm that modification is allowed during running on the spot.

F0.03	Run direction setting	Range: 0, 1	100

The 1st bit:

0: inverter forward run

1: inverter reverse run

The 2nd bit:

0: reverse run allowed

1: reverse run banned. The inverter will stop output when there is reverse run command.

The 3rd bit:

REV/JOG key selection

0: as REV key

1: as JOG key

note

If the 2nd bit is set to "1", this function is effective for keypad run command channel, terminal run command channel and serial port run command channel.

F0.04	Accelerating decelerating mode selection	range: 0, 1	0

0: linear Acce/Dece mode. Output frequency increases or decreases according to constant slope, just as shown in Fig.6-1.

1: S curve Acce/Dece mode. Output frequency increases or decreases according to S curve, just as shown in Fig.6-2.

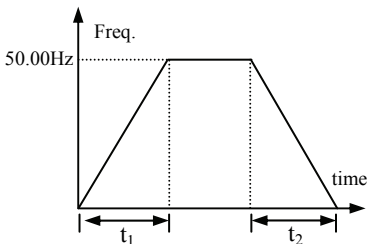


Fig.6-1 linear Acce/Dece

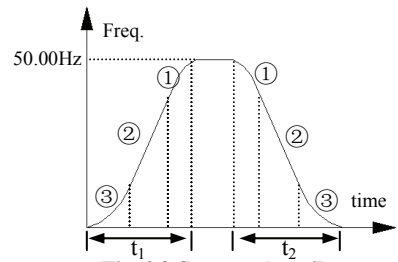


Fig.6-2 S curve Acce/Dece

F0.05	S curve starting time	range: 10.0(%)－50.0(%) (Acc/Dec time)F0.05＋F0.06≤90(%)	20.0(%)
F0.06	S curve rising time	range: 10.0(%)－70.0(%) (Acc/Dec time)F0.05＋F0.06≤90(%)s	60.0(%)

F0.05, F0.06 is only effective when S curve Acc/Dec mode(F0.04＝1)is selected during Acc/Dec selection, and **F0.05 ,F0.06**≤90%.

S curve starting time is shown as Fig. 6-2③，slope of output frequency variation increases by degrees from 0.

S curve rising time is shown as Fig.6-2②，slope of output frequency variation is constant.

S curve ending time is shown as Fig.6-2①，slope of output frequency variation steps down to 0.

note

S curve Acc/Dec mode，suitable for starting and stopping elevator, deferent belt, carrier transporter load etc..

F0.07	Acc/Dec time unit	range: 0, 1	0

This function determines Acc/Dec time unit.

0: second

1: minute

note

(1) This function is effective for all Acc/Dec process except for jog run.

(2) To choose second as time unit is recommended.

F0.08	**Acc time 1**	**range: 0.1－6000.0**	**20.0**
F0.09	**Dec time 1**	**range: 0.1－6000.0**	**20.0**

Accelerating time is defined as time for inverter accelerating from 0Hz to high limit frequency，see t1 in Fig.6-3，Dec time is defined as time for inverter decelerating from high limit frequency to 0Hz, see t2 in Fig.6-3.

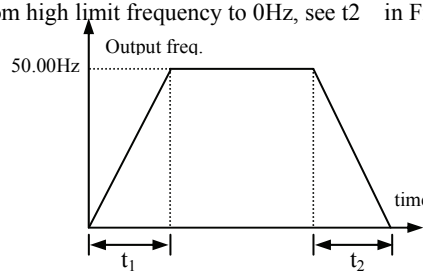


Fig.6-3 Acc/Dec time definition

note

(1) In EDS-V300 series inverter 7 kinds of Acc/Dec time are defined in total，here we only define Acc/Dec time 1，Acc/Dec time 2~7 are defined in F2.18~F2.29，please refer to Section 6.3.

(2) Can choose time unit minute or second for Acc/Dec time 1~7 by F0.07, factory default is second.

F0.10	**high limit frequency**	**range: low limit－400.00Hz**	**50.00Hz**
F0.11	**low limit frequency**	**range: 0.00－high limit**	**0.00Hz**
F0.12	**Low limit freq. run mode**	**range: 0:run at low limit freq. 1: Slow down stop 2: Free stop(when the provided freq. is higher than lower limit freq. then recover)**	**0**

The inverter will decrease output frequency gradually in set decelerating time when actual set frequency is lower than low limit frequency，after reaching low limit frequency，the inverter will run at low limit frequency if low limit frequency running mode set to 0；The inverter will reduce output frequency sequentially to zero frequency run if low limit frequency running mode set to 1; The inverter will

free stop if low limit frequency running mode set to 2. The inverter will begin to re-start from 0HZ and accelerate to a given value if given value higher than low limit frequency.

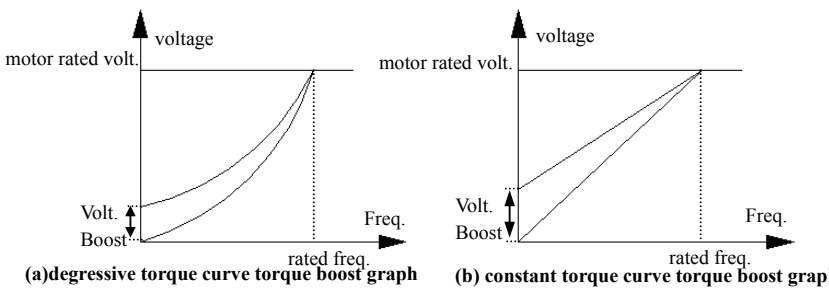
0: manual boost. Torque boost voltage is determined completely by parameter F0.14，its characteristic is boost voltage fixed，but the motor is prone to magnetic saturation when lightly loaded.

1: automatic torque boost. Torque boost voltage varies as stator current of the motor changes，bigger stator current corresponds to bigger boost voltage.

$$\text{Boost volt.}=\frac{\text{F0.14}}{100}\times\text{motor rated volt.}\times\frac{\text{inverter output current}}{2\times\text{inverter rated current}}$$

F0.14	Torque boost	Range: 0.0－12.0(%)	2.0(%)

To improve inverter's low frequency torque characteristic，can carry on boost compensation for output voltage，degressive torque curve and constant torque curve torque boost are separately shown as Fig.6-4a, b.



(a)degressive torque curve torque boost graph **(b) constant torque curve torque boost graph**

Fig.6-4 torque boost graph

note

(1) improper setting to this parameter can cause motor heating or over current protection.

(2) advise the user to adopt manual torque boost and to adjust V/F curve according to motor parameter and usage occasion when driving synchronous motor.

F0.15	V/F curve setting	range: 0~4	0

This function code defines EDS-300 flexible V/F setting mode to satisfy different load characteristic. Can choose 4 kinds of fixed curve and one custom curve according to definition of F0.15.

If F0.15=0，V/F curve bears constant torque characteristic；as curve 0 in Fig.6-5a .

If F0.15=1，V/F curve bears 2.0 order power degressive torque characteristic；as curve 3 in Fig.6-5a .

If F0.15=2，V/F curve bears 1.7 order power degressive torque characteristic；as

curve 2 in Fig.6-5a .

If F0.15=3，V/F curve bears 1.2 order power degressive torque characteristic；as curve 1 in Fig.6-5a .

The user can choose 1, 2, 3 V/F curve run mode according to load characteristic to reach better energy save result while the inverter is driving degressive torque load such as blower and water pump etc..

If F0.15=4, you can set V/F curve yourself by setting F2.37-F2.44 parameters.

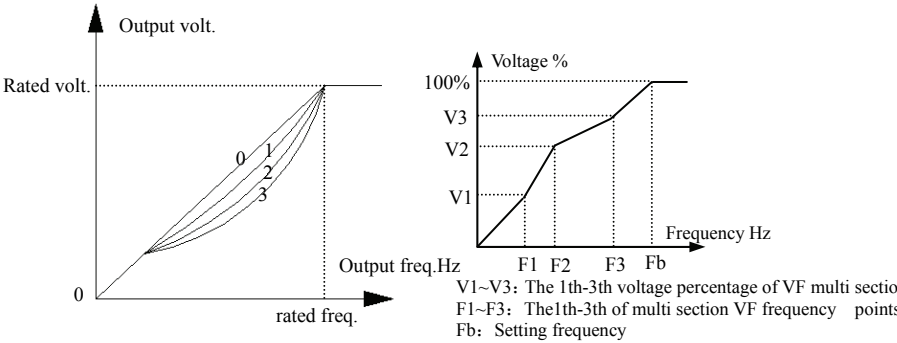


Fig.6-5 a V/F curve . . . . . b Users set the general form of V / F

F0.16	Control mode selection	range: 0~ 1	0

0: V/F control

1: no-speed sensor vector control

6.2 Start-up, stop, braking function parameter group: F1

F1.00	Start-up run mode	range: 0, 1, 2	0

0: start from starting frequency. The inverter start according to F1.01 starting frequency and F1.02 starting frequency holding time.

1: first braking then starting. First brake according to DC braking voltage and time (F1.03, F1.04)，then start at starting frequency.

note

(1) start-up mode 0: Advise the user to adopt start-up mode 0 in common application occasion and when driving synchronous motor.

(2) start-up mode 1: Be applicable to small inertia load with forward run or reverse run phenomena when the moter doesn't drive any device, for big inertia load, advise not to adopt start-up mode 1.

F1.01	**Starting frequency**	**range: 0.0－10.00Hz**	**0.00 Hz**
F1.02	**Starting freq. holding time**	**range: 0.0－20.0S**	**0.0S**

Starting frequency means initial frequency at which the inverter start up，as fs shown in Fig.6-6； Starting freq. holding time means consecutive run time during which the inverter run at starting frequency，as t_1 shown in Fig.6-6.

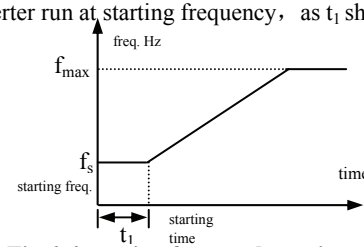


Fig.6-6 starting freq. and starting time

note Starting frequency is not limited by low limit frequency.

F1.03	**DC braking volt. when starting**	**range: 0－15(%)**	**0(%)**
F1.04	**DC braking time when starting**	**range: 0.0－20.0S**	**0.0S**

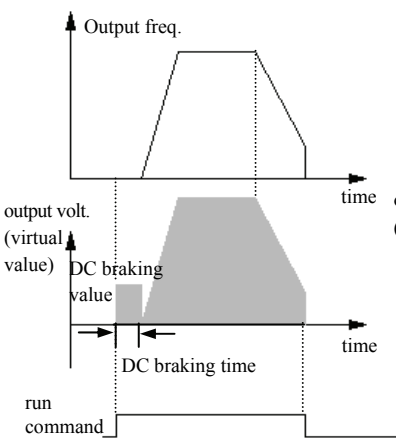


Fig.6-7 starting mode 1

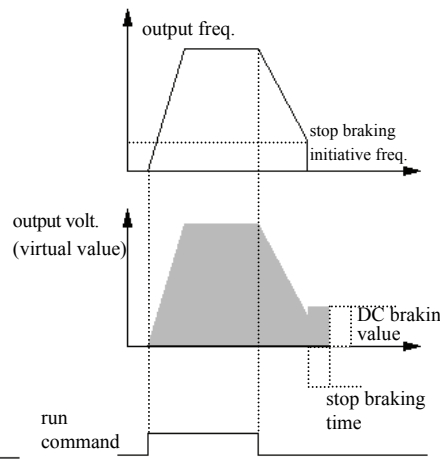


Fig.6-8 Dec stop+DC braking

F1.03 is percentage relative to inverter rated input voltage. Have no DC braking process when starting DC braking time is 0.0.

F1.05	**Stop mode**	**Range: 0, 1, 2**	**0**

0: Dec stop. The inverter reduces output frequency gradually according to set Dec time upon receival of stop command and stops running after frequency is reduced to 0.

1: free stop. The inverter stop outputting at once when receiving stop command and the load stops freely according to mechanical inertia.

2: Dec plus DC braking stop. The inverter reduces output frequency gradually according to set Dec time upon receival of stop command and start DC braking when F1.06 stop braking initiative frequency is reached.

F1.06	**Stop DC braking initiative frequency**	**range: 0.0－15.00Hz**	**3.00Hz**
F1.07	**Stop DC braking time**	**range: 0.0－20.0S**	**0.0S**
F1.08	**Stop DC braking voltage**	**range: 0－15(%)**	**0**

F1.08 is percentage relative to inverter rated input voltage. Have no DC braking process if stop braking time is 0.0s，as shown in Fig.6-8.

6.3 Auxiliary run function parameter group: F2

F2.00	**Analog filtering time constant**	**range: 0.00－30.00S**	**0.20S**

The time constant used when the inverter filter sampled value when frequency is set by exterior analog channel. Can improve the situation by increasing this filtering time constant if connecting wire is long or disturbance is serious which cause unstable set frequency.

Analog filtering time constant must be bigger than F3.11(sampling cycle), otherwise the system would run unsteadily.

F2.01	**FWD REV run dead-section time**	**range: 0.0－3600.0S**	**0.1S**

During process of transiting from forward run to reverse run or from reverse run to forward run, transition time during which the inverter wait at zero output frequency, as t_1 shown in Fig.6-10.

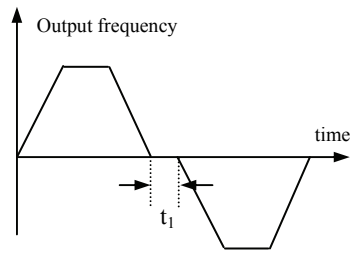


Fig.6-10 FWD REV run dead-section time

F2.02	**dead-section time compensate amend**	**range: 0~150 (%)**	**0**

Manual adjust dead-section time compensate.

F2.03	**AVR function**	**range: 0, 1, 2**	**0**

AVR namely automatic voltage adjusting function. Indicate that the inverter can output constant voltage by AVR function when the inverter input voltage fluctuates.

0: no action

1: action all the time

2: no action only during Dec

note

(1) when input voltage is higher than rated value, under normal situation should set F2.03=1. When F1.05=0 namely inverter in decelerating stop，motor Dec time is short and running current would be bigger. But the motor decrease speed placidly with small run current and long Dec time if choose AVR action all the time.

(2) should set F2.03=0, namely AVR function ineffective when the motor system oscillates which caused by choosing AVR function.

F2.04	**Slip freq. compensation**	**Range ：0～150（%）** **0— no Slip freq. compensation**	0

This function can adjust output frequency properly as the load varies to compensate slip frequency of the asynchronous motor dynamically, so that control motor speed in constant value. If act with automatic torque boost function, can get better low speed moment characteristic. As shown in Fig.6-10.

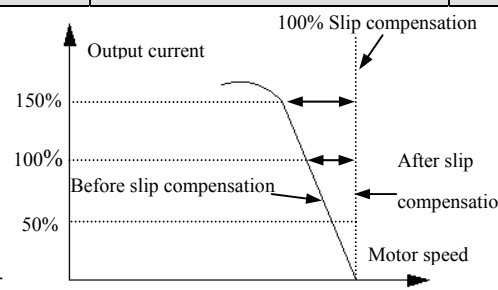


Fig.6-10 slip freq. compensation graph

When set it at the mode of vector control ,can adjust slip freq. improve control

accuracy of inverter. Restrain the static errors of speed control.

F2.05	Carrier freq.	range: 2－14.0K	Depend on device type

Carrier frequency mainly affects motor noise and heat consumption during running.Relation between carrier frequency and motor noise, current leakage, disturbance is as follows:

Carrier frequency increase(↑)，motor noise decrease(↓)，motor current leakage increase(↑)，disturbance to environment increase(↑)；

Carrier frequency decrease (↓)，motor noise increase (↑)，motor current leakage decrease (↓)，disturbance to environment decrease (↓)。

Should decrease carrier frequency properly to reduce heat consumption of the inverter when ambient temperature is high and motor load is heavy. Relation of EDS-V300 each type and carrier frequency is as shown in Table 6-1.

Table 6-1 relation table of device type and carrier frequency

carrier freq. / device type	Max.carrier freq. (KHz)	Min. carrier freq (KHz)	factory default (KHz)
0.4KW	15	2.0	2
0.75KW	14	2.0	2
1.5KW	13	2.0	2
2.2KW	12	2.0	2
3.7KW	12	2.0	2
5.5KW	11	2.0	2
7.5KW	10	2.0	2
11KW	11.0	0.7	2
15KW	10.0	0.7	2
18.5KW	9.0	0.7	2
22KW	8.0	0.7	2
30KW	7.5	0.7	2
37KW	7.0	0.7	2
45KW	6.0	0.7	2
55KW	5.5	0.7	2

note

(1) To get better control characteristic，suggest that the ratio of carrier frequency to inverter max. run frequency be not smaller than 36.

(2) Error exists in current displayed value when carrier frequency is small.

F2.06	Jog run frequency	range: 0.10－50.00Hz	5.00Hz
F2.07	Jog Acc time	range: 0.1－60.0S	20.0S
F2.08	Jog Dec time	range: 0.1－60.0S	20.0S

Jog frequency has the highest priority. Under any status, the inverter would transit to run at jog frequency at once according to set jog accelerating, decelerating time as long as jog command is inputted, as shown in Fig.6-12.

Jog accelerating time means time during which the inverter accelerate from 0Hz to high limit frequency，Jog Dec time means time during which the inverter deceleratefrom high limit frequency to 0Hz.

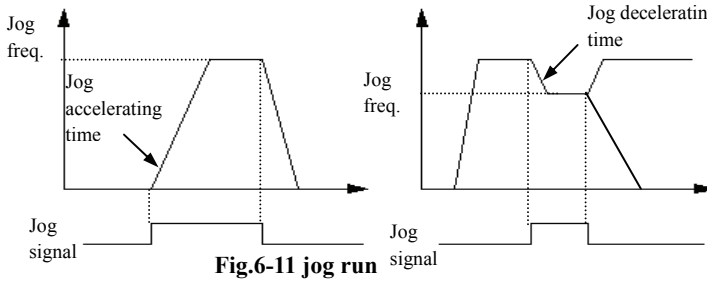


Fig.6-11 jog run

note

(1) Keypad, control terminal and serial port can do jog control all.

(2) The inverter will stop according to Dec stop mode after jog run command is withdrawn.

F2.09	Freq. input channel combination	range: 0～28	0

0: VCI＋CCI

1: VCI－CCI

2: YCI＋CCI

YCI specified frequency is positive or negative. Here YCI input 0～＋10V corresponds to frequency -50.00Hz~+50.00Hz， 0~5V corresponds to frequency -50.00～0Hz，5~10V corresponds to 0~+50.00Hz.

3: RS485+YCI

When you choose RS485+YCI，YCI input voltage 0~5V—YCI dead band (F7.12) corresponds to -50.00Hz—0.00Hz，5V—YCI dead band (F7.12)≤ YCI≤5V+YCI dead band (F7.12) corresponds to 0Hz，YCI>5V+YCI dead band (F7.12) corresponds to 0.00~+50.00Hz. You can carry out tension control by this function.

4: VCI＋YCI

5: reserved

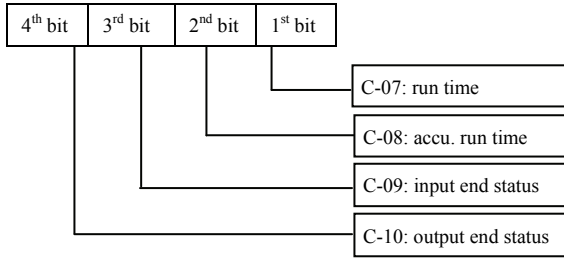
6: external pulse provision＋CCI
7: external pulse provision－CCI
8: reserved
9: reserved
10: reserved
11: reserved
12: reserved
13: VCI，CCI any nonzero value effective，VCI preferred
14: reserved
15: RS485+CCI
16: RS485-CCI
17: RS485+VCI
18: RS485-VCI
19: RS485+keypad analog potentiometer
20: RS485- keypad analog potentiometer
21: VCI+ keypad analog potentiometer
22: VCI- keypad analog potentiometer
23: CCI+ keypad analog potentiometer
24: CCI- keypad analog potentiometer
25: reserved
26: reserved
27: reserved
28: reserved

F2.10	**main&sub inverter communication freq. provision proportion**	**range: 0－500(%)**	**100(%)**

Main&sub inverter communication freq. provision proportion，this parameter need to be set in sub inverter but not need in main inverter.

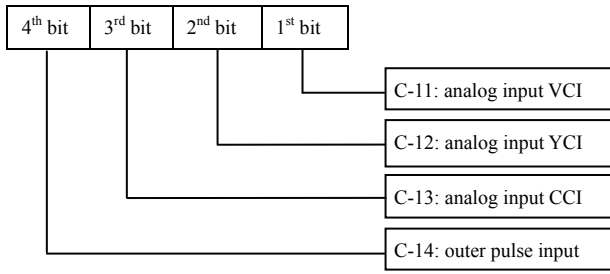
F2.11	**LED display control 1**	**range: 0000-1111**	**0000**

F2.11 make use of 4 bits of the parameter to set if C.07—C.10 is displayed in parameter, thereinto 0 indicates not displayed, 1 indicates displayed. Set parameter of 4 bit is as following figure:



F2.12	LED display control 2	range: 0000-1111	1111

F2.12 make use of 4 bit of the parameter to set if C.11—C.14 is displayed in parameter, thereinto 0 indicates not displayed, 1 indicates displayed. Set parameter of 4 bit is as following figure:



F2.13	Parameter operation control	range: LED 1st bit: 0~2 LED 2nd bit: 0~2 LED 3rd bit: 0~4	0

LED 1st bit

0: all parameter allowed to be modified

1: except this parameter，all other parameter not allowed to be changed

2: except F0.01 and this parameter，all other parameter not allowed to be changed

LED 2nd bit

0: no action

1: renew factory default

2: clear history failure record

LED 3rd bit

0: all the buttons locked

1: all the buttons locked except STOP key

2: all the buttons locked except ▲ ▼, STOP key

3: all the buttons locked except RUN, STOP key

4: all the buttons locked except SHIFT, STOP key


note

(1)Factory default of this function parameter is 0，i.e., all the function parameter can be modified.After modifying the parameter, please first set this function code to 0 if you want to modify function code setting.After modifying the parameter you can change this function code setting to expected protection grade if parameter protection is needed.

(2) After clearing memory information or renewing manufacturer parameter, the 1st bit of this function code will resume 0 automatically.

(3) After the 3rd bit of F2.13 is setted, the keypad will be locked after you press ESC for 5 seconds, and then corresponding keys is locked. Please press ESC for 5 seconds again for unlocking the keypad.

F2.14	**communication deployment**	**range: LED 1st bit: 0~5 LED 2nd bit: 0, 1, 2**	**03**

F2.14 make use of 1st bit, 2nd bit to set baud rate and data format of serial communication，thereinto LED 1st bit represents communication baud rate, set value as follows:

0: 1200BPS
1: 2400BPS
2: 4800BPS
3: 9600BPS
4: 19200BPS
5: 38400BPS

LED 2nd bit: represents data format，set value as follows:

0: 1－8－1 format, no checkout. Namely: 1 bit for starting, 8 bits for data, 1 bit for stop, no checkout.

1: 1－8－1 format，even checkout. Namely: 1 bit for starting, 8 bits for data, 1 bit for stop, even checkout.

2: 1－8－1 format，odd checkout. Namely: 1 bit for starting, 8 bits for data, 1 bit for stop, odd checkout.

F2.15	**Local address**	**range: 0－127，127 is broadcast address**	**1**

This function code is used to identify address of this inverter during serial port communication.127 is for main inverter during main and sub device communication between inverters.


note

127 is broadcast address，can only receive and execute broadcast command from upper machine but not respond to upper machine when 127 is set to broadcast address.

F2.16	**Communication overtime checkout time**	**range: 0.0－1000.0S**	**0.0S**

When serial port communication fails and its continuous time exceed set value of this function code，the inverter judge it as communication failure.
The inverter would not detect serial port communication signal, namely this function ineffective when set value is 0.

F2.17	**Local response delay time**	**range: 0－200ms**	**5ms**

Local response delay time represents the time within which the inverter serial port receive and execute command from upper device and then respond to upper device，this function is just used for setting this delay time.

F2.18	**Accelerating time 2**	**range: 0.1－6000.0**	**20.0**
F2.19	**Decelerating time 2**	**range: 0.1－6000.0**	**20.0**
F2.20	**Accelerating time 3**	**range: 0.1－6000.0**	**20.0**
F2.21	**Decelerating time 3**	**range: 0.1－6000.0**	**20.0**
F2.22	**Accelerating time 4**	**range: 0.1－6000.0**	**20.0**
F2.23	**Decelerating time 4**	**range: 0.1－6000.0**	**20.0**

F2.24	**Accelerating time 5**	**range: 0.1－6000.0**	**20.0**
F2.25	**Decelerating time 5**	**range: 0.1－6000.0**	**20.0**
F2.26	**Accelerating time 6**	**range: 0.1－6000.0**	**20.0**
F2.27	**Decelerating time 6**	**range: 0.1－6000.0**	**20.0**
F2.28	**Accelerating time 7**	**range: 0.1－6000.0**	**20.0**
F2.29	**Decelerating time 7**	**range: 0.1－6000.0**	**20.0**

Can define 3 kinds of accelerating decelerating time and can choose accelerating decelerating time 1～7 during inverter run process by different combination of control terminal，please see definition for function of accelerating decelerating time terminal in F5.00～F5.07.


note

Accelerating decelerating time 1 is defined in F0.08 and F0.09.

F2.30	**Multi-step freq. 1**	**range: low limit －high limit**	**5.00Hz**
F2.31	**Multi-step freq. 2**	**range: low limit －high limit**	**10.00Hz**
F2.32	**Multi-step freq. 3**	**range: low limit －high limit**	**20.00Hz**
F2.33	**Multi-step freq. 4**	**range: low limit －high limit**	**30.00Hz**
F2.34	**Multi-step freq. 5**	**range: low limit －high limit**	**40.00Hz**
F2.35	**Multi-step freq. 6**	**range: low limit －high limit**	**45.00Hz**
F2.36	**Multi-step freq. 7**	**range: low limit －high limit**	**50.00Hz**

These set frequency will be used in multi-step speed run mode and simple PLC run mode，please refer to multi-step speed run terminal function of F5.00～F5.07 and F4 group simple PLC function.

F2.37	**VF frequency value 0**	**0.00-F2.39**	**10.00Hz**
F2.38	**VF voltage value 0**	**0.00-F2.40**	**20.00%**
F2.39	**VF frequency value 1**	**F2.37-F2.41**	**20.00Hz**
F2.40	**VF voltage value 1**	**F2.38-F2.42**	**40.00%**
F2.41	**VF frequency value 2**	**F2.39-F2.43**	**25.00Hz**
F2.42	**VF voltage value 2**	**F2.40-F2.44**	**50.00%**
F2.43	**VF frequency value 3**	**F2.41-high limit frquency**	**40.00Hz**
F2.44	**VF voltage value 3**	**F2.42-100.0% (rated voltage)**	**80.00%**

See decription for F0.15.

F2.45	**Jumping freq. 1**	**range: 0.00－400.00Hz**	**0.00Hz**
F2.46	**Jumping freq. 1 range**	**range: 0.00－30.00Hz**	**0.00Hz**
F2.47	**reserved**		
F2.48	**reserved**		
F2.49	**reserved**		
F2.50	**reserved**		

F2.45～F2.46 function is set for keeping inverter output frequency away from resonance frequency of mechanical load.
Inverter set frequency can jump around some frequency point according to mode shown in Fig. 6-13, at most 3 jumping range can be defined.

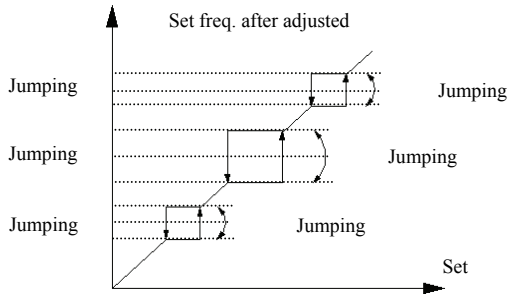


Fig.6-12 jumping frequency and range graph

F2.51	**Set run time**	**range: 0－65535h**	**0**
F2.52	**Run time accumulation**	**range: 0－65535h**	**0**

After run accumulative time reach set run time (F2.51)，the inverter will output indicator signal，please refer to F5.10～F5.13 function introduction. F2.52 denotes accumulative run time of the inverter from leaving factory to now.

F2.53	**RS485/232 frame format selection**	**range: 0－4**	**0**

0: a frame of 14 bytes or 18 bytes ASCII
1: a frame of 8 bytes or 10 bytes hex，primary response not changed
2: a frame of 8 bytes or 10 bytes hex，12 command has no response
3: a frame of 8 bytes or 10 bytes hex，14 command has no response
4: a frame of 8 bytes or 10 bytes hex，both 12 and 14 command have no response

6.4 Closed-loop run control parameter group: F3

Analog feedback control system:
Input pressure specified value through VCI port, send 4~20mA feedback value of pressure sensor to inverter CCI input port，make up of analog closed-loop control system by built-in PID adjustor，as shown in Fig.6-14.

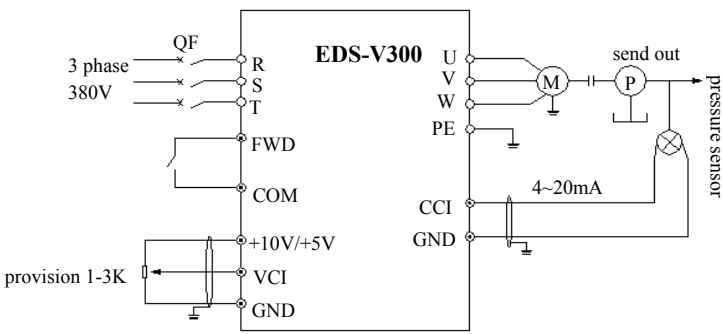


Fig.6-13 built-in PID analog feedback control system

note Specified value can also be provided with option by F0.00 function code.

EDS-V300 built-in PID adjustor make up of control system and its work principle chart is as follows:

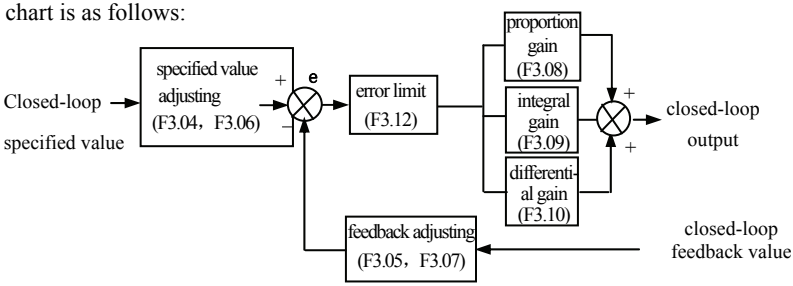


Fig.6-15 PID control principle diagram

In above diagram Kp: proportion gain；Ki: integral gain；Kd: differential gain

In above Fig.6-14 ,definition of closed-loop specified value, feedback value, error limit and proportion integral differential parameter is same as that of common PID adjustor parameter, see respectively (F3.01~F3.12) definition，relation of specified value and expected feedback value is as shown in Fig.6-15. Thereinto specified value take 10V as reference and feedback take 20mA as reference.

Specified value adjusting and feedback value adjusting in Fig.6-14 is for confirming corresponding relation and unitive dimension between specified value and feedback value.

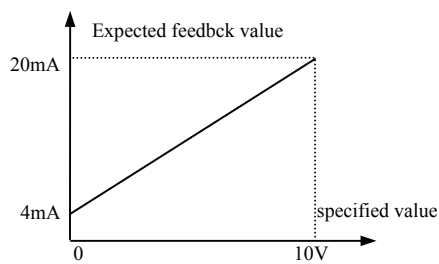


Fig.6-16 specified value and expected feedback value

When the system is determined，basic steps for setting closed-loop parameter are as follows:

(1) determine closed-loop provision and feedback channel(F3.01, F3.02)

(2) need to set relation between closed-loop provision and feedback for analog

closed-loop (F3.04~F3.07)

(3) set closed-loop presetting frequency function (F3.14, F3.15)

(4) set closed-loop proportion gain, integral gain, differential gain, sampling cycle, error limit (F3.08~F3.12)

F3.00	**Closed-loop run control selection**	**range: 0~1**	**0**

0: closed-loop run control ineffective

1: PID closed-loop run control effective

F3.01	**provision channel selection**	**range: 0~3**	**1**

0: digital provision.

1: VCI analog 0－10V voltage provision

2: CCI analog provision. Can choose 0~10V voltage or 4~20mA current provision

3: keypad analog potentiometer provision

F3.02	**Feedback channel selection**	**range: 0~6**	**1**

0: VCI analog input voltage 0－10V

1: CCI analog input

2: VCI+CCI

3: VCI-CCI

4: Min { VCI, CCI }

5: Max { VCI, CCI }

When CCI analog input is selected to be current input, it will be converted to voltage value in the inverter.

6: pulse feedback

F3.03	**Specified value digital**	**range: 0.00－9.999V**	**1.000**

When F3.00=1, figure given value F3.03 will be as specified value of closed-loop control system directly.

F3.04	**min. specified value**	**range: 0.0－max. specified value**	**000.0**
F3.05	**corresponding feedback value of min. specified value**	**range: 0.0－100.0(%)**	**000.0**
F3.06	**max. specified value value**	**range: min. specified value -100.0(%)**	**100.0(%)**
F3.07	**corresponding feedback value of max. specified value**	**range: 0.0%－100.0(%)**	**100.0(%)**

F3.04~F3.07 define relation curve of analog closed-loop provision and expected feedback. Their set value is percentage of provision and feedback actual value relative to reference (10V or 20mA)

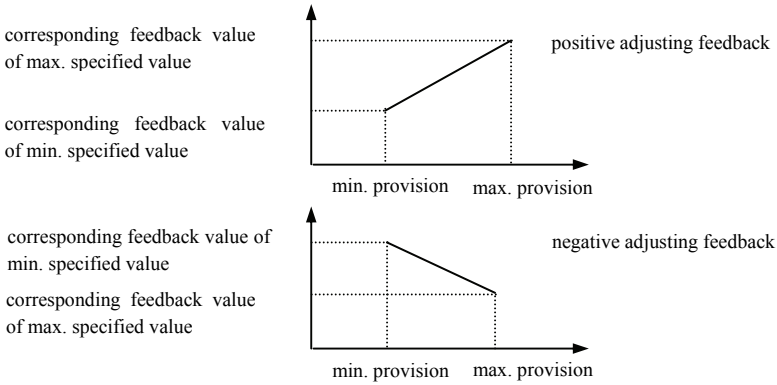


Fig.6-17 provision，feedback curve

F3.08	**Proportion gain Kp**	**range: 0.000－9.999**	**0.050**
F3.09	**Integral gain Ki**	**range: 0.000－9.999**	**0.050S**
F3.10	**Differential gain Kd**	**range: 0.000－9.999**	**0.000**
F3.11	**Sampling cycle T**	**range: 0.01－1.00S**	**0.10S**

The more big Kp proportion gain is, the more quick the response is，but overbig is prone to bringing surge.

Only applying proportion gain Kp adjustment can't eliminate offset completely，can apply integral gain Ki and differential gain to make up of PID control in order to eliminate residual offset. The bigger Ki is, the more quickly the system responds to changing offset, but overbig is prone to bringing surge.

Sampling cycle T is sampling cycle for feedback value，during each sampling cycle PID adjustor calculate for one time，the longer the sampling cycle is , the slower the system responds.

F3.12	**Offset limit**	**range: 0.0－20.0(%)**	**2.0(%)**

For Max. offset of closed-loop specified value，as shown in Fig.6-17，PID adjustor stops adjusting when feedback value is within this range. To utilize this function reasonably redound to harmonizing the conflict between system output precision and stabilization.

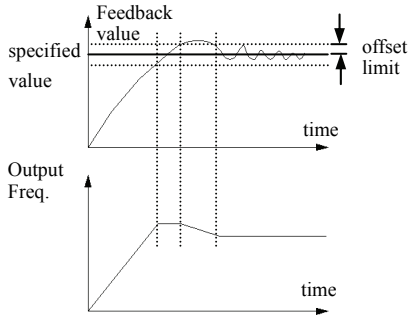


Fig.6-18 offset limit

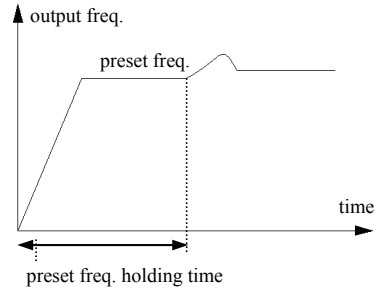


Fig.6-19 closed-loop preset freq.

F3.13	**integral separation PID adjusting threshold**	**range: 0.0－100.0%**	**100.0 （%）**

PID integral separation，integral don't react when specified value and feedback value are bigger than this limit，only when specified value and feedback value are smaller than or equal to this limit，integral react. Can adjust system response speed by adjusting this parameter.

F3.14	**closed-loop preset frequency**	**range: 0-high limit freq.**	**00.00**
F3.15	**closed-loop preset frequency holding time**	**range: 0.0-6000S**	**000.0**

This function can make closed-loop adjusting enter into stable phase quickly.

After closed-loop run starts, the inverter first accelerates to preset frequency F3.14 in terms of accelerating time，and after running at this frequency for a period of time F3.15, it runs according to closed-loop characteristic. As shown in Fig.6-19.

note Set preset freq. and holding time to "0' if closed-loop preset freq. function is not needed.

F3.16	**Reserved**		
F3.17	**Reserved**		

F3.18	**Reserved**		
F3.19	**Reserved**		
F3.20	**Reserved**		
F3.21	**Reserved**		

F3.22	**Reserved**		
F3.23	**Reserved**		

F3.24	**Speed display coefficient**	**range: 0.01－4.00S**	**1.00**

Speed sisplay coefficient Show that speed ratio relationship for existing gearing devise between the motor shaft and its load .when set this parameter factory default(1.00)Monitoring parameter C-05 display speed of motor shaft .If dead in speed ratio between the motor shaft and the load shaft because of transmission device ,the parameter displyed by Monitoring parameter C-05 show running speed of the load (such as machine tool shaft and so on)

F3.25	**Reserved**		

F3.26	**Water supply supervision Para. display**	**range: 0~1**	**0**

0: C-11, C-12 display VCI,CCI voltage.

1: C-11, C-12 display PID specified pressure and feedback pressure.

F3.27	**Closed-loop adjusting characteristic**	**range: 0, 1**	**0**

0: Forward function. motor speed increases as specified value increases.

1: Reverse function. motor speed decreases as specified value increases.

F3.28	**LED initial supervision Para. selection**	**range: 0~14**	**1**

This parameter defines initial supervision parameter selection during running or stop. For example F3.28=3, LED displays output voltage initially, please press SHIFT key if you want to see about other supervision parameter.

0: set frequency:Standby mode display set the frequency, output frequency is displayed after running.

1: output frequency:Display output frequency not only standby but also running .

2: output current
3: output voltage
4: DC bus bar voltage
5: motor speed
6: heat sink temperature
7: run time
8: accumulative run time
9: input terminal status
10: output terminal status
11: analog input VCI/PID provision

12: analog input CCI/PID feedback
13: analog input YCI
14: exterior pulse input

F3.29	**Reserved**		

F3.30	**Failure relay TA，TB，TC function selection**	**range: 0~24**	**15**

Same as detailed description for F5.10.

F3.31	**Reserved**		

6.5 Simple PLC run function parameter group: F4

The user can set by himself the output frequency direction and running time of the inverter during a running cycle by simple PLC function according to spot craft demand, as shown in Fig.6-20.

EDS-V300 serial inverter simple PLC run function provide 7 kinds of multi-step speed run mode，see below an example of 7 step speed. In Fig.6-20，a_1~a_5, d_1~d_5 is accelerating or decelerating time of relative step，set by accelerating decelerating time parameter F0.08, F0.09 and F2.18~F2.29 in total 7 kinds of parameter，f_1~f_7, T_1~T_7 indicating set frequency and run time set by function code F4.01~F4.14.

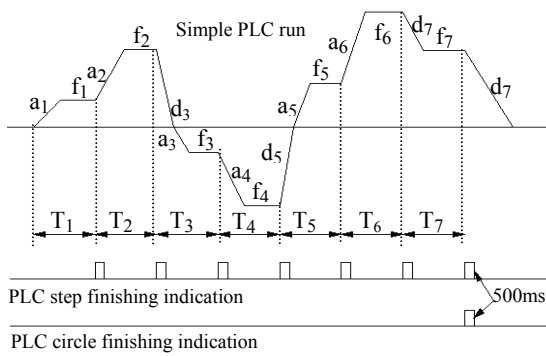


Fig.6-20 simple PLC run

EDEDS-V300 series inverter simple PLC run function can provide 7 kinds of multi-speed operation mode, takethe fowling 7speed for example Figure 6 -21 , a1~ a5, d1~d5Is the speed up time and the deceleration time of the stage, they are

setted by the acceleration time parameters F 0.08,F0.09and F2.18~F2.29, a total of seven kinds of parameters,the run frequency and run time of f1~ f7, T1~ T7 are setted by function code F4.01~f4.14.

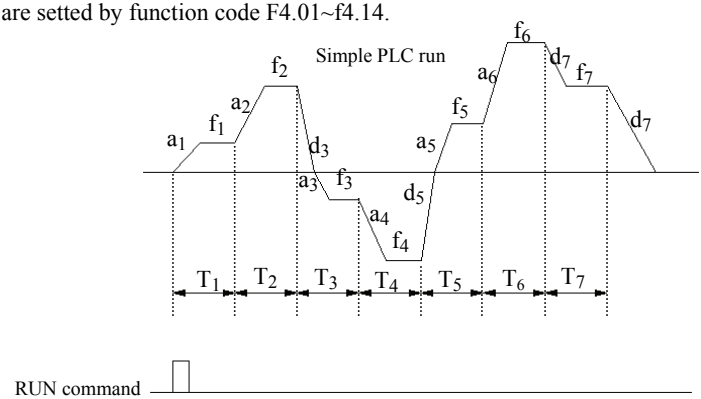


Fig.6-21 stop after PLC single circle

PLC step finishing and circle finishing indication can be realized by outputting 500mS pulse indicator signal through open circuit collector terminal OC1~OC4，detailed function defined by F5.10~F5.13.

F4.00	Simple PLC run setting	range: LED 1st bit: 0~3 LED 2nd bit: 0, 1 LED 3rd bit :0, 1	000

This function code make use of its 1st bit, 2nd bit, 3rd bit to set PLC run mode, PLC rerun mode after interruption，set run time unit，detail as follows:

LED 1st:

0: no action. PLC run mode ineffective.

1: stop after single circle. As shown in Fig.6-21，the inverter stops automatically after finishing a circle，can only start when another run command is available.

2: keep final value after single circle. As shown in Fig.6-22，the inverter keep running according to frequency, direction of final step after finishing a circle，the inverter won't stop according to set decelerating time until the stop command is available.

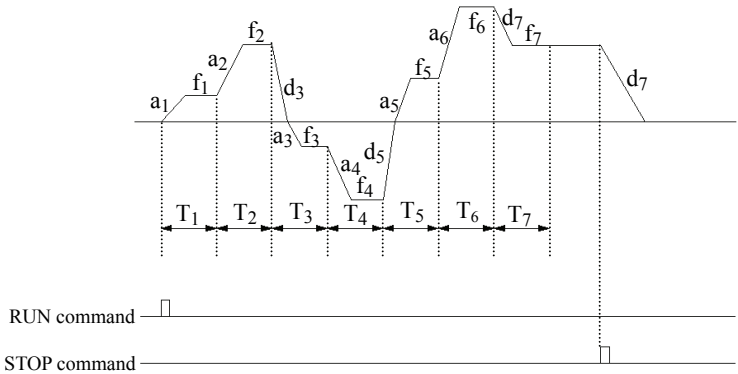


Fig.6-22 holding mode after PLC single circle

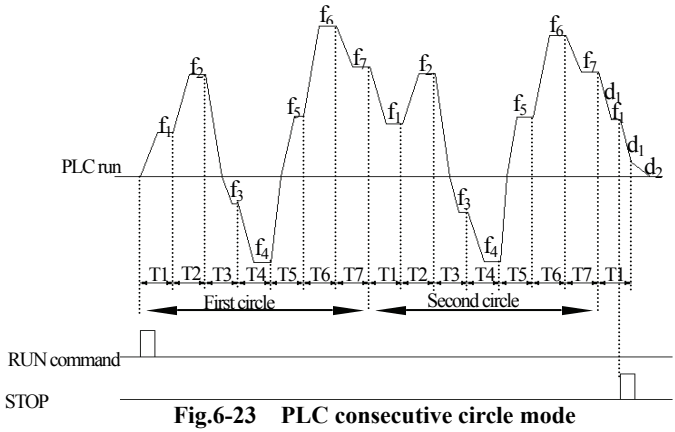


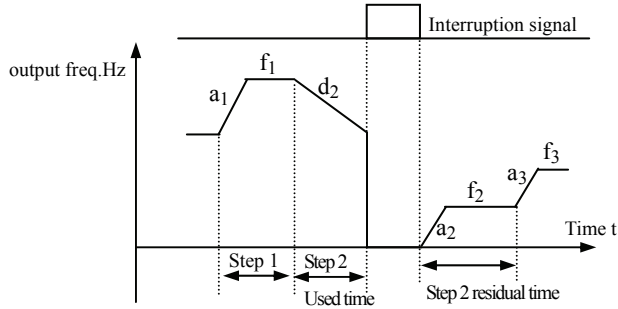
Fig.6-23 PLC consecutive circle mode

3: consecutive circle. As shown in Fig.6-23，the inverter start next circle automatically after finishing a circle，until there is stop command.

LED 2nd bit:

0: start from first step. Stop during running caused by stop command, failure or power off，after restarting the inverter will run from first step.

1: continue to run from step frequency of interruption moment. When stop during running caused by stop command or failure，the inverter will record current step used time automatically and enter into this step automatically after restarting，continue to run for residual time according to defined frequency of this step, as shown in Fig.6-24. The inverter will rerun from first step after restarting if power off.



a_1: step 1 accelerating time
a_2: step 2 accelerating time
a_3: step 3 accelerating time
d_2: step 2 decelerating time
f_1: step 1 frequency
f_2: step 2 frequency
f_3: step 3 frequency

Fig.6-24 PLC starting mode 1

LED 3rd bit : PLC run time unit

0: second; 1: minute

This unit is only effective to PLC run step time，for accelerating decelerating time of PLC run period, their unit selection is determined by F0.07.

note

(1) If run time of PLC segment is set to 0，this segment is ineffective.

(2) can make PLC process a pause, ineffective, work etc. through terminal，for detail please refer to terminal correlative function parameter group F5.

F4.01	**Step 1 setting**	**range: 000－621**	**000**
F4.02	**Step 1 runtime**	**range: 0－6000.0**	**10**
F4.03	**Step 2 setting**	**range: 000－621**	**000**
F4.04	**Step 2 runtime**	**range: 0－6000.0**	**10**
F4.05	**Step 3 setting**	**range: 000－621**	**000**
F4.06	**Step 3 runtime**	**range: 0－6000.0**	**10**
F4.07	**Step 4 setting**	**range: 000－621**	**000**
F4.08	**Step 4 runtime**	**range: 0－6000.0**	**10**
F4.09	**Step 5 setting**	**range: 000－621**	**000**
F4.10	**Step 5 runtime**	**range: 0－6000.0**	**10**
F4.11	**Step 6 setting**	**range: 000－621**	**000**
F4.12	**Step 6 runtime**	**range: 0－6000.0**	**10**
F4.13	**Step 7 setting**	**range: 000－621**	**000**
F4.14	**Step 7 runtime**	**range: 0－6000.0**	**10**

F4.01~F4.14 utilize LED 1st bit, 2nd bit, 3rd bit to separately define frequency setting，direction and accelerating decelerating time of PLC Run, see following for detail:

LED1st bit: frequency setting

0: multi-step frequency i i=1~7 is defined by F2.30~F2.44.

1: frequency is determined by function code F0.00

LED 2nd bit: run direction selection

0: forward run

1: reverse run

2: determined by run command (FWD,REV)

LED3rd bit: accelerating decelerating time selection

0: accelerating decelerating time 1

1: accelerating decelerating time 2

2: accelerating decelerating time 3

3: accelerating decelerating time 4

4: accelerating decelerating time 5

5: accelerating decelerating time 6

6: accelerating decelerating time 7

6.6 Terminal correlative function parameter group: F5

F5.00	**Input terminal X1 function selection**	**range: 0~42**	**0**
F5.01	**Input terminal X2 function selection**	**range: 0~42**	**0**
F5.02	**Input terminal X3 function selection**	**range: 0~42**	**0**
F5.03	**Input terminal X4 function selection**	**range: 0~42**	**0**
F5.04	**Input terminal X5 function selection**	**range: 0~42**	**0**
F5.05	**Input terminal X6 function selection**	**range: 0~42**	**0**
F5.06	**Input terminal X7 function selection**	**range: 0~42**	**0**
F5.07	**Input terminal X8 function selection**	**range: 0~42**	**0**

Multi-function input terminal X1~X8 provides 43 kinds of selection mode for the user，can choose based on spot requirement. For parameter function table please see Table 6-2.

Table 6-2 multifunction input function selection table

Item	Corresponding function	Item	Corresponding function
0	Leave control terminal unused	1	Multi-step speed control terminal 1
2	Multi-step speed control terminal 2	3	Multi-step speed control terminal 3
4	Multi-step speed control terminal 4	5	External forward run jog control
6	External reverse run jog control	7	Accel/Decel time selecting terminal 1
8	Accel/Decel time selecting terminal 2	9	Accel/Decel time selecting terminal 3
10	External device failure input	11	External restoration input
12	Free stop input	13	External stop command
14	stop DC braking input command DB	15	Inverter run prohibition
16	Frequency increasing command(UP)	17	frequency descending command(DOWN)
18	Accel/Decel prohibited command	19	Three-wire run control
20	Closed-loop ineffective	21	PLC ineffective
22	Simple PLC pause command	23	PLC stop status restoration (reset variable of PLC interruption moment, make it restart from first segment)
24	Frequency provision channel selection 1	25	Frequency provision channel selection 2
26	Frequency provision channel selection 3	27	Frequency switched to CCI
28	Command switched to terminal	29	Run command channel selection 1
30	Run command channel selection 2	31	Run command channel selection 3
32	Swing frequency running	33	External interruption input
34	interior counter clearing end	35	interior counter triggering end
36	Interior timer clearing end	37	interior timer triggering end
38	Pulse frequency input(only effective for X7,X8)	39	Reserved
40	Reserved	41	Reserved
42	Reserved		

Now explain listed function in Table 6-2 as follows:

1~4: Multi-step speed control terminal. Can set 15 step speed run frequency by choosing ON/OFF combination of these function terminal.

Table 6-3 multi-step speed run selection table

K_4	K_3	K_2	K_1	Frequency setting
OFF	OFF	OFF	OFF	Common run frequency

OFF	OFF	OFF	ON	Multi-step frequency 1
OFF	OFF	ON	OFF	Multi-step frequency 2
OFF	OFF	ON	ON	Multi-step frequency 3
OFF	ON	OFF	OFF	Multi-step frequency 4
OFF	ON	OFF	ON	Multi-step frequency 5
OFF	ON	ON	OFF	Multi-step frequency 6
OFF	ON	ON	ON	Multi-step frequency 7

Above multi-step frequency can be used in multi-step speed run and simple PLC run, please see below an example of multi-step speed run:

We now define control terminal X1, X2, X3, separately as follows:

After set F5.00=1, F5.01=2, F5.03=3, X1, X2, X3, are used for realizing multi-step run，as shown in Fig.6-25

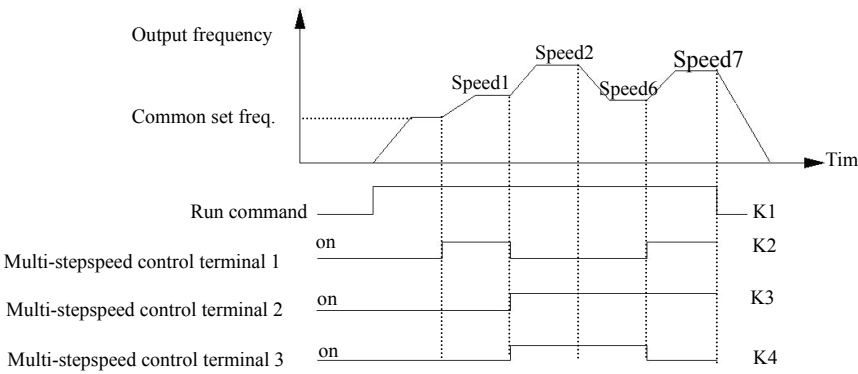


Fig.6-25 multi-step run

In fig.6-26 see an example of terminal run command channel，can make forward, reverse run control by K5, K6. In Fig.6-25, by different logic combination of K2, K3, K4，the inverter can run according to common set frequency or 1~7multi-step frequency multi-speed operation based on above table.

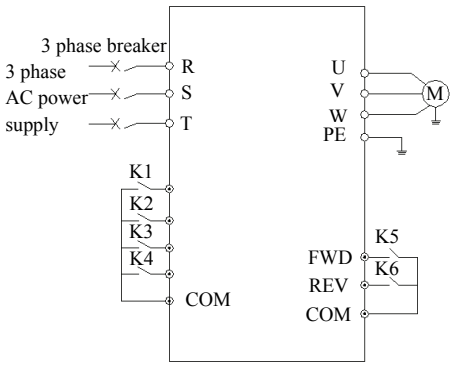


Fig.6-26 multi-step speed run

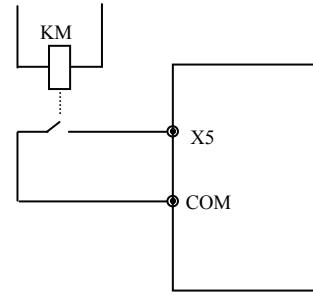


Fig.6-27exterior device failure always-open input

5~6: external jog run control input JOGF/JOGR. When run commandchannel is set to terminal run command channel F0.02=1，JOGF is jog forwardrun，JOGR is jog reverse run，jog operation frequency, jog accelerating decelerating time is defined in F2.06~F2.08 (remark: jog run commandchannel is determined by F0.02)

7~9: Accel&Decel time terminal selection

Table 6-4 Accel&Decel time terminal selection logic mode

Terminal 2	Terminal 2	Terminal 1	Accel/Decel time selection
OFF	OFF	OFF	Accel time 1/ Decel time 1
OFF	OFF	ON	Accel time 2/ Decel time 2
OFF	ON	OFF	Accel time 3/ Decel time 3
OFF	ON	ON	Accel time 4/ Decel time 4
ON	OFF	OFF	Accel time 5/ Decel time 5
ON	OFF	ON	Accel time 6/ Decel time 6
ON	ON	OFF	Accel time 7/ Decel time 7

Can realize selection for Accel&Decel time1~7 by ON/OFF combination of Accel&Decel time terminal.

10: external equipment fault input. Can input fault signal of external

equipment by this terminal to be convenient for the inverter to monitor fault of external equipment. The inverter displays “E0.14”, namely external equipment fault alarm after receiving the external equipment fault signal.

11: exterior restoration input. After the fault alarm takes place in the inverter, can restore the inverter through this terminal. Its function is same as function of RESET key on the operation panel.

12: free stop input. This function is same as free stop during running defined in F1.05，but it's realized by control terminal to be convenient for long-distance control.

13: exterior stop command. This command is effective to all run command channel，when this function is effective the inverter stops running in mode set by F1.05.

14: DC injection braking input command DB during stop. Implement DC injection braking to the motor during stop by control terminal，in order to realize urgent parking and accurate orientation of the motor. Braking initial frequency, braking time are defined in F1.06, F1.07.

15: inverter run forbiddance. The inverter during running stops freely

when this terminal is effective and forbidden to start in waiting status. Mainly applied to occasion needing safe linkage.

16~17: frequency increasing command UP/descending command DOWN. Realize frequency increasing or descending by control terminal, which substitute for keypad to realize long-distance control. Effective during common run if F0.00=2.Increasing descending speed is set by F5.09.

18: Accel&Decel speed forbidden command. Let the motor not effected by any foreign signal(except stop command)，keep running at current frequency.

note

Ineffective during normal decelerating stop.

19: three-wire run control. Please refer to function description of F5.08 run mode (three-wire run mode).

20: closed-loop ineffective. Realize flexible switch to lower level runmode under closed-loop run status.

note

(1) can switch between closed-loop and lower level run mode only during closed-loop run(F3.00=1).

(2) start stop control, direction and Accel&Decel time are subject to setting of corresponding run mode when it's switched to lower level run mode.

21: PLC ineffective. Realize flexible switch to lower level run mode underPLC run status.

note

(1) can switch between PLC and lower level run mode only during PLC run(F4.00≠0).

(2) start stop control, direction and Accel&Decel time are subject to setting of corresponding run mode when it's switched to lower level run mode.

22: simple PLC pause command. Implement pause control to PLC processduring running，run at zero frequency when this terminal is effective，not time for PLC run；after ineffective implement automatic speed tracking start and continue PLC run. For application method please refer to function description of F4.00~F4.14.

23: PLC stop status restoration. Under stop status of PLC run mode, willclear PLC run step, runtime, run frequency etc. recorded when PLC run stops if this terminal is effective，please see F4 group function description.

24~26: terminal frequency provision channel selection. Through ON/OFF combination of frequency provision channel selection terminal 24, 25, 26，can realize frequency provision channel switch shown in Table 6-5. For relation of terminal switch and function code F0.00 setting, that is, latter effective.

Table 6-5 terminal frequency provision channel selection logic mode

frequency provision channel selection end 3	frequency provision channel selection end 2	frequency provision channel selection end 1	frequency provision channel selection
OFF	OFF	OFF	hold freq. setting
OFF	OFF	ON	potentiometer provision
OFF	ON	OFF	keypad number provision
OFF	ON	ON	terminal UP/DOWN adjusting provision
ON	OFF	OFF	serial port provision
ON	OFF	ON	VCI
ON	ON	OFF	CCI
ON	ON	ON	end PULSE provision

27: switch frequency to CCI. Frequency provision channel is switched to CCI provision compulsorily when this function terminal is effective, frequency provision channel come back to previous status when this function terminal is ineffective.

28: command switched to terminal. Run command channel is switched to terminal run command channel compulsorily when this function terminal is effective.

29~31: terminal select run command channel

Table 6-6 run command channel logic mode

Run command channel selection terminal 3	Run command channel selection terminal 2	Run command channel selection terminal 1	Run command channel
OFF	OFF	OFF	hold run command channel
OFF	OFF	ON	keypad run command channel
OFF	ON	OFF	end run command channel (keypad STOP command ineffective)
OFF	ON	ON	end run command channel (keypad STOP command effective)
ON	OFF	OFF	serial port run command channel(keypad STOP command ineffective)
ON	OFF	ON	serial port run command channel(keypad STOP command effective)

Can realize control command selection shown in Table 6-6 by ON/OFF combination of run command channel selection terminal，For relation of terminal switch and function code F0.00 setting, that is, latter effective.

32: swing frequency jump-in. When swing frequency start mode is manual jump-in，swing frequency function effective if this terminal effective，see F6 function parameter description.

33: exterior interruption input.The inverter close off output and run at zerofrequency during running upon receiving exterior interruption signal. The inverter implement automatic speed tracking start-up to resume running once external interruption signal is relieved.

34: interior counter clearing end. To clear built-in counter in the inverter with cooperation of counter triggering signal.

35: interior counter triggering end. Counting pulse input port of built-in counter，pulse max. frequency: 200Hz，see function code F5.24, F5.25.

36: interior timer clearing end. To clear built-in timer in the inverter with cooperation of timer triggering signal.

37: interior timer triggering end. Please see function description for parameter F5.27.

38: pulse frequency input(only effective to X7,X8). Only effective formultifunction input terminal X7, X8，this function terminal receive pulse signal as frequency provision, for relation between inputted signal pulse frequency and set frequency in detail, please refer to F7 group parameter.

39: reserved
40: reserved
41: reserved
42: reserved

F5.08	FWD/REV run mode selection	range: 0－3	0

This parameter defines 4 kinds of exterior terminal control mode for inverter running.

0: 2-wire control mode 1

K2	K1	run command
0	0	stop
1	0	reverse run
0	1	forward run
1	1	stop

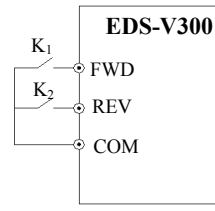


Fig.6-28 2-wire run mode 1

1: 2-wire control mode 2

K2	K1	run command
0	0	
1	0	stop
0	1	forward run
1	1	reverse run

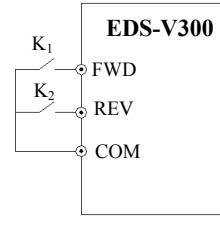


Fig.6-29 2-wire run mode 2

2: 3-wire control mode 1

thereinto:

SB1: stop button

SB2: forward run button

SB3: reverse run button

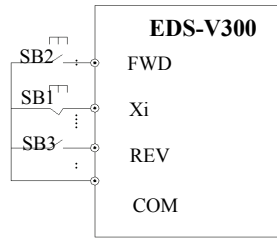


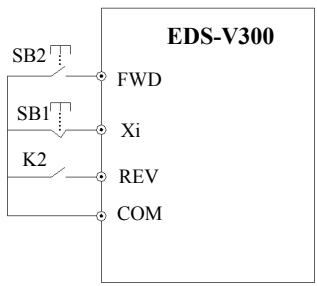
Fig.6-30 3-wire run mode 1

Xi is multifunction input terminal of X1~X8， here should define its corresponding terminal function as No. 19 “3-wire run control” function.

3: 3-wire control mode 2

SB1: stop button

SB2: run button



K2	run direction selection
0	Forward run
1	Reverse run

Fig.6-31 3-wire run mode 2

Xi is multifunction input terminal X1~X8, here should define its corresponding terminal function as No. 19 “3-wire run control” function.

The inverter restores after failure and start at once if run command channel selecting terminal and terminal FWD/REV is effective during warning alarm stop.

F5.09	**UP/DOWN speed**	**range: 0.01－99.99Hz/S**	**1.00 Hz/S**

This function code defines varying rate of the set frequency when it’s modified by UP/DOWN terminal.

F5.10	**Open collector output terminal OC1 output setting**	**range: 0~24**	**0**
F5.11	**Open collector output terminal OC2 output setting**	**range: 0~24**	**0**
F5.12	**Open collector output terminal OC3 output setting**	**range: 0~24**	**0**
F5.13	**Open collector output terminal OC4 output setting**	**range: 0~24**	**0**

OC1~OC4 open collector output terminal，Table 6-7 shows option of above 4 function parameter，choosing same output terminal function repeatedly is allowed.

Table 6-7 output terminal function selection table

Item	Corresponding function	Item	corresponding function
0	Inverter running signal (RUN)	1	Frequency arriving signal (FAR)
2	Frequency level detecting signal (FDT1)	3	reserved
4	Overload warning signal(OL)	5	Output Freq. reach high limit(FHL)
6	Output Freq. reach low limit(FLL)	7	Inverter stops for under voltage blockage (LU)
8	Stop for exterior failure(EXT)	9	Inverter zero speed running
10	In PLC run process	11	Simple PLC segment run finished
12	PLC finish one cycle run	13	reserved
14	Inverter is ready for run(RDY)	15	Inverter failure
16	Swing Freq. high&low limit restriction	17	Interior counter final value arrive
18	Interior counter specified value arrive	19	Set runtime arrive
20	Interior timer timing arrive	21	OC1- variable Freq. for the 1st pump OC2- power source for the 1st pump OC3- variable Freq. for the 2nd pump OC4- power source for the 2nd pump
22	reserved	23	reserved
24	reserved		

Now introduce function listed in Table 6-7 as follows:

0: inverter during running(RUN). The inverter is in run status，output indicator signal.

1: frequency arriving signal(FAR). Refer to function description of F5.14.

2: Frequency level detecting signal(FDT1). Refer to function description of F5.15~F5.16.

3: reserved

4: overload warning signal(OL). Inverter output current exceed F9.05 overload detect level and time exceed F9.06 overload detect time，output indicator signal.

5: output frequency reach high limit(FHL). When set frequency≥high limit frequency and run frequency reach high limit frequency，output indicator signal.

6: output frequency reach low limit(FLL). When set frequency≤low limit frequency and run frequency reach low limit frequency，output indicator signal.

7: Inverter stops for under voltage blockage(LU). When the inverter is running, LED displays“P.OFF”and output indicator signal if DC bus-bar voltage is lower than limitative level.

8: stop for exterior failure(EXT). When the inverter give the alarm (E014) and stops for exterior failure, output indicator signal.

9: inverter zero speed running. When the inverter output zero frequency but in run status, output indicator signal.

10: In PLC run process

11: Simple PLC segment run finished. After simple PLC current segment run is finished，output indicator signal(single pulse signal，width 500ms).

12: PLC finish one cycle run

13: reserved

14: Inverter is ready for run(RDY). If this signal is effective, shows that bus-bar voltage is normal and run prohibition terminal is ineffective, the inverter can receive start-up command.

15: Inverter fault. If failure takes place when the inverter is running, the inverter output indicator signal.

16: Swing freq. high&low limit restriction. After choosing swing frequency function, if frequency fluctuant range based on center frequency of swing frequency is above high limit frequency F0.10 or under low limit frequency F0.11, the inverter will output indicator signal, as shown in Fig. 6-32.

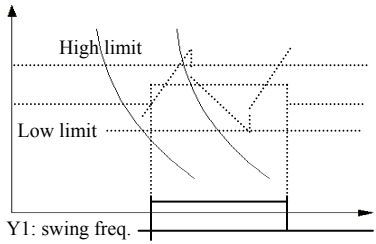


Fig.6-32 swing freq. range restriction

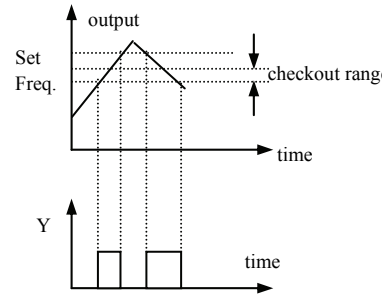


Fig.6-33 freq. arriving signal output

17: Interior counter final value arrive

18: Interior counter specified value arrive

17~18 please refer to function description of F5.25~F5.26.

19: Set runtime arrive. When accumulative runtime of the inverter (F2.52) reach set runtime(F2.51)，output indicator signal.

20: Interior timer timing arrive. Refer to function description for F5.27.

21: OC1- variable Freq. for the 1st pump

OC2- power source for the 1st pump

OC3- variable Freq. for the 2nd pump

OC4- power source for the 2nd pump

22: Reserved

23: Reserved

24: Reserved

F5.14	**Freq. arriving(FAR)detect range**	**range: 0.00－50.00Hz**	**5.00Hz**

This parameter is supplementary definition to No. 1 function in Table 6-7.As shown in Fig.6-34， when output frequency of the inverter is within high&lowdetect range of set frequency，output pulse signal.

F5.15	**FDT1(freq. level) electric level**	**range: 0.00－high limit frequency**	**10.00Hz**
F5.16	**FDT1 lag**	**range: 0.00－50.00Hz**	**1.00Hz**

F5.15~F5.16 is supplementary definition to No.2 function in Table 6-7, introduce as follows:When output frequency exceed the set frequency(FDT1 electric level)，output indicator signal，till output frequency descend to be some frequency(FDT1 electric level-FDT1 lag) lower than FDT1 electric level，as shown in Fig.6-33.

F5.17	Analog output(AO1)selection	range: 0－9	0

0: output frequency(0－high limit frequency)

1: set frequency(0－high limit frequency)

2: output current(0－2×rated current)

3: output voltage(0－1.2×load motor rated voltage)

4: bus-bar voltage(0－800V)

5: PID provision (0.00-10.00V)

6: PID feedback (0.00-10.00V)

7: reserved

8: reserved

9: reserved

F5.18	Analog output(AO1)gain	range: 0.00－2.00	1.00
F5.19	Analog output(AO1) offset	range: 0.00－10.00V	0.00

For AO1 and AO2 analog output, the user can modify display measuring range or emend meter head error by adjusting output gain if necessary.

F5.20	Analog output(AO2)selection	range: 0－9	0

Same as F5.17 function parameter description.

F5.21	Analog output(AO2)gain	range: 0.10－2.00	1.00
F5.22	Analog output(AO2) offset	range: 0.00－10.00V	0.00

Same as F5.18 and F5.19 function parameter description.

note **This function makes real-time effect to analog output when it's being**

F5.23	DO terminal output function selection	range: 0~9	0

Same as F5.17 function parameter description.

F5.24	DO max. pulse output freq.	range: 0.1－20.0(max. 20KHz)	10.00

DO port max. output pulse frequency corresponds to maximum value optioned by F5.23，for example 0: output frequency，then max. Output pulse frequency corresponds to high limit frequency.

F5.25	Set interior count number arriving provision	range: 0--9999	0
F5.26	Specified interior count number arriving provision	range: 0--9999	0

F5.25, F5.26 is supplementary definition to No. 17, 18 function in Table 6-7.

Set count number provision，shows that when some number of pulse are inputted to Xi(count triggering signal input function terminal), OCi (open collector Output terminal) output a indicator signal.

As shown in Fig.6-34，OC1 output an indicator signal when the 8th pulse is inputted to Xi. Here F5.25=8.

Specified count number provision，shows that when some number of pulse are inputted to Xi, OCi output a indicator signal，till set count number is reached.

As shown in Fig.6-34，OC2 start to output an indicator signal when the 5th pulse is inputted to Xi. Until set count number 8 is reached. Here F5.26=5. Specified count number is ineffective when it is bigger than set count number.

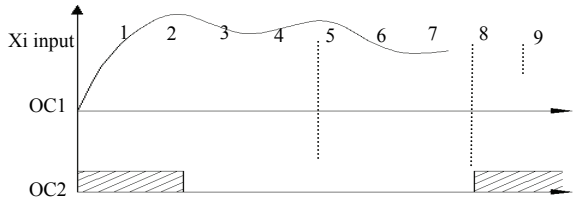


Fig.6-34 Set count number and specified count number provision

F5.27	**Interior timer timing setting**	**range: 0.1－6000.0s**	**60.0**

This parameter is used to set timing time of interior timer of the inverter.The timer is activated by exterior triggering end(triggering end selected by F5.00~F5.07), the timer begins timing upon receiving exterior triggering signal, after it's up to timing time one effective pulse signal of 0.5s will be outputted from relative OC end.

6.7 Vector control parameter group: F6

F6.00	**Reserved**		

F6.01	**Oscillation suppression lower limiting frequency**	**Range：** 0.00－2.00	0.50Hz
F6.02	**Oscillation suppression upper limiting frequency**	**Range：** 8.50－35.00	12.50Hz
F6.03	**Oscillation suppression Compensation gain**	**Range：** 100.0－130.0(%)	100.0(%)

note

1. In many industrial applications, current oscillations easily appear when the motor no-load operation in certain frequency bands, with the power to increase this phenomenon is more obvious. This could lead to instability in the motor running, and converter's serious over-current. When the operating frequency increases, the current oscillation has eased, F6.01 and F6.02 can be set corresponding upper and lower limit frequency ,which is the current oscillation range.
2. When F6.03 is set 100% of the compensation amount to zero, be careful that compensation amount should not be too large while setting, or it will cause over-current fault.
3. The amount of compensation may be different for different power of motor , please under the guidance of the engineer.

F6.04	**Torque limit value**	**Range：** 50.0－200.0%	150.0%

Torque limit is used to limit torque current output the speed controller. Torque limit value 50.0-200.0% is the percentage of inverter rated current; Torque limit = 100%, that is, the torque current limit set to the rated current.

Torque limit of factory default is 150% factory, try not to set in the application of the torque limit value too large and long running at 150% of rated current , or it would shorten the drive's life of internal IGBT due to thermal fatigue, but also affect the life of the motor.

F6.05	**Speed loop gain proportion**	**Range：** 0.000－6.000	0.700
F6.06	**Speed loop integral time constant**	**Range：** 0.000－9.999	0.360

F6.05, F6.06 can set the speed regulator proportional gain and integration time, thus changing the speed of response of vector control.

note

PI speed loop parameters is closely related to electric condition, it requires reasonable adjustment on the basis of factory default for different application during operating. Thus to meet to meet different requirements, to achieve the best results.

F6.07	**reserved**		

6.8 Frequency provision function parameter group: F7

F7.00	**VCI minimum provision**	**range: 0.00－F7.02**	**0.0V**
F7.01	**Corresponding freq. to VCI minimum provision**	**range: 0.00－high limit frequency**	**0.00Hz**
F7.02	**VCI max. provision**	**range: 0.00－10.00V**	**9.9V**
F7.03	**Corresponding freq. to VCI maximum provision**	**range: 0.00－high limit frequency**	**50.00Hz**
F7.04	**CCI minimum provision**	**range: 0.00－F7.06**	**0.00V**
F7.05	**Corresponding freq. to CCI minimum provision**	**range: 0.00－high limit frequency**	**0.00Hz**
F7.06	**CCI max. provision**	**range: 0.00－10.00V**	**9.9V**
F7.07	**Corresponding freq. to CCI max. provision**	**range: 0.00－high limit frequency**	**50.00Hz**
F7.08	**YCI minimum provision**	**range: 0.00－F7.10**	**0.00V**
F7.09	**Corresponding freq. to YCI minimum provision**	**range: 0.00－high limit frequency(REV)**	**0.00Hz**
F7.10	**YCI max. provision**	**range: 0.00－10.00V/5V**	**9.9V**
F7.11	**Corresponding freq. to YCI max. provision**	**range: 0.00－high limit frequency(FWD)**	**50.00Hz**
F7.12	**YCI dead band range setting**	**range: 0.00V－2.00V**	**0.10V**

The inverter can decide FWD run or REV run according to YCI input when YCI is selected to be frequency provision(i.e. F0.00=6). YCI frequency defined in F2.09 may be positive or negative when YCI isn't selected to be frequency provision.

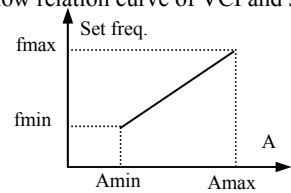
Shown as the figure: 0—dead band the frequency is negative.
5V−dead band—5V+dead band YCI set frequency is 0
5V+ dead band—10V the frequency is positive

F7.13	**PULSE max. pulse input**	**range: 0.01－20.0K**	**10.0K**
F7.14	**PULSE minimum provision**	**range: 0.0－F7.16**	**0.0K**
F7.15	**Corresponding freq.To PULSE min. provision**	**range: 0.00－high limit frequency**	**0.00Hz**

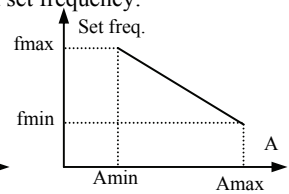
F7.16	**PULSE max. provision**	**range: F7.14(PULSE min. provision)－F7.13(max. input pulse)**	**10.0K**
F7.17	**Corresponding freq. to PULSE max. provision**	**range: 0.00－high limit frequency**	**50.00Hz**

F2.00 sets the analog channel filtering time constant，to filter input signal， the more long filtering time is, the more great anti-jamming ability is, but response speed descend; the more short filtering time is, the more fast the inverter respond, but anti-jamming ability is weakened.

See below relation curve of VCI and set frequency:



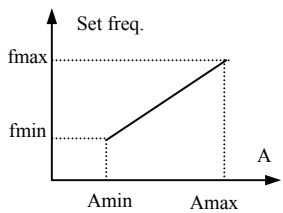
(1)plus characteristic



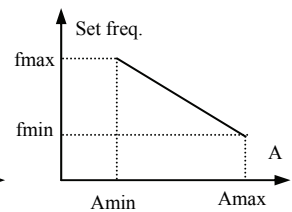
(2)minus characteristic

A:VCI provision
Amin:min. provision　　fmin:corresponding freq. of min. provision
Amax:max. provision　　fmax:corresponding freq. of max. provision

See below relation curve of CCI and set frequency:



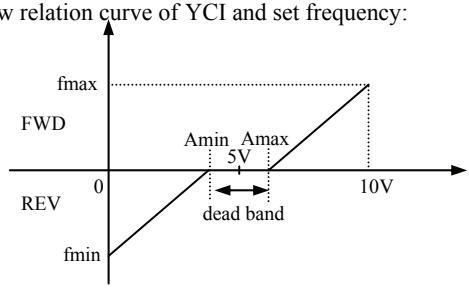
(1) plus characteristic



(2) minus characteristic

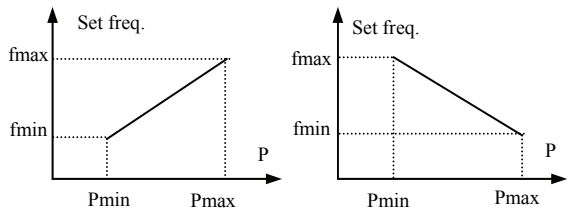
A:CCI provision
Amin: min. provision　　fmin: corresponding freq. to min. provision
Amax: max. provision　　fmax: corresponding freq. to max. provision

See below relation curve of YCI and set frequency:



A:YCI provision
Amin: min. provision fmin: corresponding freq. to min. provision
Amax: max. provision fmax: corresponding freq. to max. provision

See below relation curve of PULSE and set frequency:



(1) plus characteristic (2) minus characteristic

P: PULSE provision
Pmin: min. provision fmin: corresponding freq. to min. provision
Pmax: max. provision fmax: corresponding freq. to max. provision

6.9 Motor parameter group：F8

F8.00	**Load type**	**Range：0～2**	**0**

0：G Type Constant torque/ Mutations load application

1：L Type Light load/ Smooth load application

2：J Type Large Large inertia /heavy load application

F8.01	**Motor rated voltage**	**Range：1－480V**	**Depend on device type**
F8.02	**Motor rated current**	**Range：0.1－999.9A**	**Depend on device type**
F8.03	**Motor rated frequency**	**Range：1.00－400.00Hz**	**Depend on device type**

F8.04	**Motor rated speed**	**Range：1－9999r/min**	**Depend on device type**
F8.05	**Motor pole quantity**	**Range：2－14**	**Depend on device type**
F8.06	**Motor rated power**	**Range：0.1－999.9KW**	**Depend on device type**

Please set above parameters according to rated data of motor drived by the inverter for the sake of safe running.

F8.07	**Motor stator resistance**	**Range: 0.000－9.999 ohm**	**Depend on device type**
F8.08	**Motor rotor resistance**	**Range: 0.000－9.999 ohm**	**Depend on device type**
F8.09	**Motor stator inductance leak**	**Range: 0.0－999.9mH**	**Depend on device type**
F8.10	**Motor rotor inductance leak**	**Range: 0.0－999.9mH**	**Depend on device type**
F8.11	**Motor mutual inductance**	**Range: 0.0－999.9mH**	**Depend on device type**
F8.12	**Motor no-load current**	**Range: 0.1－999.9A**	**Depend on device type**

The inverter will set F8.07～F8.12 to be default standard motor parameter everty time after motor rated data modified.

F8.13	**Reserved**		
F8.14	**Reserved**		
F8.15	**Reserved**		
F8.16	**Reserved**		

F8.17	**Parameter Self Tune**	**Range：0～2**	**0**

0：Inaction

1：Static Self Tune

When the load can not be torn off motor or tedious process for motor being torn off, choose static Self Tune. Before Self Tune, input the correct motor nameplate parameters (F8.01 ~ F8.06), set F8.17 as 1, press (ENTER DATA) Key , thus Self Tune

begins.

While Self Tune is going on, Keypad will display the ID-1 ID-2 and with flash. When Self Tune is over, ID-1 / 2 won't be displayed any longer. the Self Tune data of stator resistance, rotor resistance, stator leakage inductance and rotor leakage inductance, Which are stored in the F8.07 ~ F8.10.

Motor no-load current and mutual inductance will not be able to Self Tune, the user can enter the appropriate values provided by the motor factory or data in motor test report. If there is no corresponding data, you can use the factory default values, but it may impact motor control performance. During Self Tune process, in case of exception, the user can press STOP RESET to finish Self Tune.

2：Rotating no-load auto-tuning

If the motor load is less than 30% of the rated load or the load carried by a large inertia load can not choose to rotate the auto-tuning, but try to disengage the load, the motor at rest and no-load state, or the auto-tuned parameters may not be correct.

Before setting, input the motor nameplate parameters (F8.01 ~ F8.06) correctly, set F8.17 as 2, press key ENTER DATA then auto-tuning start, at this time with the auto-tuning keep going, keypad will display the ID-1, ID -2, ID-3, and flashing; when auto-tuning end, keypad won't displayed no longer. At this time all the parameters (F8.01 ~ F8.12) required by vector control have been auto-tuned. In the auto-tuning process, if unusual cases, the end user can press key STOP RESET to end parameter self-tuning

6.10 Protection function parameter: F9

F9.00	**reserved**		

F9.01	**failure self-restoration times**	**range: 0－10**	**0**
F9.02	**failure self-restoration interval**	**range: 0.5－20.0S**	**5.0S**

During run process, failure will take place accidently due to load fluctuation and the inverter will cut off output, here failure self-restoration function can be applied in order to let the device continue to run. During self-restoration, the inverter will try to resume running in speed checking restart mode but stop outputting and failure protected if the inverter can't resume running successfully within set times. Self-restoration function will be shut down if failure self-restoration times is set to 0.

note

(1) To use failure self-restoration function must take device allowance and no essential failure in the inverter as preconditions.

(2) Self-restoration function is ineffective to failure protection caused by overload and over heat.

F9.03	**Motor overload protection mode selection**	**range: 0, 1**	**1**

This parameter defines protecting action mode when overload, overheat take place in the inverter.

0: no action. No motor overload protection characteristic(apply with caution)，here the inverter have no overload protection for load motor；

1: inverter cut off output at once. The inverter cut off output and motor stop freely when overload, overheat take place.

F9.04	**motor overload protection coefficient**	**range: 20.0-120.0(%)**	**100.0(%)**

This parameter sets sensibility of the inverter implementing thermal relay protection to load motor, can implement correct heat protection to the motor by setting this value when output current value of load motor don't match rated current of the inverter, as shown in Fig.6-35.

Value of this parameter can be determined by following formula:

$$[\text{F9.04}] = \frac{\text{motor rated current}}{\text{inverter rated output current}} \times 100$$

note

The inverter will lose thermal relay protecti on function when a piece of inverter drive multi ple motors in parallel. Please assemble heat protection relay at input side of each motor to protect them effectively.

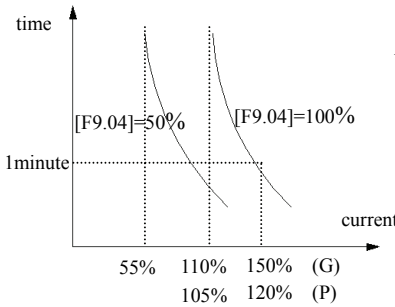


Fig.6-35 electronic thermal relay protection

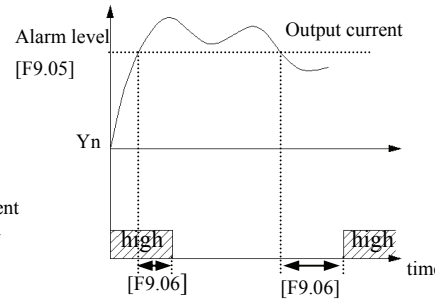


Fig.6-36 overload alarm

F9.05	**overload alarm checkout level**	**range: 20－200(%)**	**130(%)**
F9.06	**overload alarm delay time**	**range: 0.0－20.0S**	**5.0S**

If output current exceeds electric level set by parameter F9.05 continuously，open collector outputs effective signal(refer to Fig.6-36 and interrelated description of parameter F5.10~F5.13) after delay time set by F9.06 passed.

F9.07	**Overvoltage stall selection**	**range: 0, 1**	**1**
F9.08	**Stall overvoltage point**	**range: 120-150(%)**	**130(%)**

0: banned

1: allowed

Actual descending rate of motor speed may be lower than that of output frequency due to effect from load inertia when the inverter is in decelerating run process, here the motor will feed electric energy back to inverter which will make DC bus-bar voltage of the inverter increase, overvoltage protection will takes place if not take steps.

Overvoltage stall protection function, indicates that output frequency of the inverter stops descending if bus-bar voltage detected during run process exceed stall voltage point defined by F9.08 (relative to standard bus-bar voltage) and the inverter continue to implement decelerating run when bus-bar voltage detected again is lower than stall overvoltage point. As shown in Fig. 6-37.

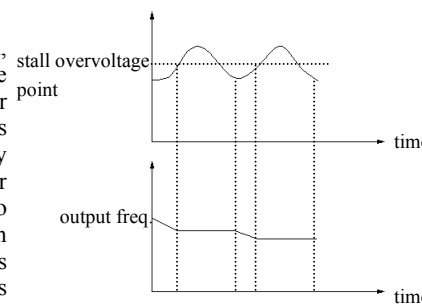


Fig.6-37 overvoltage stall function

F9.09	**automatic current limiting level**	**range: 110－200(%)**	**150(%)**
F9.10	**frequency descending rate during current limiting**	**range: 0.00－99.99Hz / S**	**0.00Hz/S**
F9.11	**automatic current limiting action selection**	**range: 0, 1**	**0**

By automatic current limiting function the inverter can limit load current not to exceed automatic current limiting level set by F9.09 to avoid tripping out for failure caused by rushing current. This function is especially suitable for some biggish inertia or acutely changing load occasion.

Automatic current limiting (F9.09) defines current threshold value of automatic current limiting action, its value is the percentage relative to inverter rated current.

Frequency descending rate during current limiting (F9.10) defines adjusting rate to output frequency during automatic current limiting action.

If frequency descending rate during automatic current limiting F9.10 is too small，inverter isn't easy to get rid of automatic current limiting state which may cause overload failure finally；If descending rate F9.10 is too big, the inverter may be in generating state for long time which will cause overvoltage protection.

Automatic current limiting function is effective in accelerating decelerating

state and whether it's effective in constant speed run state is determined by automatic current limiting action selection (F9.11).

F9.11=0 indicates that automatic current limiting is ineffective during constant speed running；

F9.11=1 indicates that automatic current limiting is effective during constant speed running；

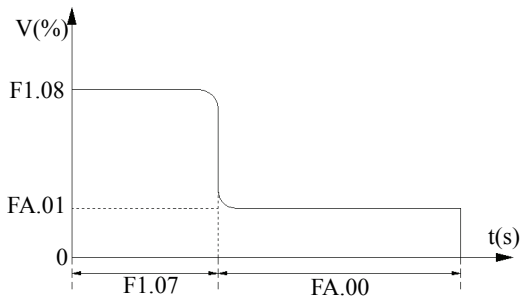
Output frequency may varies during automatic current limiting action，so automatic current limiting function is not suitable for occasion demanding stable output frequency during constant speed run.

Select the vector control, The percentage of automatic current limiting level (F9.09) should not set less than the torque limit value (F6.04) in the setted value.

6.11 Stop auxiliary function parameter group: FA

FA.00	**Auxiliary DC brake time**	**Range：0.0—20.0s**	**0.0s**
FA.01	**Auxiliary DC brake**	**Range：0—15（%）**	**0**

Auxiliary DC brake means when the inverter stop DC brake is finished give the second stage DC braking. Role in some special circumstances require rapid braking, and stop long time in the state of DC braking, but to prevent motor heat circumstances.



FA.02	**Reserved**		
FA.03	**Reserved**		

6.12 Failure record function parameter: Fd

Fd.00	**previous one failure record**	**range: 0~23**	**0**
Fd.01	**previous two failure record**	**range: 0~23**	**0**
Fd.02	**previous three failure record**	**range: 0~23**	**0**
Fd.03	**previous four failure record**	**range: 0~23**	**0**
Fd.04	**previous five failure record**	**range: 0~23**	**0**
Fd.05	**previous six failure record**	**range: 0~23**	**0**

0: no failure

1－23: failure E0.01-E0.23，please see chapter 7 for specified failure type

Fd.06	**Set freq. at previous failure**	**range: 0-high limit**	**0**
Fd.07	**Output freq. at previous failure**	**range: 0-high limit**	**0**
Fd.08	**output current at previous failure**	**range: 0-999.9A**	**0**
Fd.09	**output volt. at previous failure**	**range: 0-999V**	**0**
Fd.10	**DC bus-bar vlot. at previous failure**	**range: 0~800V**	**0**
Fd.11	**Load motor speed at previous failure**	**range: 0~9999**	**0**
Fd.12	**Module temp. at previous failure**	**range: 0~100**	**0**
Fd.13	**Input end state at previous failure**		**0**
Fd.14	**Accu. runtime at previous failure**	**range: 0~65535h**	**0**

6.13 Code and manufacturer function parameter: FF

FF.00	**user password**	**range: 0000－9999**	**1**

User password setting function is used for prohibiting unauthorized personnel from consulting and modifying function parameter.

Set this function code to 0000 when user password function isn't wanted.

First input 4 bits number as user password and press ENTER/DATA key to confirm, then the password will come into effect at once.

Password modification:

Enter into password verification state by pressing ESC/MENU key, after inputting primary 4 bits password parameter editing state is available，choose FF.00(here FF.00=0000)，input new password and press ENTER/DATA key to confirm，then the password come into effect at once.

note Please keep the password you set without fail, in case the password is missing please consult the manufacturer.

FF.01	**manufacturer password**	**range: 0000－9999**	**0000**

Setting function for the manufacturer, user need not to modify it.

7 Troubleshooting

7.1 Failure and countermeasure

Possible failure types in EDS-V300 are shown in Table 7-1 and failure code is from E001 to E023. Some failure code is reserved for intelligent automatic diagnosis function which will be executed continuously in future. When failure takes place in the inverter, the user should check according to note of this table first and record failure phenomena detailedly. Please contact our after-sale service and technical support Department or agent in your local place when technical service is needed.

Table 7-1 failure type and the countermeasure

failure code	failure type	possible reason	countermeasure
E001	overcurrent during accelerating process	Accelerating time is too short	Prolong accelerating time
		Improper V/F curve	Adjust V/F curve setting，adjust manual torque boost or change to automatic torque boost
		Restart rotating motor	Set deceleration restart function
		Low power source voltage	Check input power supply
		Too small power of the inverter	Choose inverter with high-power
E002	overcurrent during decelerating process	Decelerating time is too short	Prolong decelerating time
		Have potential energy load or big Inertia load	Increase braking power of external energy consumption braking subassembly
		Power of inverter is a bit small	Choose inverter with high-power
E003	overcurrent during constant speed process	Load change suddenly or Have unwonted phenomena	Check or reduce break of the load
		Accel/Decel time is set to too short	Prolong accelerating decelerating time properly
		low power source voltage	Check input power supply
		Power of inverter is a bit small	Choose inverter with high-power
E004	overvoltage during accelerating process	Unwonted input voltage	Check input power supply
		Accel time is set to too short	Prolong accelerating time properly
		Restart rotating motor	Set speed checking restart function

E005	overvoltage during decelerating process	Decelerating time is too short	Prolong decelerating time
		Have potential energy load or big inertia load	Increase braking power of external energy consumption braking subassembly
E006	Overvoltage during constant speed process	Unwonted input voltage	Check input power supply
		Accel/Decel time is set to too short	Prolong accelerating decelerating time properly
		Input voltage change abnormally	Assemble reactor
		Load inertia is a bit big	Use energy consumption subassembly
E007	Inverter control power supply overvoltage	Unwonted input voltage	Check input power supply or look for service
E008	Inverter overload	Accel time is set to too short	Prolong accelerating time
		DC injection braking is too big	Reduce DC injection braking current，prolong braking time
		improper V/F curve	Adjust V/F curve and torque boost
		Restart rotating motor	Set speed checking restart function
		power source voltage is too low	check power source voltage
		Load is too big	Choose inverter with high-power
E009	Motor overload	improper V/F curve	Adjust V/F curve and torque boost
		power source voltage is too low	check power source voltage
		General motor run at low speed with big load	Can choose frequency conversion motor for long time low speed run
		motor overload protection factor set incorrectly	to set motor overload protection factor correctly
		motor blocked up or load change too suddenly and quickly	Check the load
E010	inverter over heating	Air-path blocked	To clear air-path or improve ventilation condition
		Ambient temperature is too high	Improve ventilation condition, lower carrier frequency
		Fan damaged	Replace the fan

E011	reserved	reserved	reserved
E012	reserved	reserved	reserved
E013	IGBT failure	Transient overcurrent of the inverter	Refer to countermeasure for overcurrent
		phase to phase short circuit or earthing short circuit of output 3 phase	wiring again
		Connecting wire or insert on control board loose	Check and connect the wire again
		Unwonted current wave caused by missing output phase etc.	Check wiring
		Assistant power supply damaged and drive voltage lacking	Look for service from manufacturer or agent
		Unwonted control board	Look for service from manufacturer or agent
E014	external device failure	use sudden stop key STOP in non-keypad run mode	Look up operation mode
		Use sudden stop key STOP under condition of stall	Set running parameter correctly
		Sudden stop terminal for external failure closed	Open external failure terminal after external failure is settled
E015	current detecting circuit failure	Connecting wire or insert on control board loose	Check and connect the wire again
		Assistant power supply damaged	Look for service from manufacturer or agent
		Hall component damaged	Look for service from manufacturer or agent
		Unwonted amplifying circuit	Look for service from manufacturer or agent
E016	RS485 communication	Baud rate set improperly	set Baud rate properly
		Serial port communication error	press STOP RESET key to reset，look for service
		Failure warning parameter set improperly	Modify F2.16, F2.17

	failure	Upper device doesn't work	Check if upper device work and wiring is correct
E017	Overcurrent in setting	Inverter Lower power	Select the suitable power inverter
E018	Over volt. in setting	When processing motor rotating setting and starting to decelerate, there is over volt. caused by big inertia	Configurating external dynamic braking assembly or corresponding braking power
E019	Under voltage failure	Under voltage	check spot input voltage
E020	reserved		
E021	Failure.not remove.or hardware circuit failure	Failure not remove hardware circuit failure	Remove failure, inspect hardware, Look for service
E022	reserved	reserved	reserved
E023	reserved	reserved	reserved
P.OFF	DC bus-bar under vlot.	Input power supply unusual	Check spot input voltage

7.2 Failure record lookup

This series inverter can record latest 6 failure code and inverter run parameter of the last failure, to search these informations can redound to finding out reason of the failure.

Failure information is all stored in Fd group parameter，please enter into Fd group parameter to see about information by referring to keypad operation method.

code	content	code	Content
Fd.00	previous one failure record	Fd.08	output current at previous failure
Fd.01	previous two failure record	Fd.09	output volt. at previous failure
Fd.02	previous three failure record	Fd.10	DC bus-bar vlot. at previous failure

Fd.03	previous four failure record	Fd.11	load motor speed at previous failure
Fd.04	previous five failure record	Fd.12	module temp. at previous failure
Fd.05	previous six failure record	Fd.13	input end state at previous failure
Fd.06	set freq. at previous failure	Fd.14	Accu. runtime at previous failure
Fd.07	output freq. at previous failure	—	—

7.3 Failure reset

(1) Before reset you must find out reason of failure downright and eliminate it，otherwise may cause permanent damage to the inverter.

(2) If can't reset or failure takes place again after resetting, should look for reason and continuous resetting will damage the inverter.

(3) Reset should take place 5 minutes after overload, overheat protection action.

To resume normal running when failure takes place in the inverter, you can choose following any kind of operation:

(1) After you set any terminal of X1~X8 to be inputted by external RESET (F5.00~F5.07=11), you can open it after connected to COM.

(2) When failure code is displayed，press 

key after restoration is confirmed.

(3) Cut off power supply.

8 Maintenance

8.1 Daily maintenance

When you use ESD-V300 series you must assemble and operate it according to demand listed in this《service manual》strictly. During run state, temperature, humidity, vibration and aging parts may affect it. To avoid this, it is recommended to perform routine inspections.

Table 8-1 Daily inspection items

period		Inspection item	Inspection content	Criterion
daily	periodic			
√		Run state parameter	(1)output current	(1)within range of rated value
			(2)output voltage	(2)within range of rated value
			(3)inside temp.	(3)temp. increment < 35℃
√		Cooling system	(1)installing ambient	(1)good ventilation, unblocked air-path
			(2)local fan	(2)rotate normally without abnormal noise
√		Motor	(1)heating	(1)no abnormality
			(2)noise	(2)even
	√	Inverter	(1) vibration, heating	(1)vibration balanced, proper wind temp.
			(2)noise	(2) without abnormal sound
			(3)fixation of lead, terminal	(3)fixed screw don't loose
√		Run ambient	(1)temperature, humidity	(1)-10℃~+40℃ 40℃~50℃used in lower volume or execute compulsory heat dissipating
			(2)dust, water and leakage	(2)no water leakage imprint, no dust
			(3)gas	(3)no peculiar smell

Recommend to inspect with following instrument:

Input voltage: electric voltmeter; output voltage: rectifying voltmeter; input output current: pincers ammeter.

8.2 Inspection and replacement of damageable parts

Some component parts in the inverter will be abraded or bear descending performance for long-term usage，to assure that the inverter can run stably and reliably, it is recommended to perform defending maintenance and replace corresponding parts if necessary.

(1) cooling fan

Abnormal noise, even oscillation may take place if the fan have wearing bearing, aging blade, here replacement of the fan should be considered.

(2) filter electrolyte capacitance

When frequent-changing load causes increasing pulsant current and aging electrolyte under high ambient temperature, the electrolyte capacitance may be damaged and here should replace it.

8.3 Repair guarantee

(1) Within 12 months from purchasing date, if failure caused by inverter itself takes place under normal conservation and usage, we will provide free repair service.

(2) We will take some upkeep if one of following situations takes place within period of repair guarantee.

a. If did not use the inverter according to《service manual》strictly or did not use it under ambient demanded in《service manual》, which cause failure.

b. Failure caused by applying the inverter to non-normal function;

c. Failure caused by self-repair, refit which is not already allowed;

d. Damage caused by bad keeping, falling down from high place or other extrinsic factor after purchasing the inverter;

e. Failure caused by natural disaster or its reason such as unwonted voltage, thunderbolt, water fog, fire, salt corroding, gas corroding, earthquake and storm etc.;

f. Make bold to tear up product logo (such as: nameplate etc.); Body serial number don't accord with that in repair guarantee card.

(3) We calculate service fee based on actual cost, which is subject to contract if any.

(4) You can contact the agent and also our company directly if you have questions. After repair guarantee period, we shall also provide lifetime charged repair service for our products.

note

Our company will also provide lifetime repair service with fee for inverter which is not within period of repair guarantee.

8.4 Storage

The user must pay attention to following points for temporary storage and long-term storage after purchasing the inverter:

(1) Avoid storing the inverter in high temperature, moist place and place of dust, metal powder and assure good ventilation.

(2) Longtime storage will cause electrolyte capacitance of low quality, so must assure that it's electrified for one time within 2 years and electrification time is not shorter than 5 hours and input voltage must be increased to rated value gradually by voltage adjustor.

9 Fitting parts

9.1 Communication subassembly

9.1.1 Long-distance operation key board

Maximum electric distance from local keypad to inverter is 2m.

RS485 communication mode is adopted between inverter and long-distance keypad，only a four-core cable is needed between them and maximum electric distance can reach 1000m.They communicate with each other in main-auxiliary mode, namely take long-distance keypad as main device and inverter as auxiliary one. Connecting wire end is fixed by common screw which is easy to maintain.

This series of inverter support usage of local keypad and long-distance keypad at the same time，no priority order，both can operate the inverter synchronously.

Following function can be realized by long-distance keypad:

(1) Can control run, stop, jog, failure restoration, changing set frequency modifying function parameter and run direction of auxiliary device.

(2) Can identify auxiliary device type and monitor run frequency, set frequency output voltage, output current, analog closed loop feedback, analog closed loop setting and exterior counting value of auxiliary device.

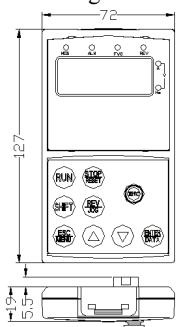


Fig.9-1 long-distance keypad

9.1.2 Communication cable

(1) Long-distance keypad communication cable

Type: EN-LC0030 (3.0m)

Used for connecting between long-distance keypad and inverter.

Remark: 1m, 2m, 3m, 5m, 10m, 15m are standard deployment for our company's inverter，it's needed to subscribe for the cable if it exceeds 15m.

10 Serial port RS485 communication protocol

10.1 Summarization

We provide general RS485/RS232 communication interface in our Inverters (such asEDS-V300 series, EDS1000 series, EDS2000 series, EDS2800 series, etc.) for the user. Through this communication interface upper device (such as PC, PLC controller etc.) can perform centralized monitor to the inverter (such as to set inverter parameter, control run of inverter, read work state of the inverter) and also long-distance control keypad can be connected to realize various usage requirement of the user.

This communication protocol is interface criterion file designed for realizing above-mentioned function, please read it earnestly and program according to it so that realize long-distance and network control to the inverter.

10.2 Protocol content and description

10.2.1 Communication net buildup mode

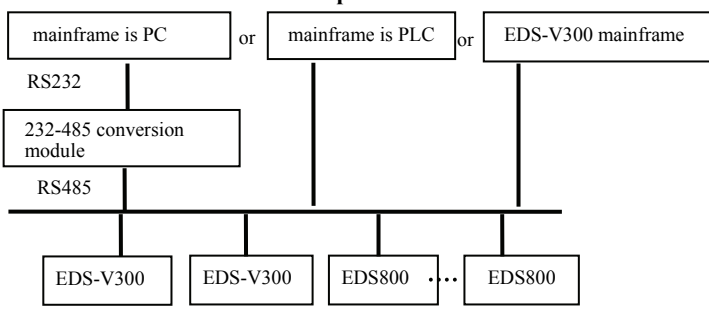


Fig.10-1 net buildup graph

10.2.2 Communication mode

At present, EDS-V300 inverter can be used not only as auxiliary device but also mainframe device in RS485,if the inverter used as auxiliary ddevice,master device can be completed by PC,PLC or human interface,and if used as mainframe device ,the main- auxiliary control of the inverter can be complement by it, Specific communication mode is as mentioned below:

(1) PC or PLC as mainframe，inverter as auxiliary device，point-to-point communication between mainframe and auxiliary device.

(2) Auxiliary device don't response when mainframe send out command by broadcast address.

(3) User can set local address, baud rate and data format of the inverter through auxiliary device keypad.

(4) Auxiliary device report current failure information to mainframe in the last response frame.

(5) EDS-V300 provides RS485 interface.

10.2.3 Transport mode

Asynchronous serial，semiduplex transport mode. Default format and transport rate: 8-N-1，9600bps.For specific parameter setting please see description for F2.14~F2.17 group function code.

10.2.4 Data command frame format

main device command frame format																	
sending order	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
	frame head	auxiliary device address	auxiliary device address	main device command	main device command	assistant index	assistant index	command index	command index	set data	set data	set data	set data	checkout sum	checkout sum	checkout sum	checkout sum	frame end
Definition	head	address		command area		Index area				setting data area				checkout area				end
sending byte	1	2		2		4				4				4				1

auxiliary device response frame format																		
sending order	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18
	frame head	auxiliary device address	auxiliary device address	auxiliary device reponse	auxiliary device reponse	failure index	failure index	command index	command index	run data	run data	run data	run data	checkout sum	checkout sum	checkout sum	checkout sum	frame end
Definition	head	address		reponse area		Index area				Run data area				Checkout area				end
sending byte	1	2		2		4				4				4				1

Fig.10-2 command/response frame format

Remark:

(1) "Setting data area" and "run data area" may not be existent in some command/data frame format, so in protocol command list it's marked with "nothing".

(2) In protocol effective character set is: ~, 1, 2, 3, 4, 5, 6, 7, 8, 9, A, B, C, D, E, F and hex data 0DH，ASCII lowercase a, b, c, d, e, f are invalid.

(3) Effective command frame length is 14 or 18 byte.

10.2.5 Explanation and description for format

(1) frame head

It's character "~" (namely hex 7E),single byte.

(2) auxiliary device address

Data meanings: local address of auxiliary device, double byte. ASCII format. Inverter factory default is 01.

(3) mainframe command/auxiliary device respond

Data meanings: mainframe send out command and auxiliary device respond to the command. Double byte, ASCII format.

Response code function classification:

Species 1>: command code= "10"，mainframe ask auxiliary device to report current preparation state and control situation.

Table 10-1 response code meanings for command code "10"

response code ASCII	meanings		
	preparation state of auxiliary device	Control from mainframe is allowed	To set frequency is allowed
10	Don't get ready	no meaning	
11	get ready	allow	allow
12	get ready	allow	allow
13	get ready	don't allow	don't allow
14	get ready	don't allow	don't allow
20	frame error		

Species 2>: command code= "11" ~ "15", 5 kinds of function command which mainframe send to auxiliary device, for detail please see protocol command list.

Table 10-2 response code meanings for command code "11~15"

response code ASCII	Meanings of response code	description
00	Auxiliary device communication and control is normal; function code modification is effective; password is correct.	
20	(1) frame checkout error; (2) "command area" data overrun; (3) "index area" data overrun; (4) frame length error/non ASCII byte exist in area except frame head, frame end.	When this response code is reported, data of "command area", "index area" and "running data area" are not reported.
30	(1) control to auxiliary device is ineffective; (2) ineffective function code parameter modification; (3) "setting/running data" area data overrun. (4) password error.	Whether report this response code relate to current set state of auxiliary device. When report data of area", "index area" and "run data area" are reported according to protocol requirement.

(4) auxiliary index/command index/failure index

Data meanings: include auxiliary index byte and command index byte.

For mainframe, auxiliary index, command index are used for cooperating mainframe command in realizing specific function.

For auxiliary device, auxiliary index, command index are used for reporting failure state code, command index are reported without modification.

Data type: hex，4 byte, ASCII format.

Command index occupy 2 low byte, data range: "00"～"FF".

Auxiliary index occupy 2 high byte, data range: "00"～"FF".

Auxiliary device failure state occupy "auxiliary index" byte，see Appendix table 10-3.

Table 10-3 failure type description

failure code	description	failure code	description
1	Accelerating run over current	13	Converting module protection

2	decelerating run over current	14	External device failure
3	Constant speed run over current	15	current detecting circuit failure
4	accelerating run over voltage	16	RS485 communication failure
5	decelerating run over voltage	17	reserved
6	Constant speed run over voltage	18	reserved
7	Controller power supply over voltage	19	Under voltage
8	Inverter overload	20	System disturbance
9	Motor overload	21	Reserved
10	Inverter over heat	22	Reserved
11	reserved	23	E^2PROM read and write error
12	reserved		

(5) checkout sum

Data meanings: frame checkout，4 byte, ASCII.

Calculation method: accumulative sum of ASCII code value of all byte from "auxiliary device address" to "run data".

(6) frame end

Hex 0D，single byte.

10.2.6 Protocol command list

Frame 7E and frame end 0D, address, checkout sum，ASCII character format are omitted in following description.

Table 10-4 protocol command table

Name	Main-frame order	Auxi-liary index	order index	run data setting range	Mainframe sending example，such as PC control operation of inverter(C language cluster format，auxiliary device address is set to 01)	run data precision	description

look up auxiliary motor state		10	00	00	no	~010A00000192\r	1	
Read parameter of auxiliary motor	current set freq.	11	00	00	no	~010B00000193\r	0.01Hz	
	current run freq.	11	00	01	no	~010B00010194\r	0.01Hz	
	Output voltage	11	00	02	no	~010B00020195\r	1V	
	Output current	11	00	03	no	~010B00030196\r	0.1A	
	Bus-bar voltage	11	00	04	no	~010B00040197\r	1V	
	Load motor speed	11	00	05	no	~010B00050198\r	1rpm	
	Module temp.	11	00	06	no	~010B00060199\r	1^0C	
	Runtime	11	00	07	no	~010B0007019A\r	1h	
	accumulative time	11	00	08	no	~010B0008019B\r	1h	
	Input terminal	11	00	09	no	~010B0009019C\r	no	
	output terminal	11	00	0A	no	~010B000A01A3\r	no	
	analog input VCI	11	00	0B	no	~010B000B01A6\r	0.01V	
	analog input YCI	11	00	0C	no	~010B000C01A7\r	0.01V	
	analog input CCI	11	00	0D	no	~010B000D01A8\r	0.01V	
	exterior pulse input	11	00	0E	no	~010B000E01A9\r	0.01Hz	
	read inverter state	11	00	0F	no	~010B000F01AA\r	no	
Run control and adjusting function	auxiliary device run command	12	00	00	no	~010C00000194\r	no	
	set current run frequency provision of auxiliary device	12	00	01	0Hz~high limit freq.	~010C00010FA0027C\r	0.01Hz	Set freq. =40.00Hz
	auxiliary device run with run freq. provision	12	00	02	0Hz~ high limit freq.	~010C00020FA0027D\r	0.01Hz	auxiliary device run set freq. =40.00Hz
	auxiliary device forward run	12	00	03	no	~010C00030197\r	no	
	auxiliary device reverse run	12	00	04	no	~010C00040198\r	no	

	auxiliary device forward run with run freq. provision	12	00	05	0Hz~ high limit freq.	~010C00050FA00280\r	0.01Hz	forward run boot-strap set freq. =40.00Hz
	auxiliary device reverse run with run freq. provision	12	00	06	0Hz~ high limit freq.	~010C00060FA00281\r	0.01Hz	reverse run boot-strap set freq. =40.00Hz
	auxiliary device stop	12	00	07	no	~010C0007019B\r	no	
	auxiliary device jog run	12	00	08	no	~010C0008019C\r	no	
	auxiliary device forward jog run	12	00	09	no	~010C0009019D\r	no	
	auxiliary device reverse jog run	12		0A	no	~010C000A01A5\r	no	
	auxiliary device stop jog run	12	00	0B	no	~010C000B01A6\r	no	
	auxiliary device failure restoration	12	00	0C	no	~010C000C01A7\r	no	
	auxiliary device urgent stop	12	00	0D	no	~010C000E01A8\r	no	
Read function code parameter	Run freq. digital setting F0.01	13	00	01	no	~010D00010196\r	0.01Hz	
	Run direction setting F0.03	13	00	03	no	~010D00030198\r	1	
	accelerating time1 F0.08	13	00	08	no	~010D0008019D\r	0.1S	
	decelerating time1 F0.09	13	00	09	no	~010D0009019E\r	0.1S	

Set function code parameter	Run freq. digital setting F0.01	14	00	01	0Hz~ high limit freq.	~010E00011388026B\r	0.01Hz	Set function code F0.01=50.00Hz
	Run direction setting F0.03	14	00	03	0, 1	~010E00030001025A\r	1	Set function code F0.03 to reverse run
	accelerating time1 F0.08	14	00	08	0~8CA0	~010E000803E8028B\r	0.1S	Set function code F0.08 to 10.0s
	decelerating time1 F0.09	14	00	09	0~8CA0	~010E000903E8028C\r	0.1S	Set function code F0.09 to 10.0s
Software version query order	Query auxiliary device software version	15	00	00	no	~010F00000197\r	1	

Table 10-5 response state word meanings of reading inverter state command

bit	signification		
	description	0	1
Bit0	Stop/run state	stop	run
Bit1	Logo for under voltage	normal	Under voltage
Bit2	FWD/REV run logo	Forward run	Reverse run
Bit3	Swing freq. run mode logo	ineffective	effective
Bit4	Common run mode logo	ineffective	effective
Bit5	jog run mode logo	no	jog
Bit6	PLC run mode logo	no	yes
Bit7	multi-step freq. run mode logo	no	yes

Bit8	PI closed loop run mode logo	no	yes
Bit9	Set counting value arriving logo	no	yes
Bit10	specified counting value arriving	no	yes
Bit11~15	reserved		

Table 10-6 read auxiliary device function code parameter

function definition	Read auxiliary device function code parameter: all function code parameter except user password and manufacturer password						
meanings	frame head	address	order	order index	run data	checkout sum	frame end
mainframe order	7EH	ADDR	13	see remark	4	BCC	0DH
byte quantity	1	2	2	4	0	4	1
auxiliary device respond	7EH	ADDR	06	see remark	Function code para.	BCC	0DH
byte quantity	1	2	2	4	4	4	1

remark

Command index=combinated by function code group number and hex code of function code number. For instance:
If want to read parameter of F0.05 function code, order index=0005;
If want to read parameter of F2.11 function code, order index =020B;
If want to read parameter of F2.15 function code, order index =020F;
If want to read parameter of F2.13 function code, order index =020D;

Corresponding relation between decimal and hex value of function code group

function group	decimal	hex	function group	decimal	hex
F0	0	00H	F6	6	06H
F1	1	01H	F7	7	07H
F2	2	02H	F8	8	08H
F3	3	03H	F9	9	09H
F4	4	04H	FD	13	0DH

	F5	5	05H	FF	15	OFH
virtual data	0~FFFF (namely 0~65535)					

Please input correct “user password” before you set user function code parameter.

Table 10-7 set auxiliary devsice function code parameter

function definition	Set auxiliary device function code parameter: all function code parameter except user password and manufacturer password						
meanings	frame head	address	order	order index	run data	checkout sum	frame end
mainframe order	7EH	ADDR	14	see remark	4	BCC	0DH
byte quantity	1	2	2	4	0	4	1
auxiliary device respond	7EH	ADDR	06	see remark	Function code para.	BCC	0DH
byte quantity	1	2	2	4	4	4	1

remark

Command index=combinated by function code group number and hex code of function code number. For instance:
If want to set parameter of F0.05 function code, order index=000B；
If want to set parameter of F2.11 function code, order index =020B；
If want to set parameter of F2.15 function code, order index =020F；
If want to set parameter of F2.13 function code, order index =020D；

Corresponding relation between decimal and hex value of function code group No.

function group	decimal	hex	function group	decimal	hex
F0	0	00H	F6	6	06H
F1	1	01H	F7	7	07H
F2	2	02H	F8	8	08H
F3	3	03H	F9	9	09H
F4	4	04H	FD	13	0DH
F5	5	05H	FF	15	0FH

Virtual data	0~FFFF (namely 0~65535)

Appendix 1 Modbus communication protocol

1.1 Summarization

We provide general RS485 communication interface in our inverters (such as EDS800 series, EDS1000 series, EDS-V300 series and etc.) for the user. Through this communication interface upper device (such as HMI, PC, PLC controller and etc.) can perform centralized monitor to the inverter (such as to set inverter parameter, control run of inverter, read work state of the inverter).

This communication protocol is interface criterion file designed for realizing above-mentioned function, please read it earnestly and program according to it so that realize long-distance and network control to the inverter.

1.2 Communication net buildup mode

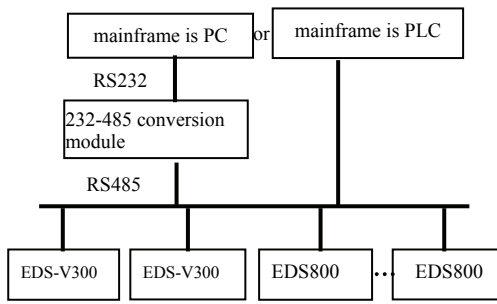


Fig.1 net buildup graph

1.3. Communication mode

At present, EDS-V300 inverter can be used only as auxiliary device in RS485 net. Can realize communication between inverters through PC, PLC or HMI if it's needed. Specific communication mode is as mentioned below:

(1) PC or PLC as mainframe，inverter as auxiliary device, point-to-point communication between mainframe and auxiliary device.

(2) Auxiliary device don't response when mainframe send out command by broadcast address.

(3) User can set local address, baud rate and data format of the inverter through auxiliary device keypad or serial communication mode.

(4) EDS-V300 provides optional RS485 interface.

(5) Default mode: Asynchronous serial，semiduplex transport mode. RTU mode.

Default format and transport rate: 8-N-1, 9600bps.

For specific parameter setting please see description for function code F2.14~F2.17 as follows:

(remark：Below definition for F2.14~F2.17 is only effective under Modbus communication mode, and definition for other parameters are the same as original)

F2.14	Communication configuration	LED first bit：baud rate selection 0：1200BPS 1：2400BPS 2：4800BPS 3：9600BPS 4：19200BPS 5：38400BPS LED second bit：data format 0：1-8-1 format，no checkout 1：1-8-1 format，even checkout 2：1-8-1 format，odd checkout LED third bit：response selection 0：Respond to host command and reply to data packet 1：Respond to host command, but not reply	1	003	×
F2.15	Local address	0－127，0 is broadcast address	1	1	×
F2.16	Communication timeout detection time	0.0－1000.0s, 0 means communication timeout detection invalid	0.1s	0.0s	×
F2.17	Local response delay	0－200ms	1ms	5ms	×

1.4 RTU Communication Mode：

1.4.1 Data frame format

Using RTU mode, messages are sent at least 3.5 character time interval pause. The first transmitted field is device address, the character you can transfer is hexadecimal 0x00 ~ 0xFF. Network equipment Continuously monitor the bus, including pauses. When the address field is received, all equipment determine whether it is sent to their own. when the last character of the packet transfer is complete, at least a 3.5 character times pause mean the end of the message. A new message can begin after this pause.

The entire message frame must be transmitted as a continuous flow. If a new message start transmitting in less than 3.5 character times after a message and then receiving device will consider it a continuation of the previous message. This will cause an error, because in the final CRC field value can not be right.

RTU frame format as the talbe below：

Frame Header	3.5 characters time pause
Slave address	Slave value：1~127
Communication command code	03H：read slave parameter 06H：write slave parameter
Data content DATA	The contents of packet: Parameter address（16bit）; Number of parameter or bytes of parameter value; Parameter value（16bit）
Data content DATA	
……	
……	
CRC check value low byte	16bit Unsigned check value
CRC check value high byte	
Closing Flag	3.5 characters time pause

Regarding generation method of CRC check value, please refer to this Appendix check way paragraph.

1.4.2 Host read slave parameter

Command code 03H. Host can read or one or more parameter(up to ten) by initiating a communication transaction .

E.g., read 2 contiguous inverter parameter values from the address 0000H of inverter whoes address is 01, the contents of host command ：

ADR	01H
CMD	03H
Parameters initial address high byte	00H
Parameters initial address low byte	00H
Number of parameter high byte	00H
Number of parameter low byte	02H
CRC check value low byte	Be calculated
CRC check value high byte	Be calculated

The contents of slave reply：

ADR	01H
CMD	03H
Parameter value bytes	04H
Address 0000H content high byte	00H
Address 0000H content low byte	01H
Address 0001H content high byte	13H
Address 0001H content low byte	88H
CRC check value low byte	Be calculated
CRC check value high byte	Be calculated

1.4.3 Host write slave parameter

Command code 06H. Host can write an parameter by initiating a communication transaction .

E.g.,The decimal system 5000 (1388H) written to the inverter 0001H address whose slave address is 02，host command including：

ADR	02H
CMD	06H
Parameter address high byte	00H
Parameter address low byte	01H
Parameter value high byte	13H
Parameter value low byte	88H
CRC check value low byte	Be calculated
CRC check value high byte	Be calculated

The contents of slave reply：

ADR	02H
CMD	06H
Parameter address high byte	00H
Parameter address low byte	01H
Address 0903H content high byte	13H
Address 0903H content low byte	88H
CRC check value low byte	Be calculated
CRC check value high byte	Be calculated

1.5 Data communication address allocation

1.5.1 Function code Fd-F0 group communication address

Inverter function parameter's MODBUS communication address addressing process follows PPnn way: PP means high byte of the address, corresponding to function parameter's group number; nn means low byte of the address, corresponding to function code parameter's group internal code. For example: F3.21 function code's communication address is 0315H, 03H is the hex form of group number 3, 15H is the hex form of grop internal code 21.

F0.00~F9.11 communication address is 0000H~090BH, Fd group fault record parameter start address is 0D00H.

1.5.2 control command and status word communication address

Variable Name	Communication address	Reading-writing attribute	Command data or response value meaning
run command word	2000H	Writing only	1: inching run
			2: inching stop
			3: forward inching run
			4: reversal inching run
			5: run
			6: stop
			7: forward run
			8: reversal run
			9: fault reset
			10: emergency stop

Serial port frequency provision	2001H	Reading and writing	Lower frequency~upper frequency
Inverter status	2100H	Reading only	1: forwarder running 2: reversal running 3: stop 4: alarm status
Alarm code	2180H	Read	0: without alarm 1~23:mean E001~E023 alarm

1.5.3 Monitor parameter communication address

Monitor parameter	Name	Communication address (read)
C-00	Set frequency	1000H
C-01	Output frequency	1001H
C-02	Output current	1002H
C-03	Output voltage	1003H
C-04	DC bus-bar vlotage	1004H
C-05	Load motor speed	1005H
C-06	module temperature.	1006H
C-07	Power on running time	1007H
C-08	Accumulative running time	1008H
C-09	Input terminal status	1009H
C-10	Output terminal status	100AH
C-11	Analog input VCI value	100BH
C-12	Analog input CCI value	100CH
C-13	Analog input YCI value	100DH
C-14	External impulse frequency	100EH

1.6 Communication error processing

Inverter receiving data packet detection error, it finds reading&writing parameter address or parameter value invalid, so reply to the host with communication error response packet. Communication error response packet (host command code +80H) as command code, with 1 byte error code.

Format for communication error response packet as follows:

ADR	01H
CMD	83H/86H
communication error code	01H~06H (for details, please check below table)
Low byte of CRC checksum	Obtain by calculating
High byte of CRC checksum	Obtain by calculating

Meaning for each communication error code value as follows:

Communication error code value	Type of communication error
0x01	CRC checksum error
0x02	Command code illegal
0x03	Register address visited illegal
0x04	Value to register illegal
0x05	Not allow to modify parameters
0x06	Register number read illegal

1.7. CRC checksum mode

CRC checksum value calculating function written by C language is as follows:

```
unsigned int cal_crc_value (unsigned char *pval, unsigned char len)
{
    unsigned int crc_value=0xFFFF;
    unsigned int i;

    while(len--)
    {
        crc_value ^= *pval++;
        for(i=0; i<8; i++)
        {
            if(crc_value & 0x0001)
            {
                crc_value >>= 1;
                crc_value ^= 0xA001;
            }
            else
            {
                crc_value >>= 1;
            }
        }
    }
    return(crc_value);
}
```

Appendix 2 Braking resistance

1.1 Braking resistance

The motor's electric potential energy will charge inverter's capacitance up reversely if speed of the motor decends too quickly or load of the motor wobbles too quickly while the inverter is running, which will increase the voltage upon power modules suddenly and is easy to make the inverter damaged. The inverter will control it according to load size and performance. You only need to connect external braking resistance to realize timely energy discharge when the braking function is needed. To connect external resistance is a kind of energy consumption braking mode, as all the energy is consumed by the braking resistance.

We can add built-in braking unit for EDS-V300-2S0004~2S0037 with additional cost upon receival of your requirement; EDS-V300-4T0007~4T0150 have built-in braking unit, but no braking resistance.

When braking function needed, please connect external braking resistance according to below table.

Braking unit&braking resistance configuration and External braking resistance configuration table

Type	Built-in braking unit	Built-in braking resistance	External braking resistance	Qty.	Power of external braking resistance
EDS-V300-2S0004	Need to be customized	N/A	≥150Ω	1	200W
EDS-V300-2S0007	Need to be customized	N/A	≥100Ω	1	250W
EDS-V300-2S0015	Need to be customized	N/A	≥70Ω	1	400W
EDS-V300-2S0022	Need to be customized	N/A	≥50Ω	1	600W
EDS-V300-2S0037	Need to be customized	N/A	≥30Ω	1	1000W
EDS-V300-4T0007	Yes	N/A	≥300Ω	1	200W
EDS-V300-4T0015	Yes	N/A	≥300Ω	1	200W
EDS-V300-4T0022	Yes	N/A	≥300Ω	1	200W
EDS-V300-4T0037	Yes	N/A	≥125Ω	1	400W
EDS-V300-4T0055	Yes	N/A	≥80Ω	1	650W
EDS-V300-4T0075	Yes	N/A	≥80Ω	1	650W
EDS-V300-4T0110	Yes	N/A	≥50Ω	1	1000W
EDS-V300-4T0150	Yes	N/A	≥40Ω	1	1000W